

Fast simulation of Time Projection Chamber response at MPD using GANs

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LAMBDA • HSE



October 29, 2020

Outline of the talk

- ▶ About us
- ▶ Introduction to Generative Adversarial Networks (GANs)
- ▶ Our approach to fast simulating TPC using GANs
- ▶ Preliminary results

About us

► People involved:

- Artem Maevskiy (NRU HSE)
- Fedor Ratnikov (NRU HSE)
- Alexander Zinchenko (JINR)

Members of the Lambda laboratory (<https://cs.hse.ru/en/lambda/>)

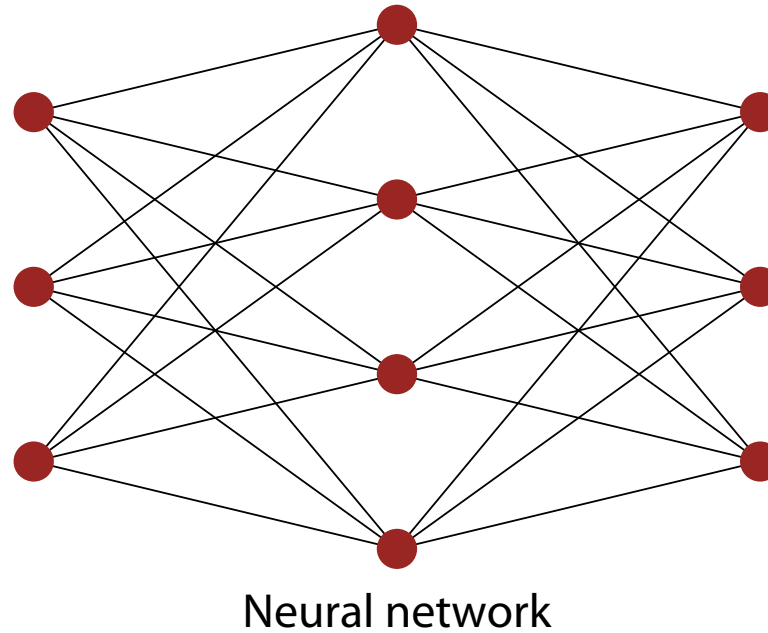
Our lab specializes in the applications of **machine learning** techniques to high energy physics problems.

We have similar projects in the LHCb experiment — developing **fast simulation models** for the Cherenkov detectors and the electromagnetic calorimeter

Generative Adversarial Networks

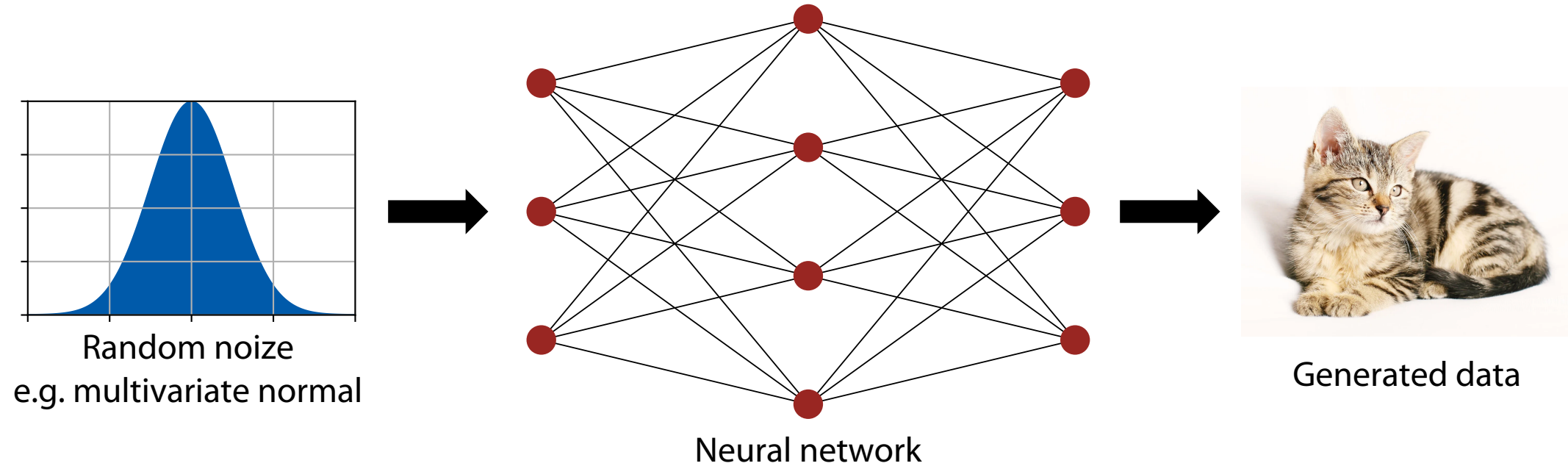


How can a neural network generate data?



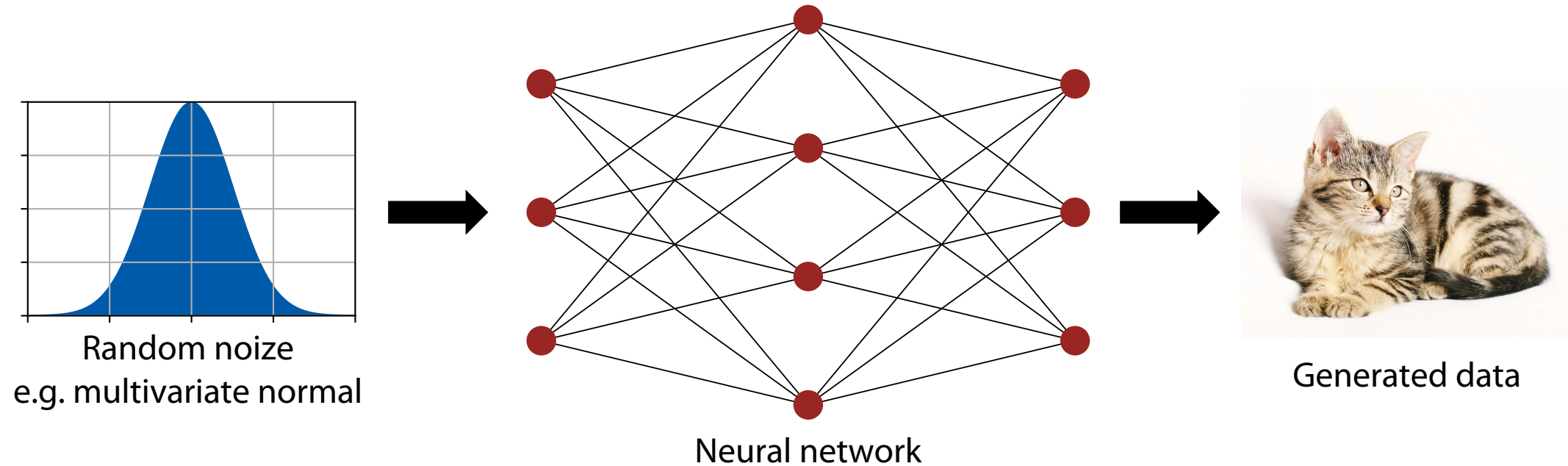
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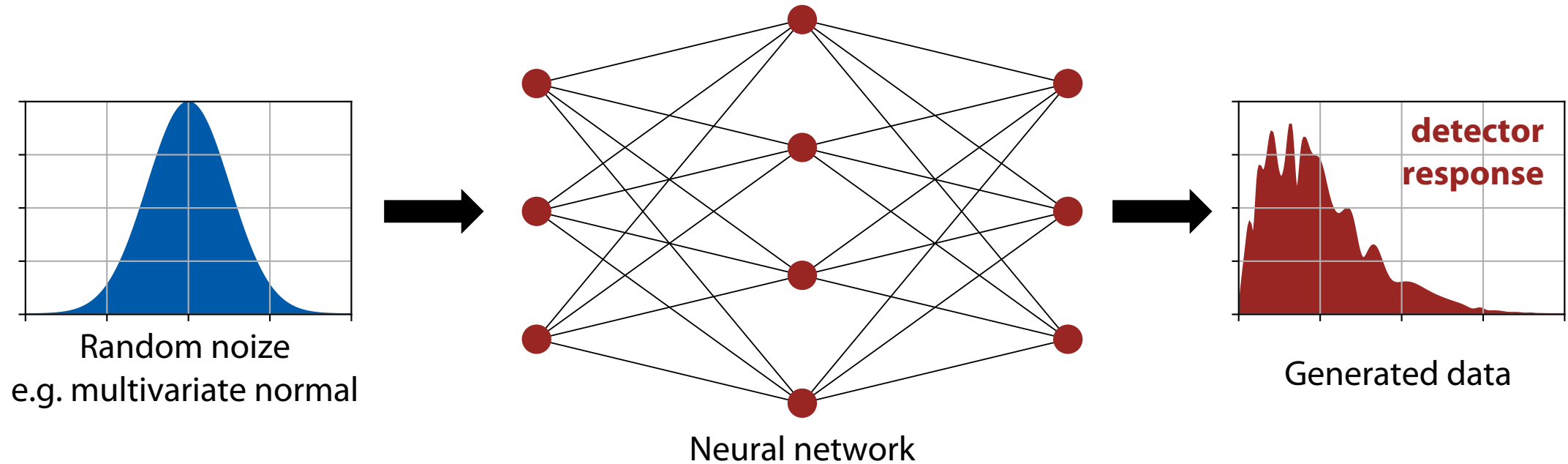
Cat image attribution: <https://pixabay.com/users/chiemsee2016-1892688/>

