Fast simulation of Time Projection Chamber response at MPD using GANs

MPD Physics Forum, 11 February 2021

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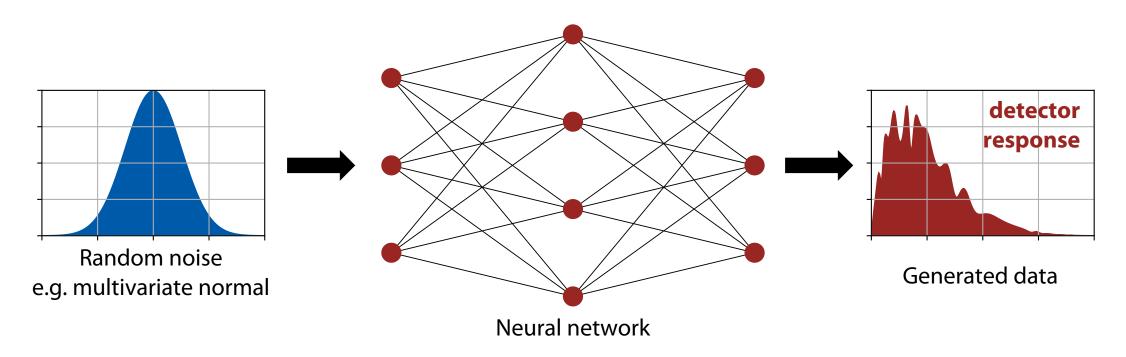






Generative Adversarial Networks and Fast Simulation

How can a neural network generate data?



- ► This makes the generated object being a differentiable function of the network parameters
 - The parameters of the network can be optimized with gradient-based methods
- Generating a sample is as fast as a single forward pass through the net

GANs for fast simulation

Quite a developing field!

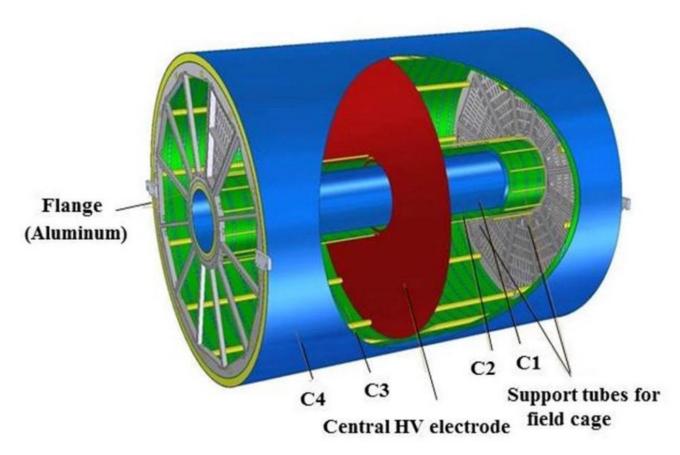
GANs interpolate the available training data

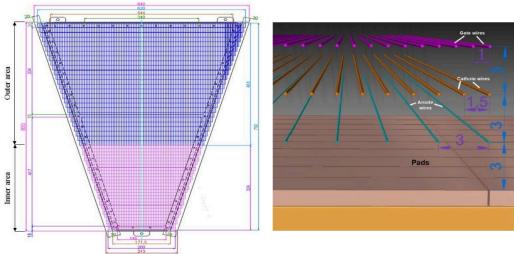
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Time projection chamber





