



The ATLAS Data Acquisition System in LHC Run 2

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Outline

- From LHC Run 1 to Run 2
- High level overview of trigger systems
- The ATLAS Data Acquisition System:
 - Data Flow components
 - Data acquisition network
 - Control and Monitoring
- Conclusions
- Future work

From LHC Run 1 to Run 2



Run 1 conditions:

- 8 TeV centre-of-mass energy
- Peak Lumi = $7 \times 10^{33} cm^{-2} s^{-1}$
- Average pileup = 20.7 (peak = 40)
- 70 kHz L1 trigger rate (peak 2012)

New conditions in Run 2:

- 13 TeV centre-of-mass energy
- Peak Lumi = $1.74 \times 10^{34} cm^{-2} s^{-1}$
- Average pileup = 32.2 in 2017 (peak = 60)
- 100 kHz L1 trigger rate (97 kHz peak 2016)



The ATLAS Trigger and Data Acquisition System in Run 1



The ATLAS Trigger and Data Acquisition System in Run 2



The ATLAS Trigger

A high level overview

Level 1 Trigger

- Rejects or accepts an event at 40 MHz
- Reduces the event rate down to 100 kHz (peak)
- Deterministic decision time: $2.5 \ \mu s$
- Implemented in custom electronics:
 - ASICs and FPGAs

High Level Trigger

- Reduces the event rate from 100 kHz (peak) to few kHz
- Incremental data collection and filtering
 - Average decision time: $\sim 300 \text{ }ms \text{ at} < \mu > = 30$
- Server farm:
 - ~2000 nodes, ~40000 cores

The ATLAS Data Acquisition System in Run 2

DAQ system responsibilities

- Read out and buffer 160 GB/s from custom electronic devices (Read Out Drivers)
- Transport necessary event data (>30 GB/s) to the HLT farm for event filtering
- Provide temporary storage for selected events before copying to permanent storage
- Orchestrate all the previous tasks
- Monitor the system and recover from bad states and error conditions

The Read-Out System

- Receives and buffers event fragments from detector specific electronic boards (RODs) and sends them to the HLT farm upon request
- New read-out card: RobinNP
 - Based on ALICE C-RORC card
 - C-RORC = Common Readout Receiver Card
 - Custom ATLAS FW
 - 12 Readout Links
 - 8 GB of RAM
- 1900 Read-Out Links connected to 102 ROS PCs
 - 2 RobinNPs / PC
 - Data management done by CPU of host PC
 - Contrary to Run1 card where processing was done on-board
 - Data collection network connectivity: 4 x 10 GbE
 - For redundancy

The Read-Out System

Region of Interest Builder and Supervisor

- Region of Interest Builder (RoIB)
 - Assembles Regions of Interest (RoI) from fragments produced by L1 sources:
 - Central Trigger Processor, L1 Calorimeter and Topological Triggers and L1 Muon
- High Level Trigger SuperVisor (HLTSV)
 - Assigns events to HLT nodes
 - Clears events from the ROS buffers
 - Re-assigns events that time out during processing
- In Run 1 the RoIB was implemented in custom hardware in VME crate
- In Run 2 the RoIB and the HLTSV run on a commodity server
 - $\circ~$ A ROS PC with a RobinNP card
 - Achieve over 100 kHz event assignment rate

Region of Interest Builder and Supervisor

Event Building: Data Collection Manager

- Requests the event fragments from the ROS on behalf of the Processing Units
 - Single-threaded instance based on *Boost ASIO*
 - Shared memory communication with Processing Units based on *Boost Interprocess*
- A credit based traffic shaping mechanism used to avoid instantaneous network saturation
- In addition, it supports:
 - Duplication of accepted events going to different output streams (e.g. for calibration purposes)
 - Data compression before event logging

Data logging: The Sub-Farm Output

- The SFOs provide 48h of **temporary storage**
- Direct Attached Storage unit with multiple redundant data paths for fault tolerance and resilience
 - Maximum I/O: 6.5 GB/s
 - Average I/O: ~1.6 GB/s
- Background jobs copy the files to permanent storage, deleting them on the local disk only when they are safely on tape

Data logging: The Sub-Farm Output

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Control and monitoring in the ATLAS DAQ system

Control and monitoring in the ATLAS DAQ system

Tasks

- Coordinate more than 30.000 applications used for the detector control and data taking
 - Custom software supported by heterogeneous development teams
- System robustness is mandatory
 - Hardware and software failures happen frequently
 - Impact on data taking must be minimized
- The DAQ system provides all the needed infrastructure for:
 - Run control
 - Process management
 - Resource management
 - System configuration
 - ...and much more
- In Run 2 two Complex Event Processing (CEP) engines have been introduced:
 - CHIP and SA