How can a neural network generate data?



- This makes the generated object being a **differentiable function** of the network parameters

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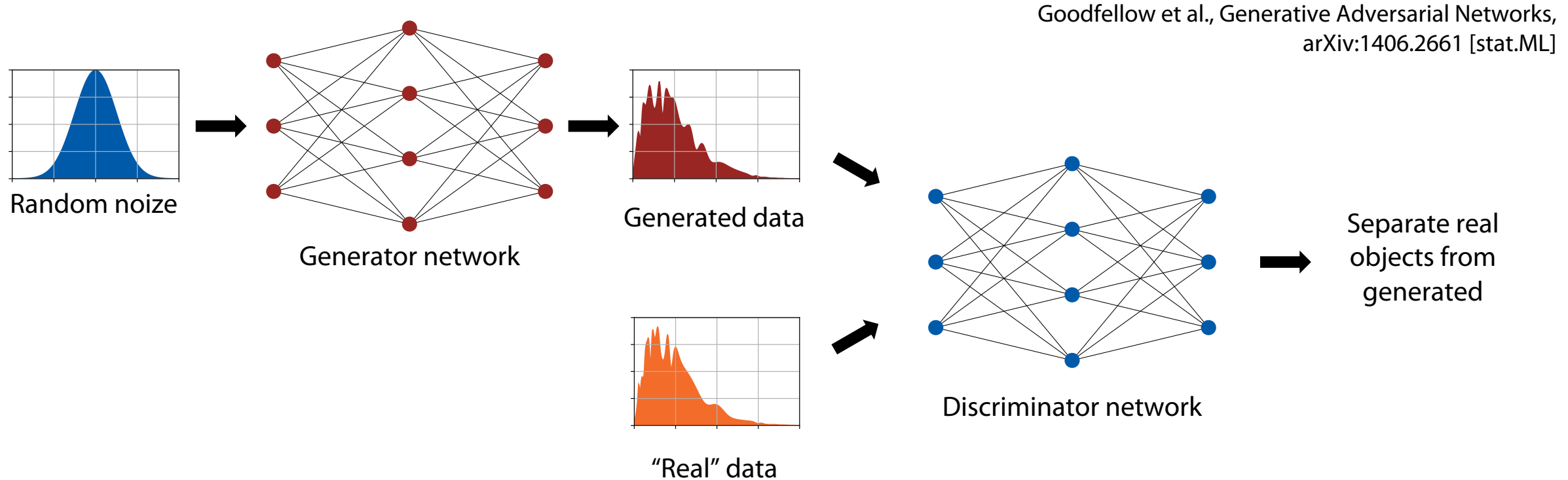


- This makes the generated object being a **differentiable function** of the network parameters

How to train such a generator?

- ▶ Generated object is a differentiable function of the network parameters
- ▶ Need a differentiable **measure of similarity** between the generated objects and real ones
 - Can optimize with gradient descent
- ▶ How to find such a measure?

Adversarial approach



- Measure of similarity: how well can another neural network (discriminator) tell the generated objects apart from the real ones

GANs for fast simulation

K. Matchev, P. Shyamsundar, Uncertainties associated with GAN-generated datasets in high energy physics, arXiv:2002.06307 [hep-ph]

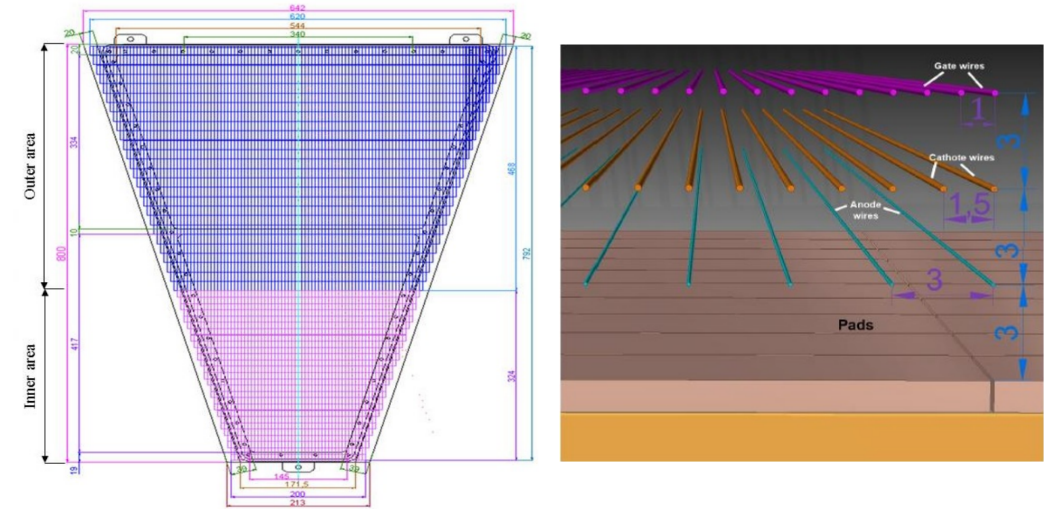
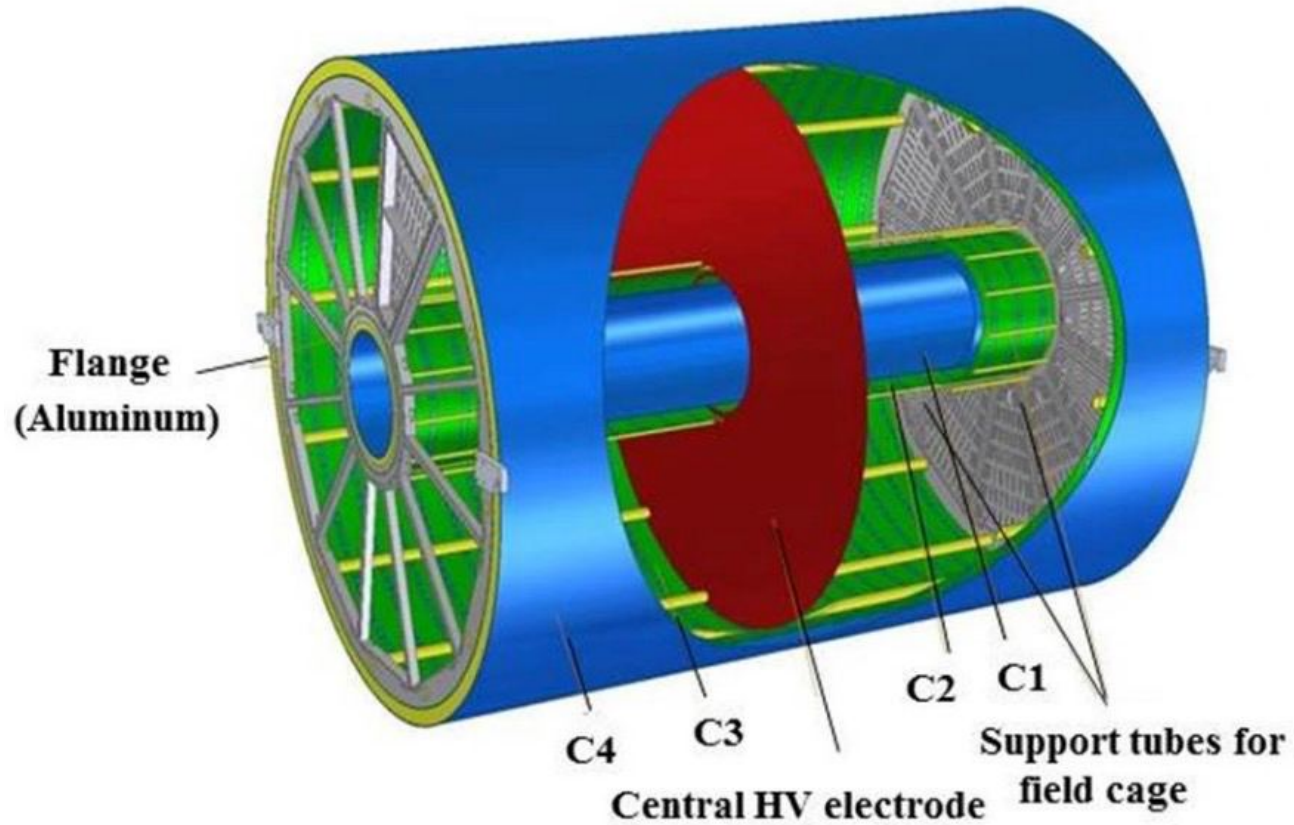
- ▶ Quite a developing field!
- ▶ Important note: one cannot increase the statistics with GANs
- ▶ GANs rather memorize and interpolate the available data