Pad and wire planes

95 232 pads

310 time buckets

Digitization time: ~25 sec/event

Goal:

develop a deep learning model for faster digitization of TPC

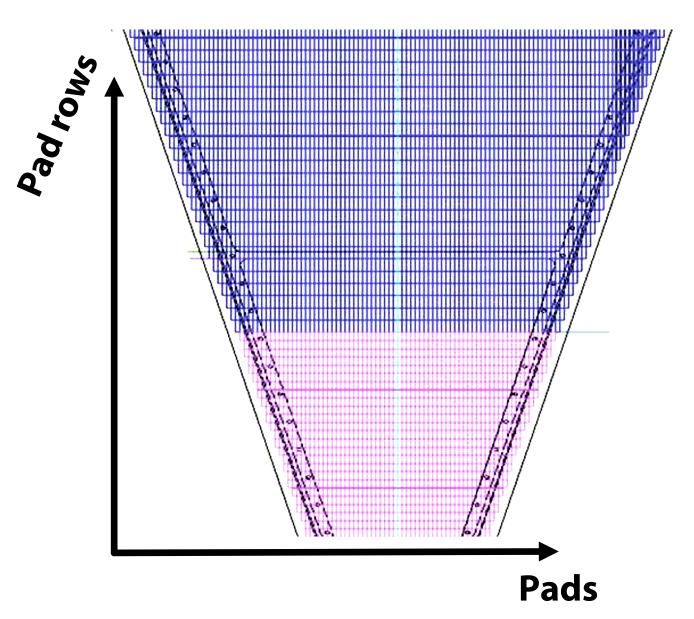
http://mpd.jinr.ru/wp-content/uploads/2019/01/TpcTdr-v07.pdf

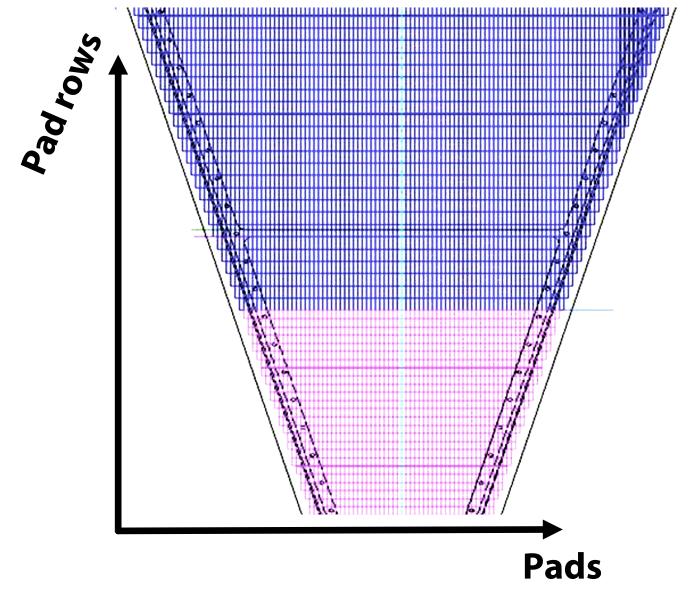
Our approach to fast simulating TPC

Objective

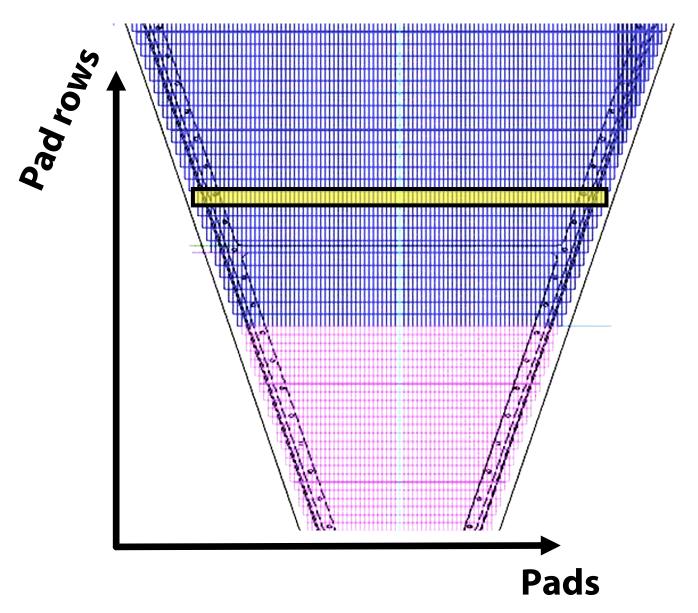
- For each event need to generate the signal for:
 - 95 232 · 310 elements (pads x time buckets)
 - Conditioned on the track parameters for the whole event
- Very large output space
- Input of varying dimensionality

Need to simplify somehow!