CEP: Complex Event Processing

- Methods for finding complex patterns in monitoring data:
 - Correlation
 - Aggregation
 - Causality
 - Sliding time window
- ...and take corresponding actions
- ESPER: CEP engine which uses an SQL-like syntax for defining rules
 - It allows working on continuous streams of data
 - Simple syntax to define actions

i.e. React on FATAL or ERROR messages from some applications

i.e. React if a component is reporting high load conditions for more than 60 seconds

i.e. React if ATLAS is not running but physics collisions are provided by the accelerator

i.e. Detect unbalanced rates to the data storage

CHIP: Central Hint and Information Processor

- Is the brain of the Run controller application
 - Error management
 - Anomaly detection
- Maximizes efficiency:
 - Reacting fast and effectively to errors
 - Reducing the need of human interventions
- Optimizes manpower resources:
 - Reduces workload on the operator
 - Formalizes expert knowledge

CHIP: Central Hint and Information Processor

Action type

Action status

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Shifter Assistant

- Another CEP engine to assist ATLAS shifters
 - Promptly notify shifters of problems and failures
 - Pertinent information provided taken from different data sources
 - Reminds the shifters to (not) take action

Example:

Name

trigger-left-on-hold

	Created on 09/18/2017, 6:14:09		
Message	The expert system failed completing automated recoveries Stopless-REMOVAL on component TRTEndcapC_E-06/TRTBusyChannel_rod341501 (detector TRT_ENDCAP_C_SIDE). The trigger was left on hold 1 times.		System C
Action	Alert the relevant TRT_ENDCAP_C_SIDE desk, if you are sure it will be harmless and it is appropriate, you should resume the trigger.		

ERROR

System Monitoring

- Monitoring the system is necessary for its correct functioning:
 - System health
 - Operating point monitoring
 - Physics rates
 - Data quality
- The DAQ monitoring framework offers a wide set monitoring tools to fulfill these requirements:
 - Online monitoring
 - Error reporting
 - Histogram publication
 - Event sampling

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- In Run2 a new tool was introduced for persistent storage of the monitoring data:
 - PBEAST: Persistent Back-End for AtlaS Tdaq

PBEAST: Persistent Back-End for AtlaS Tdaq

- Time-series database to store monitoring information
- Stores an important fraction of operational data from ATLAS
 - Up to 500 kHz attributes refresh rates
 - 1 TB/month in 2015 and 1.5 TB/month in 2016
 - All raw data of Run 2 are available
- PBEAST provides several programming interfaces:
 - Data insertion: via Online Monitoring API or REST API
 - Data retrieval: C++, Python and REST
- Operates on two nodes (2015q4):
 - Dual 12 cores CPU Xeon E5-2680V3 @ 2.5GHz, 256 GB RAM, 8x4TB RAID
- Custom implementation based on low level primitives of Google Protocol Buffers for data interoperability, compaction and compression
 - Cassandra and Splunk prototypes tested during Run 1 -> Unsatisfactory outcome so completely reimplemented by start of Run 2

PBEAST: Grafana dashboard

- Grafana is an open source metric analytics & visualization suite mostly for time-series data
- Custom PBEAST plugin developed:
 - Minimize the amount of transferred data
 - Minimize the required post-processing in the browser
- Perform persistent down-sampling on PBEAST server side

ATLAS data taking efficiency in 2017

 The Data Acquisition System has positively contributed to the high ATLAS efficiency in 2017 despite the more challenging conditions:

Conclusions

- Data Acquisition is a complex engineering problem making use of the latest technology
 - Electronics, computing, networking, storage...
 - Based on Run 1 experience, ATLAS DAQ has evolved to address the new challenges of Run 2
- Controlling and Monitoring data taking in ATLAS is a complex task
 - CEP engines help automate many of them, maximizing the efficiency of the system
 - New monitoring tools deployed
 - PBEAST system had to be developed for persistent storage of monitoring data
- New challenges will arise as LHC increases luminosity
 - We have begun work on addressing them

Physics Shutdown

Next challenges for the DAQ system

LHC Phase I: 2019-2024

- Bring Commercial Off-The-Shelf technology closer to the subdetectors
 - Servers and network
- Use common read-out hardware
 - New common read-out board: FELIX
 - Implement ROD functionality in SW
 - Only few subdetectors in a first instance

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Next challenges for the DAQ system

LHC Phase II: 2026-2035

- High-Luminosity LHC
 - Target: $7.5 \times 10^{34} cm^{-2} s^{-1}$
- A new DAQ is needed
 - 6 TB/s read-out
 - FELIX system expanded to all subdetectors
 - Decouple detector read-out and software trigger processing using a high throughput distributed storage system