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Simulating TPC with a GAN



Time projection chamber



Pad and wire planes

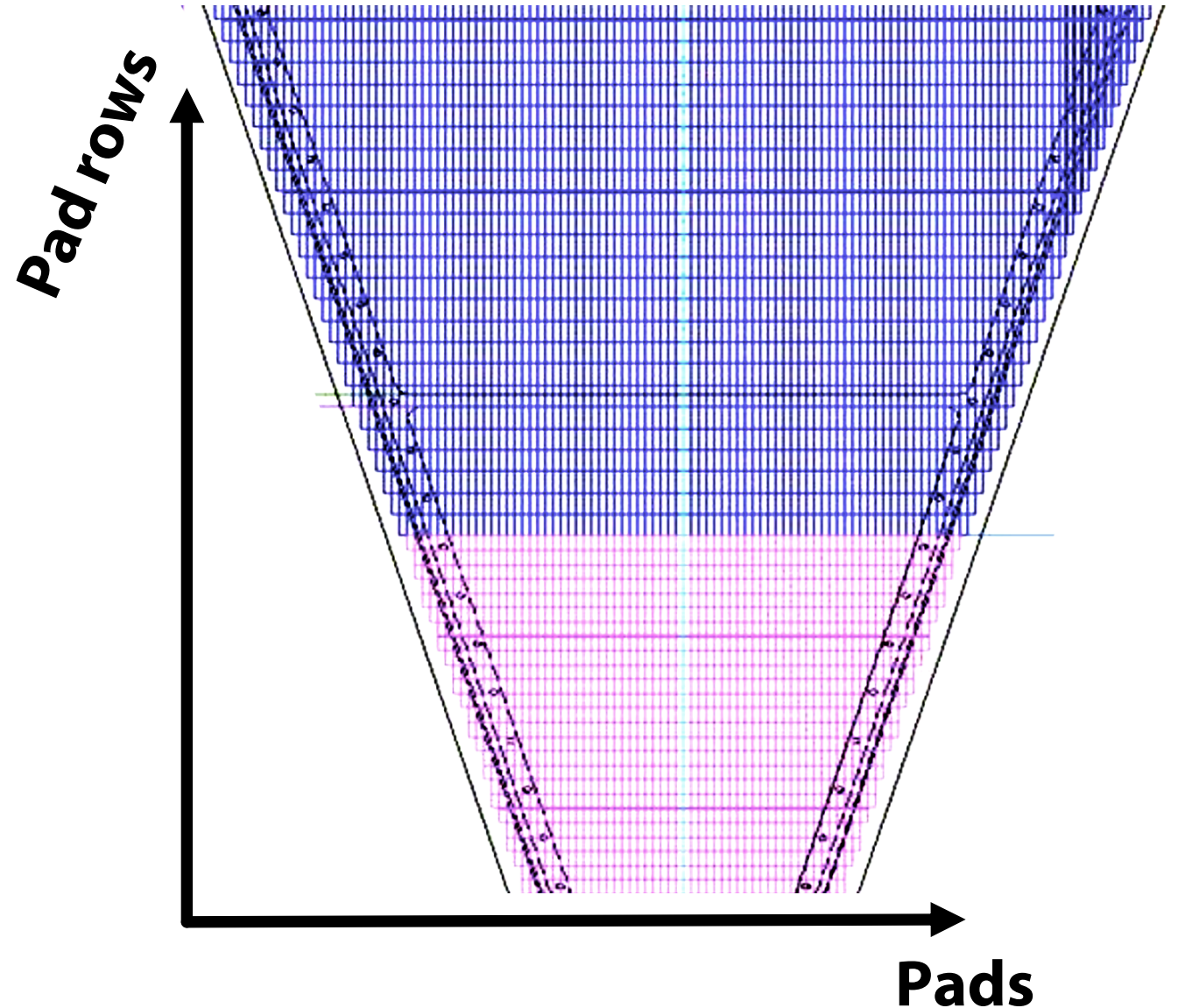
95 232 pads

**310 time
buckets**

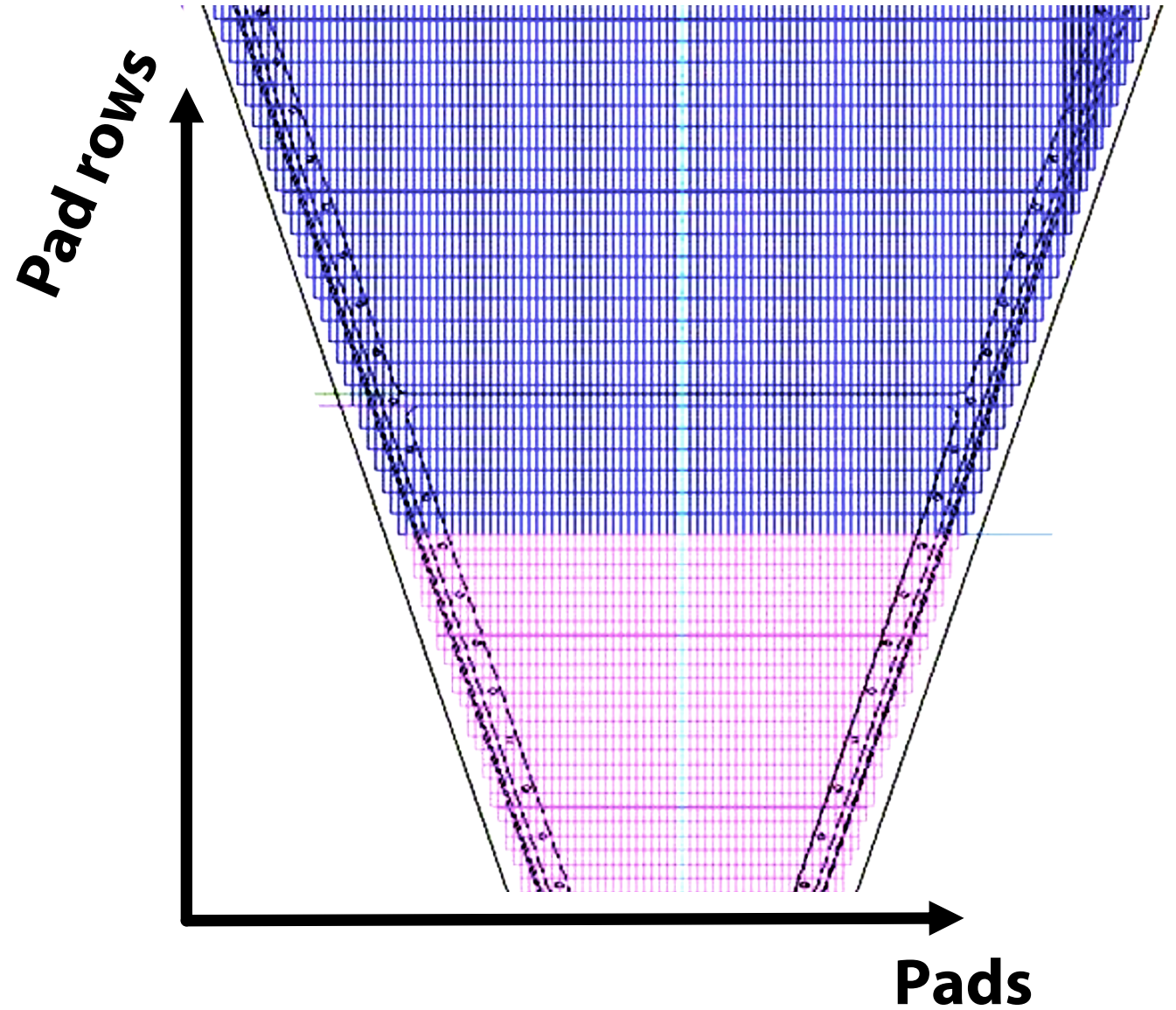
**Simulation
time:
~25 sec/event**

Objective

- ▶ For each event need to generate the signal for:
 - $95\,232 \cdot 310$ elements (pads x time buckets)
 - Conditioned on the track parameters for the whole event