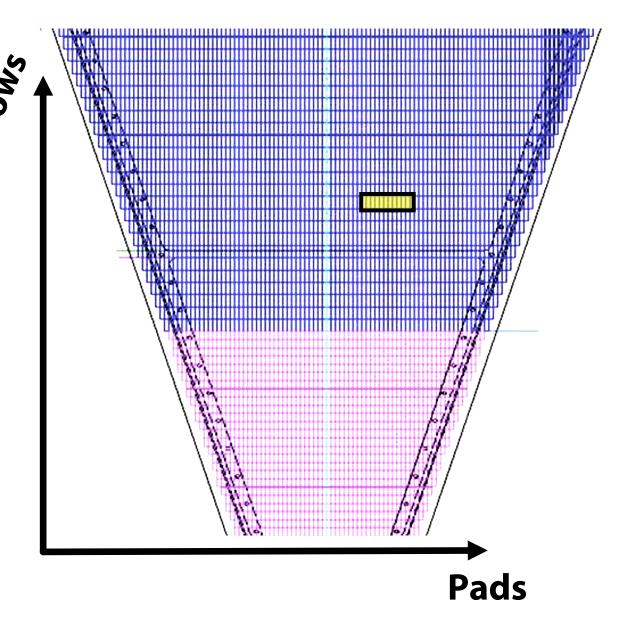




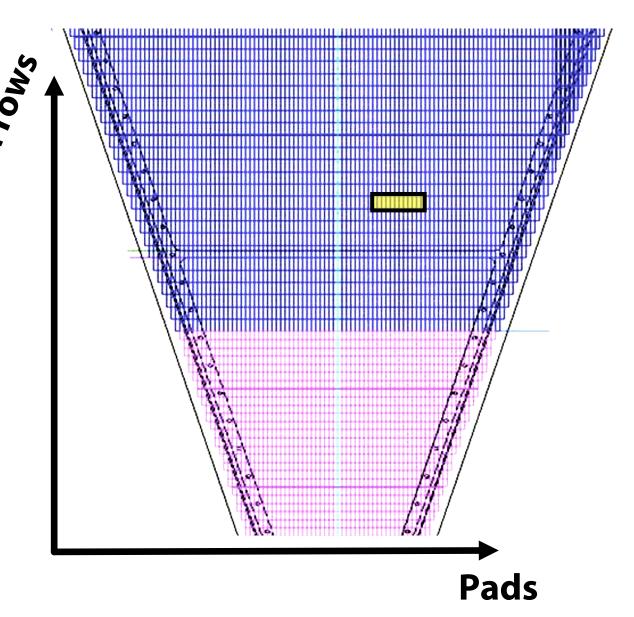
- Factorizing the pad rows
 - dividing tracks to segments, each contributing to a particular pad row
 - can model such contributions independently!



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- Signal localization (both position & time)
 - model only a small area instead of the full row
 - model only a few time buckets



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- Signal localization (both position & time)
 - model only a small area instead of the full row
 - model only a few time buckets
- Target dimensionality:
 8 pads x 16 time buckets
 (instead of original 95 232-310)