- ▶ Very large output space
- ▶ Input of varying dimensionality
- ▶ Need to simplify somehow!

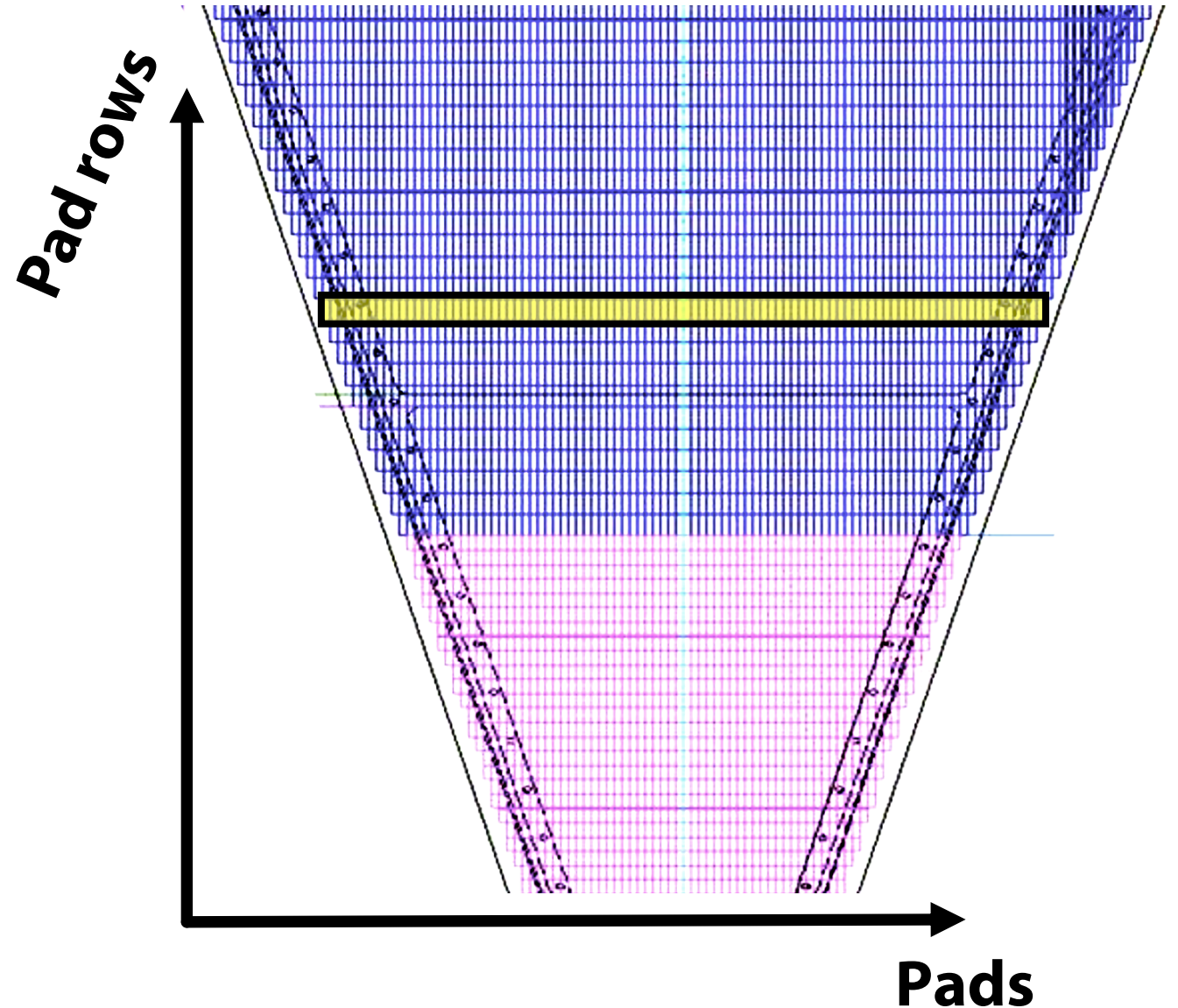


Assumptions for fast simulation



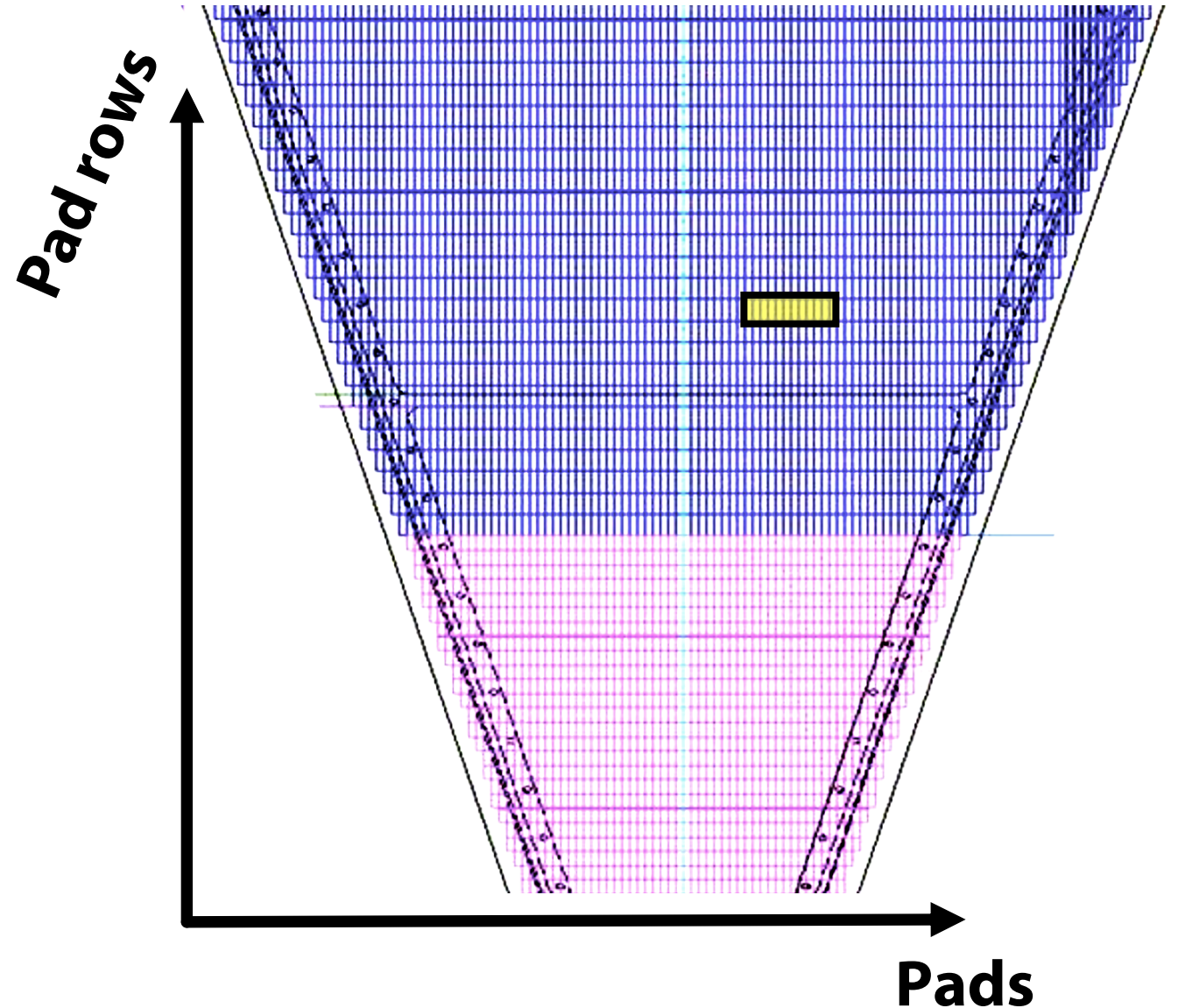
Assumptions for fast simulation

- ▶ Factorizing the pad rows
 - dividing tracks to segments, each contributing to a particular pad row
 - can model such contributions **independently!**