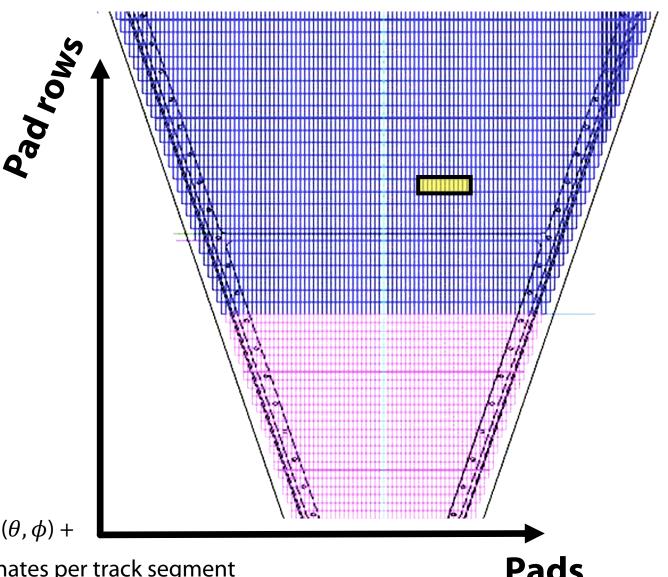


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Input:

2 angles (θ, ϕ) +

3 coordinates per track segment



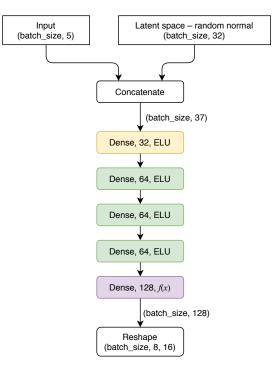
Training data

- Pion particle gun
- ▶ 20 000 pions with fixed $p_{\rm T}=478.3~{\rm MeV/c}$
- Origin point uniformly distributed along the drift path and the pad row direction
- Uniformly distributed azimuthal and polar angles

Model details

- Model: WGAN-GP (arXiv:1704.00028 [cs.LG])
- Generator:
 - Fully connected
 - ELU activations, custom output layer activation
 - 5 layers
- Discriminator:
 - Deep convolutional NN
 - ELU activations
 - Dropout layers
- Optimization: RMSprop, learning rate exponential decay

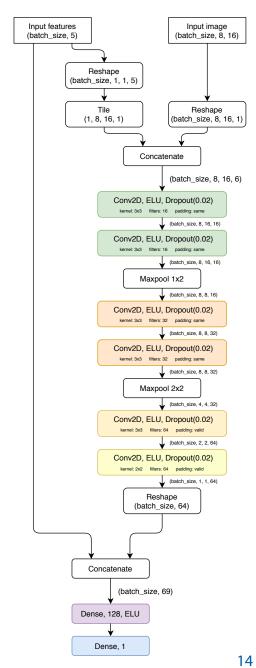
Generator



Custom activation

$$f(x) = \begin{cases} \alpha T e^x & x \le 0 \\ T\left(\alpha + (1 - \alpha)\frac{x}{\delta}\right) & 0 \le x \le \delta \\ T - \delta + x & \delta \le x, \end{cases}$$

Discriminator



Model details

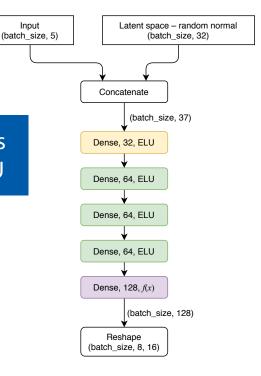
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Generator:

Convolutional layers are too slow on CPU

- Fully connected
- ELU activations, custom output layer activation
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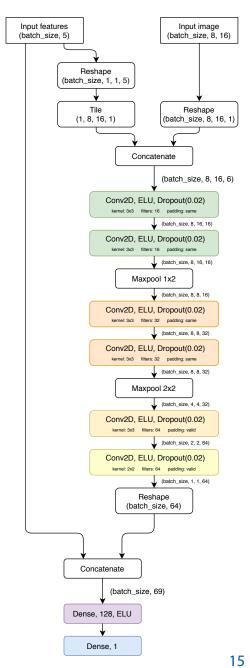
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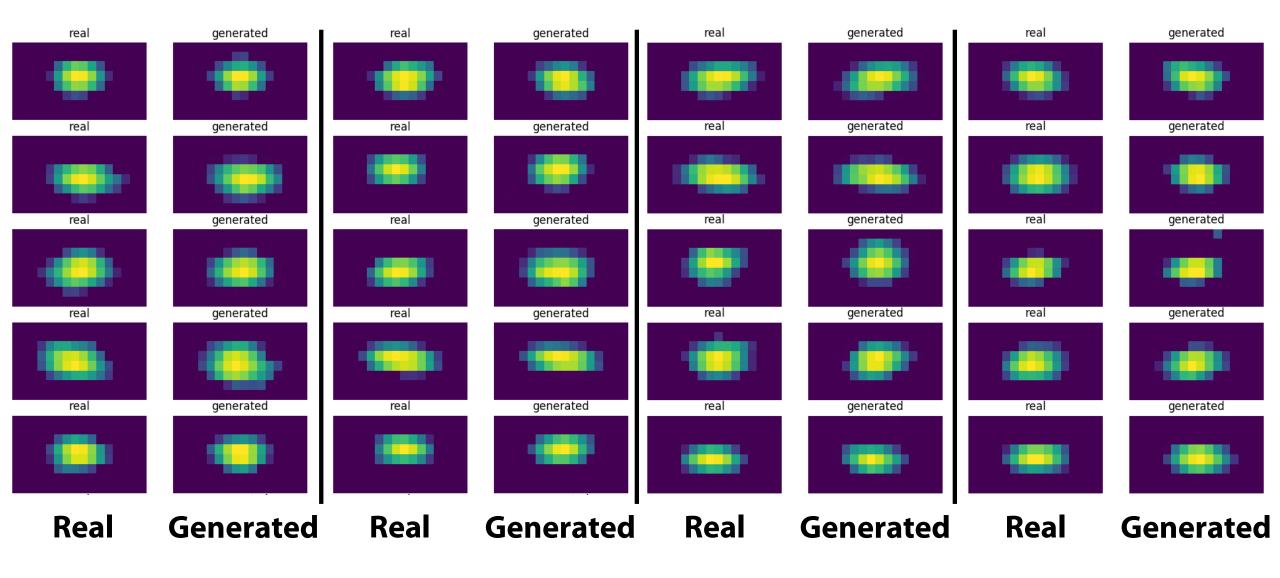
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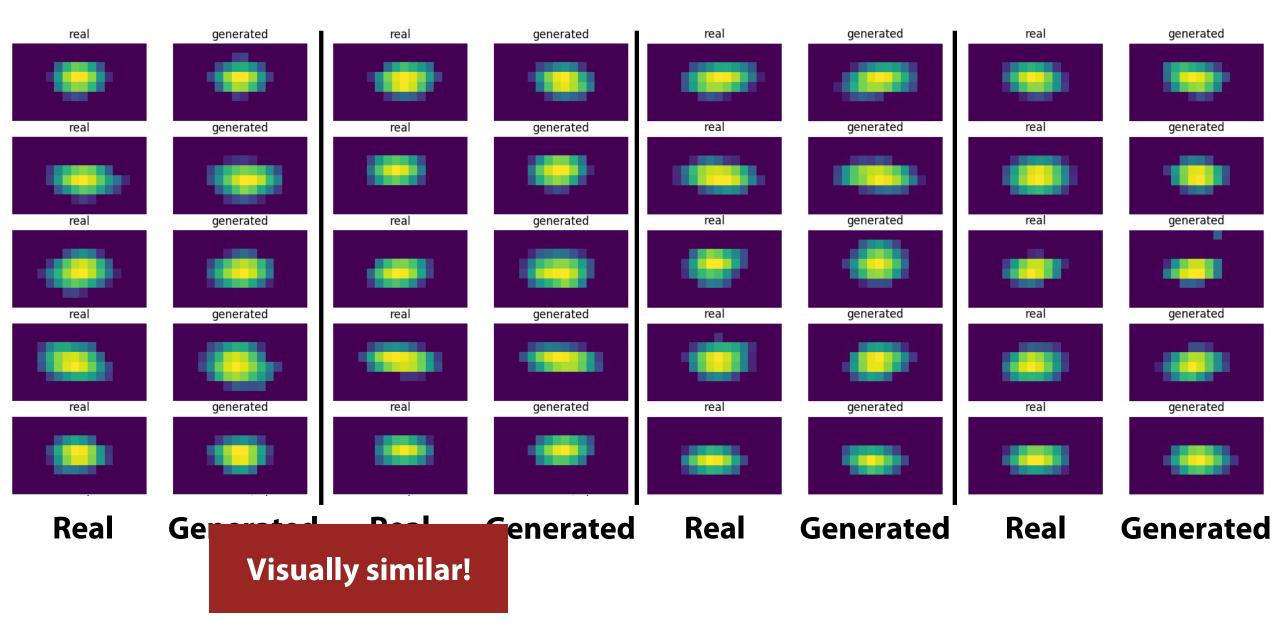
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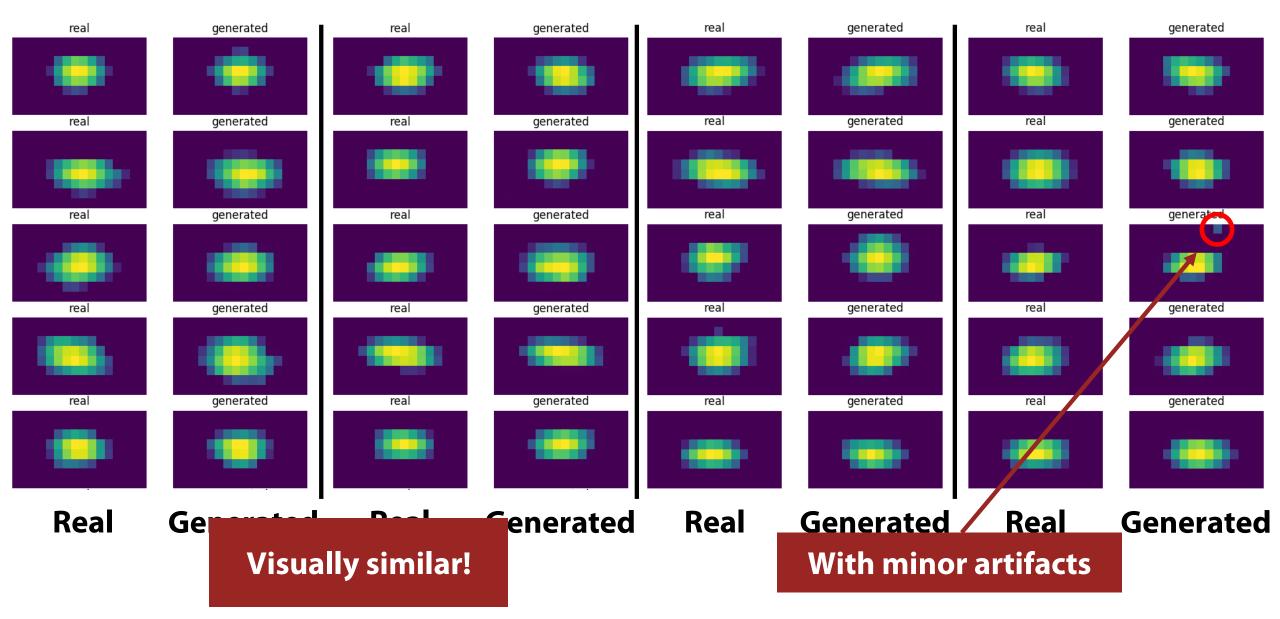
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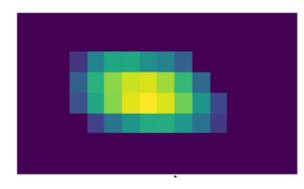