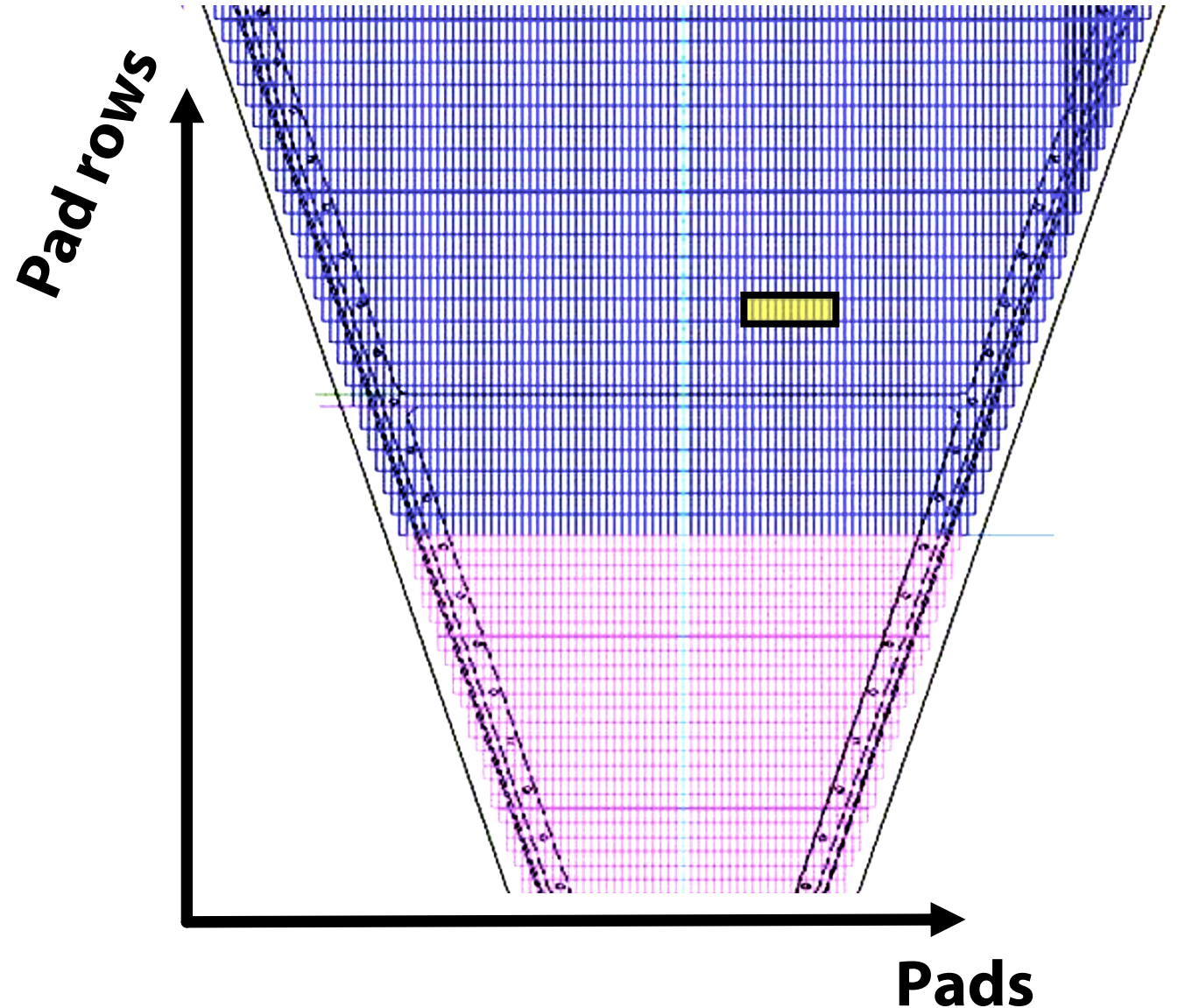
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- ▶ Signal localization (both space & time)
 - model only a **small area** instead of the full row
 - model only a **few time buckets**



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 - model only a **few time buckets**
- ▶ Target dimensionality:
8 pads x 16 time buckets



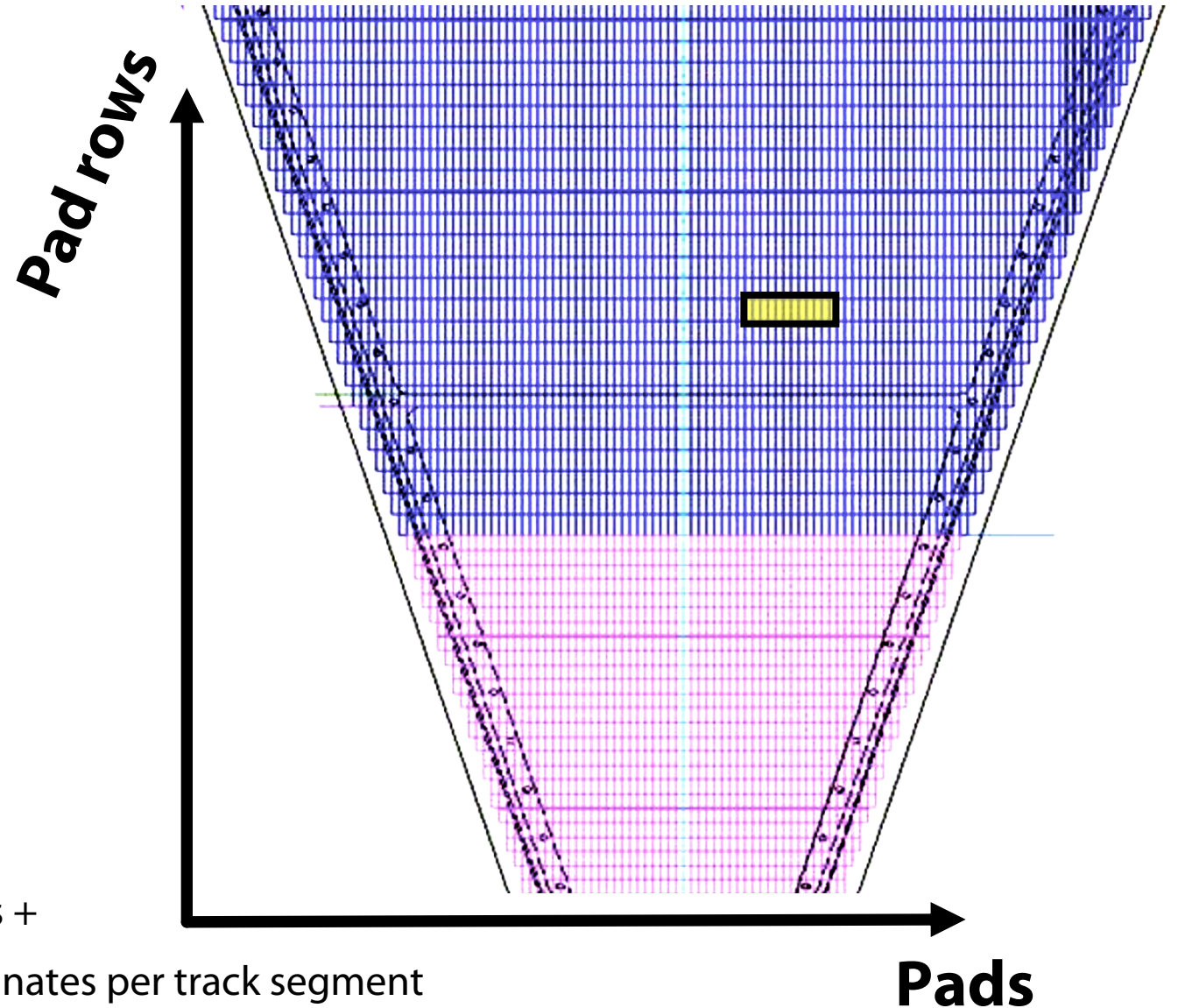
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Input:

2 angles +

3 coordinates per track segment



Model details

- ▶ Model: WGAN-GP (arXiv:1704.00028 [cs.LG])
- ▶ Generator:
 - Fully connected
 - ELU activations
 - 5 layers
- ▶ Discriminator:
 - Deep convolutional NN
 - ELU activations
 - Dropout layers
- ▶ Optimization: RMSprop, learning rate exponential decay

Model details

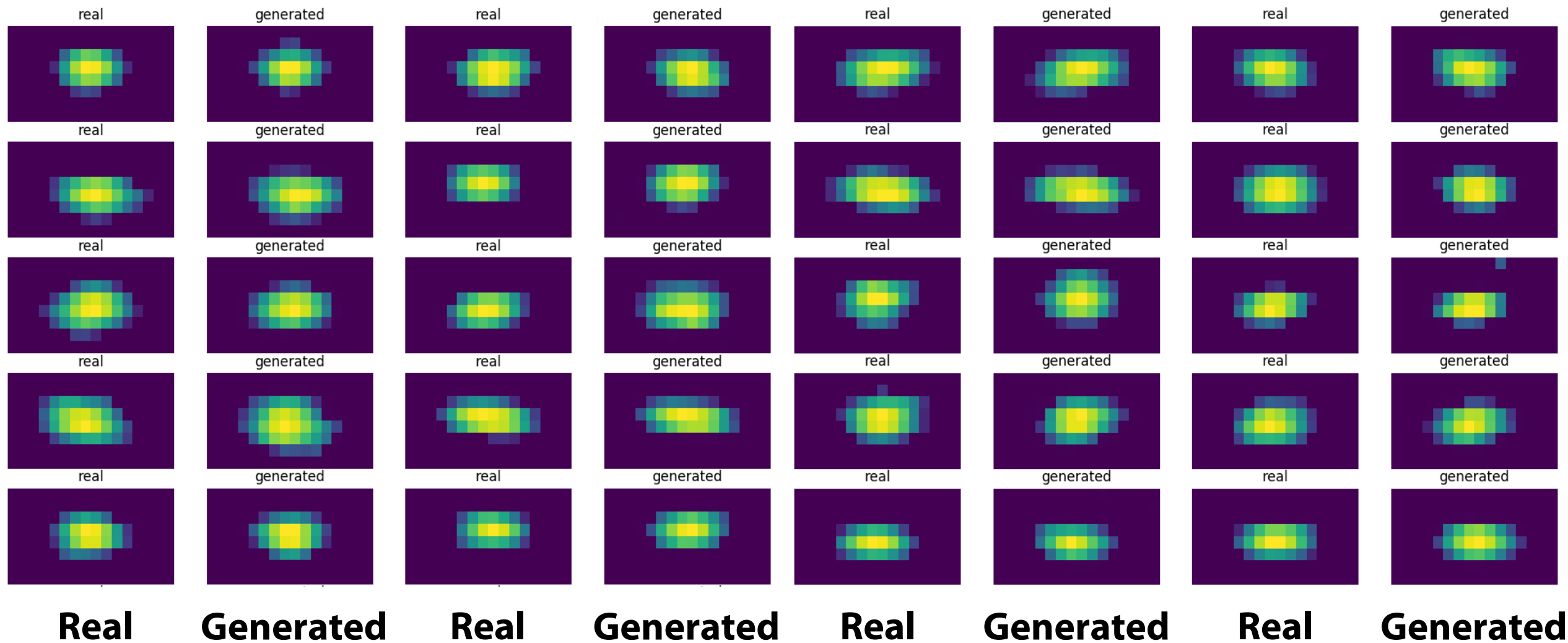
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Convolutional layers
are too slow on CPU

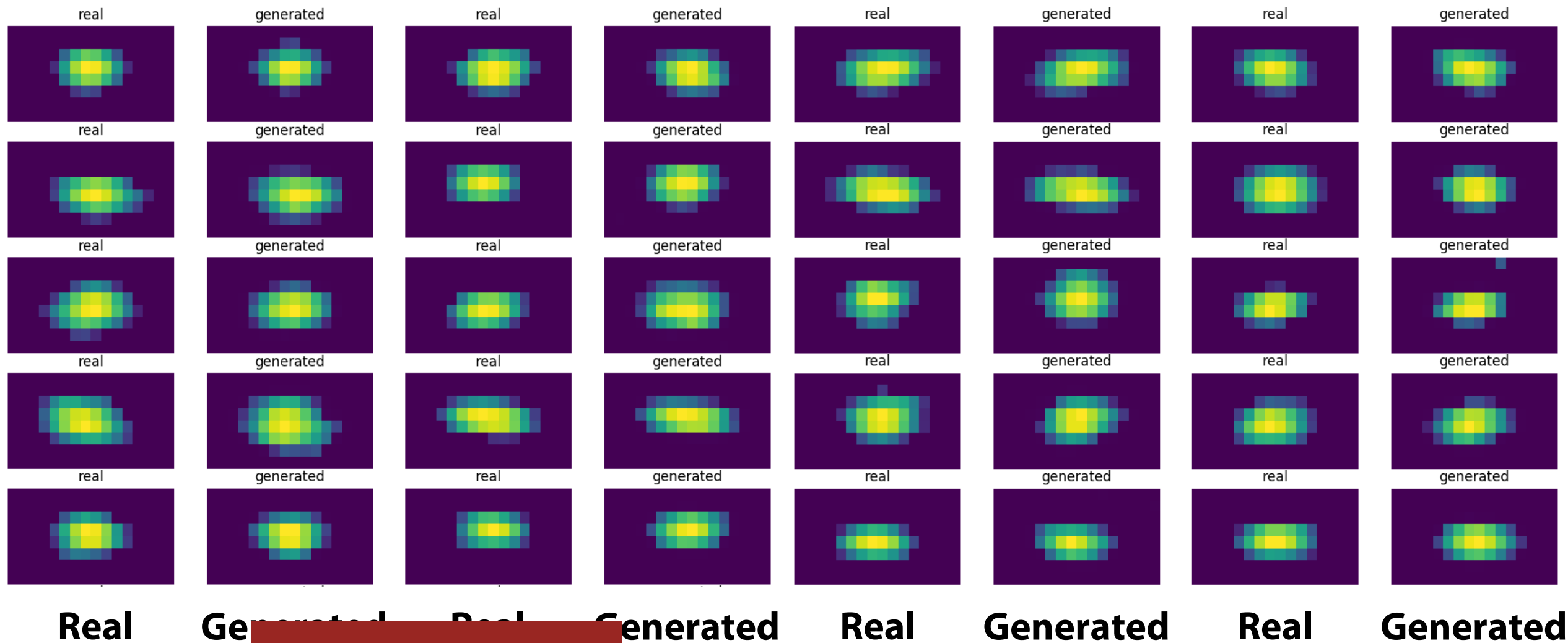
Results



Results

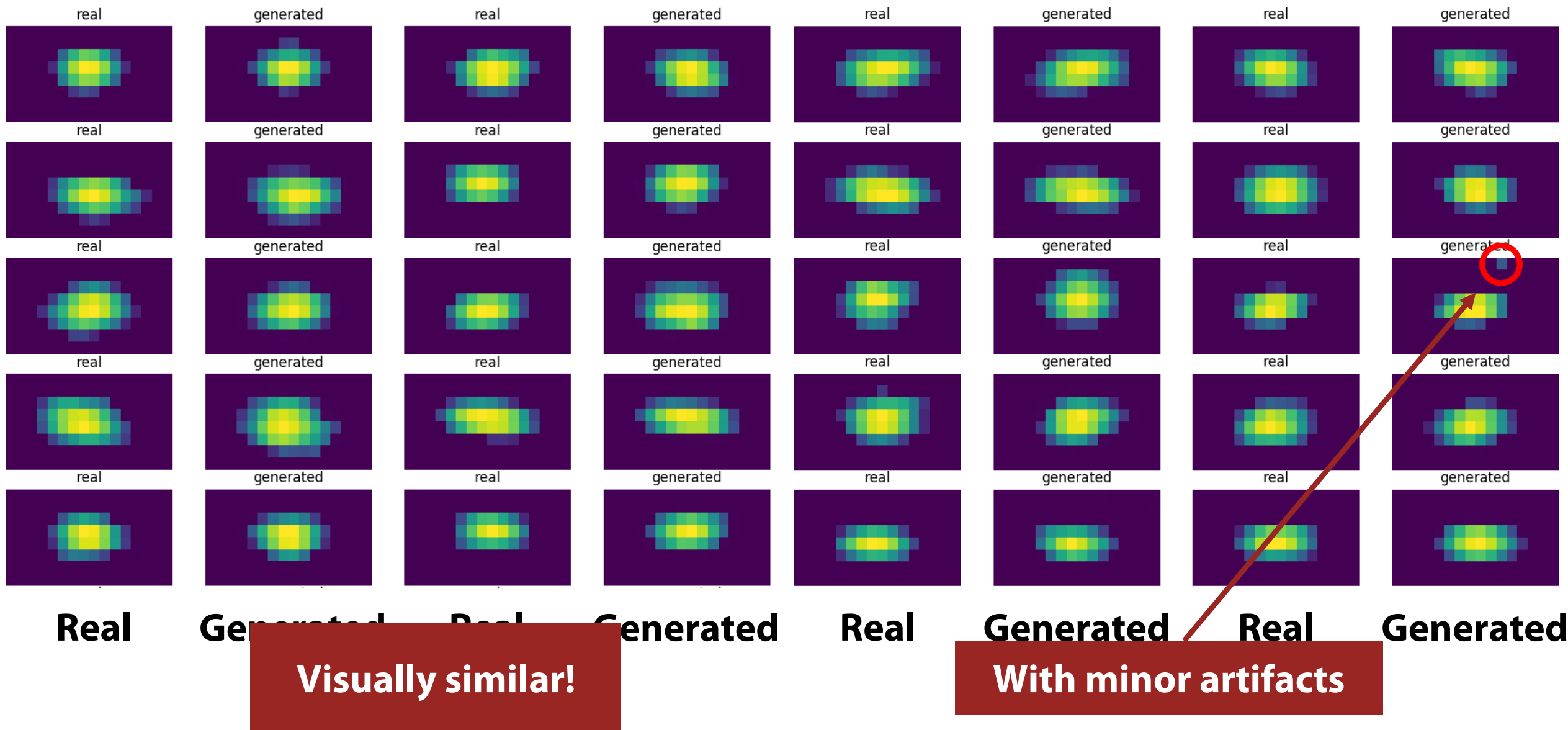


Results



Visually similar!

Results

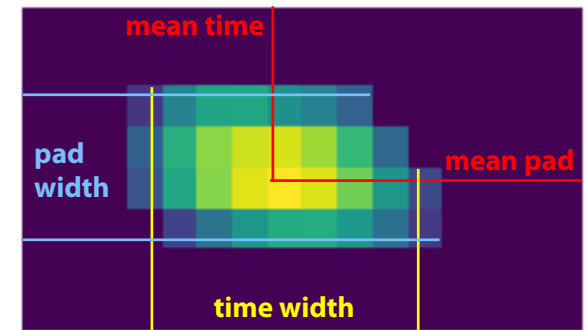


Metrics

- ▶ Model not yet integrated into the MPD software
- ▶ So far, no direct way of measuring the quality from e.g. tracking performance

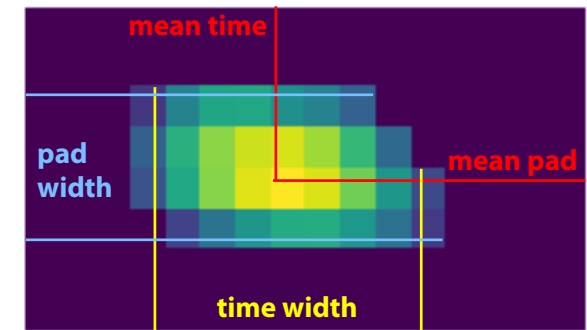
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- ▶ Instead (as a preliminary metric): we compare the 1st & 2nd order moments of the signal images, i.e.:
 - the location of the signal in pads and time bins
 - the widths of the signal in pads and time bins
 - the tilt of the signal in the pad-time matrix
- ▶ Also looking at the integrated amplitudes



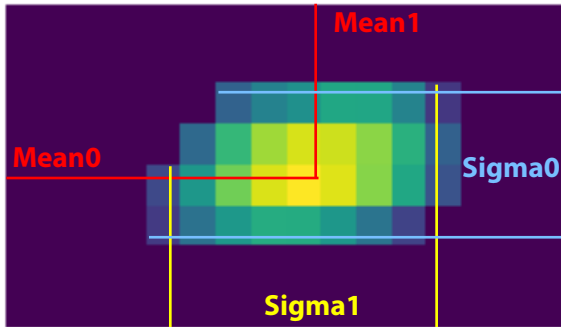
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- ▶ Also looking at the integrated amplitudes
- ▶ All this as a function of track segment parameters (2 angles + 3 coordinates)