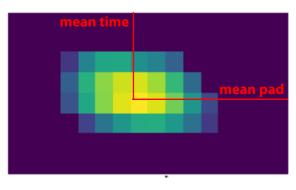




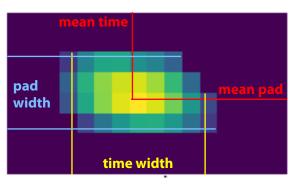
► Start with a simple preliminary metric: we compare the 1st & 2nd order moments of the signal images, i.e.:



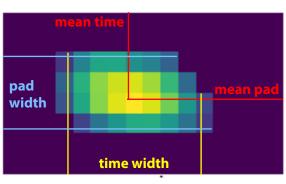
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 - the location of the signal in pads and time bins



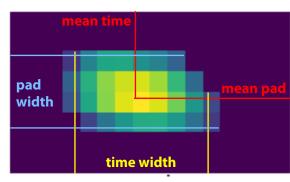
- Start with a simple preliminary metric: we compare the 1st & 2nd order moments of the signal images, i.e.:
 - the location of the signal in pads and time bins
 - the widths of the signal in pads and time bins



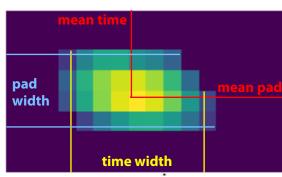
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 - the location of the signal in pads and time bins
 - the widths of the signal in pads and time bins
 - the tilt of the signal in the pad-time matrix



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 - the location of the signal in pads and time bins
 - the widths of the signal in pads and time bins
 - the tilt of the signal in the pad-time matrix
- Also looking at the integrated amplitudes

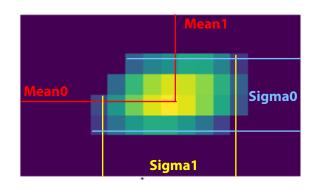


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- Also looking at the integrated amplitudes
- ► All this as a function of track segment parameters (2 angles + 3 coordinates)