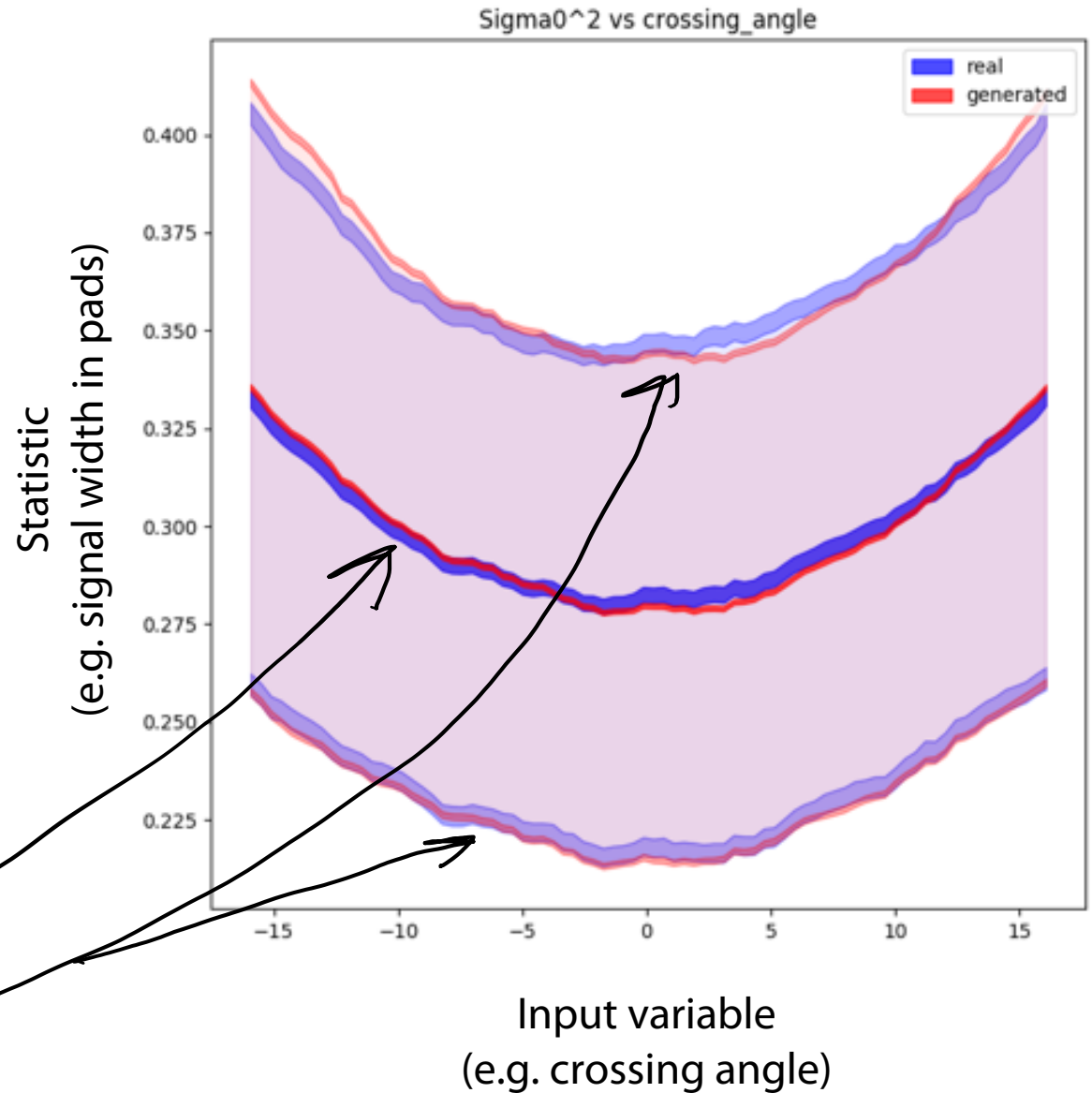
Explaining the profiles

Widths of the shaded lines correspond to the statistical uncertainties

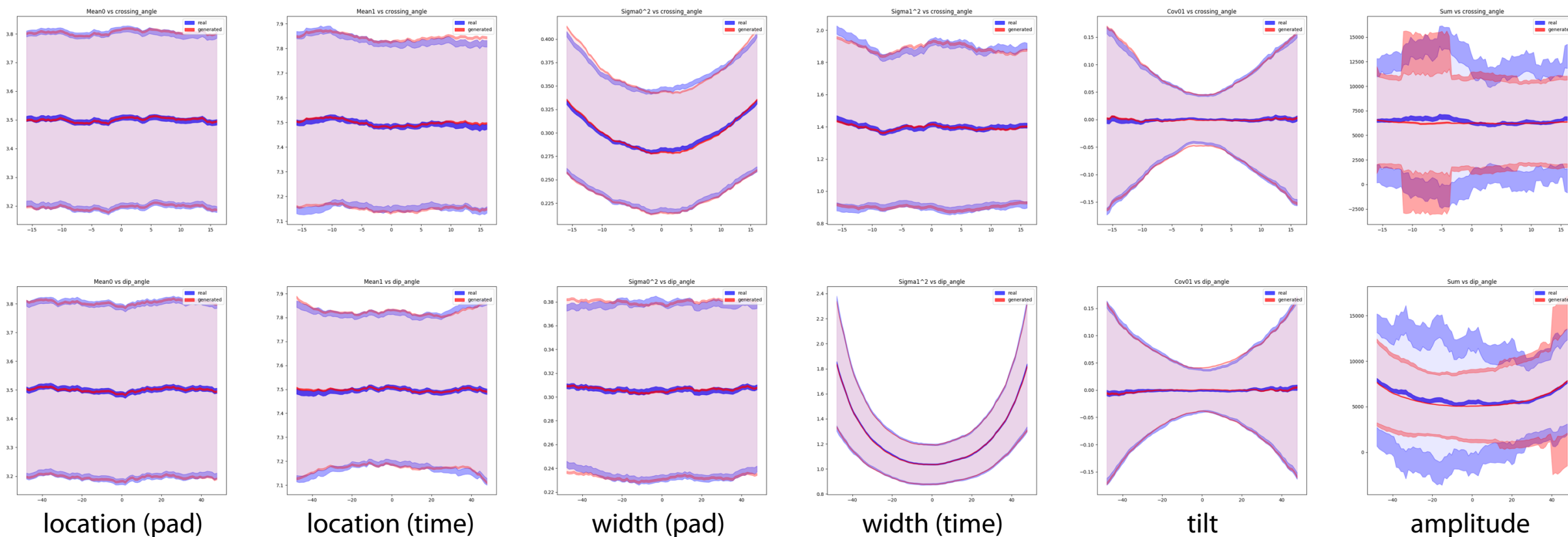


Mean of the statistic

Mean $\pm$ 1 standard deviation

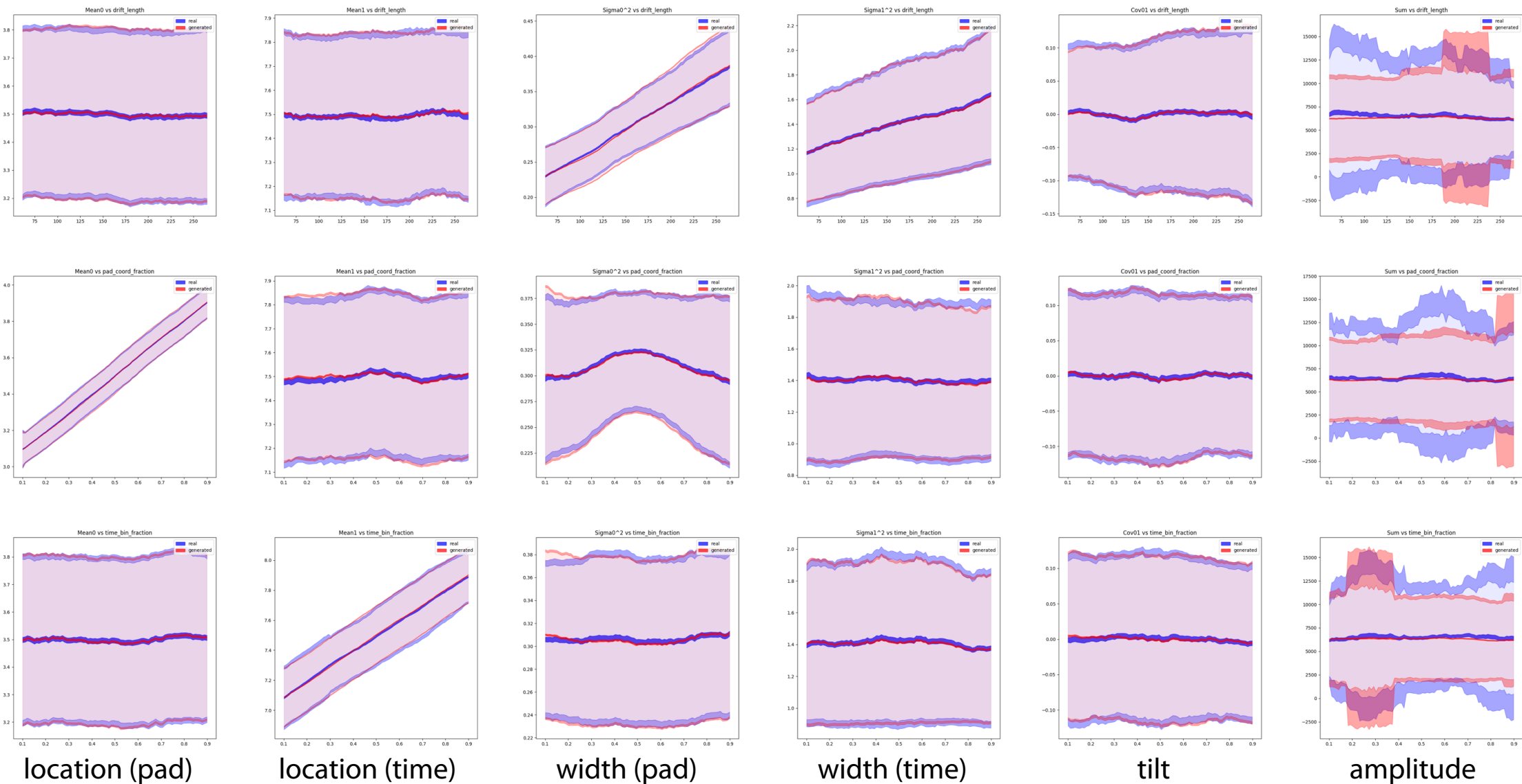


Results (profiles)



- 6 metrics vs the 2 angles

**“Real”
Generated**



► 6 metrics vs the 3 coordinates

**“Real”
Generated**

Summary

- ▶ Promising results
 - Reasonable quality according to the proposed metric
- ▶ About 30x improvement in speed
 - preliminary number, not yet estimated on the target platform
- ▶ Major TODOs:
 - Integrate our model into the MPD software stack
 - Validate the tracking and dE/dx performance from full reconstruction

Thank you!