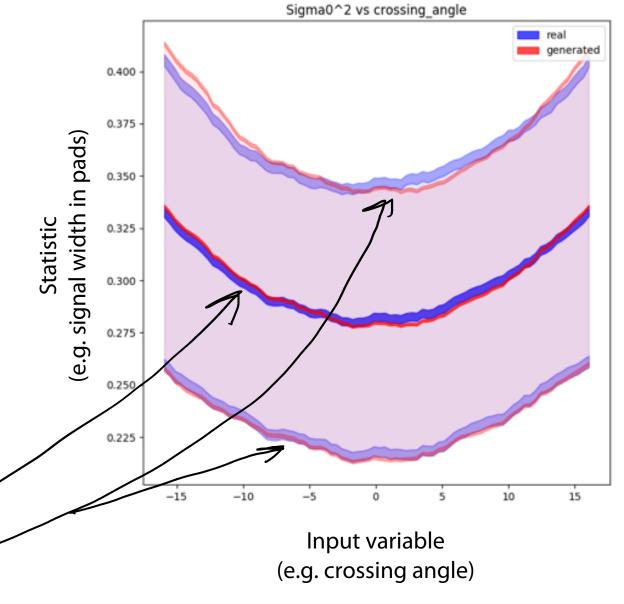
Explaining the profiles

Widths of the shaded lines correspond to the statistical uncertainties

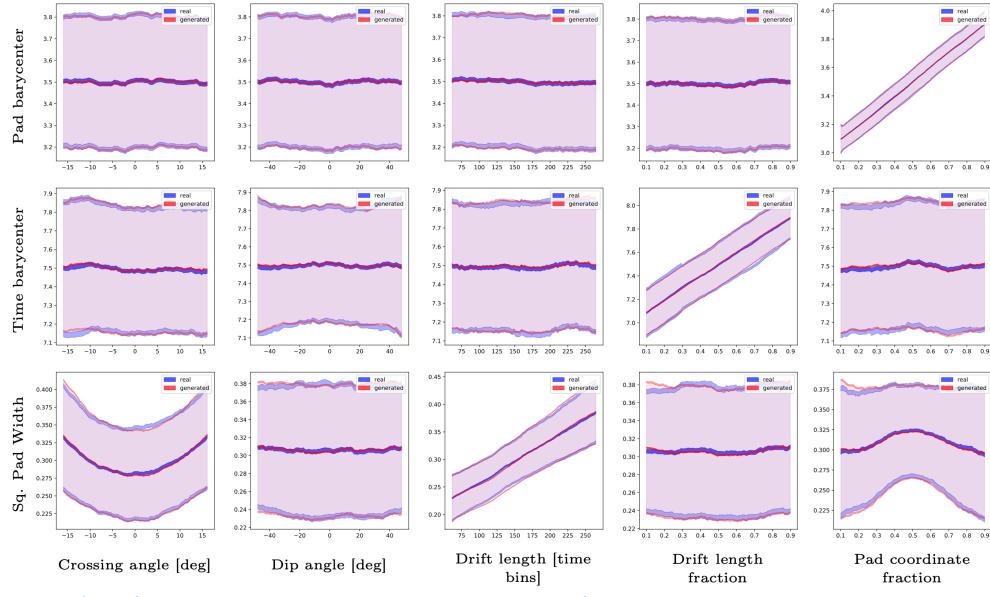


Mean of the statistic

Mean ± 1 standard deviation



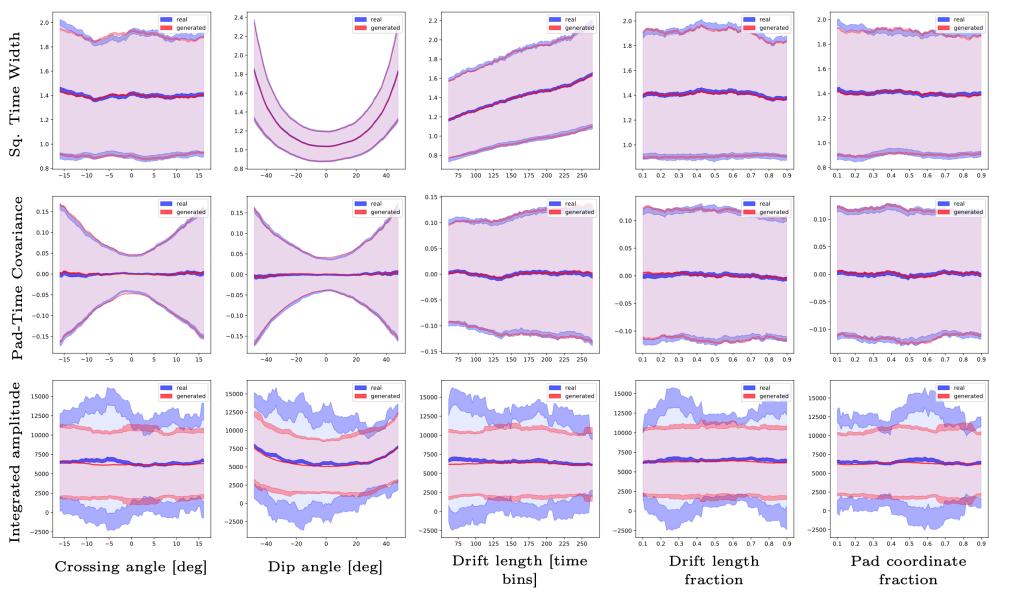
Results (profiles)



Mostly good agreement



Results (profiles)



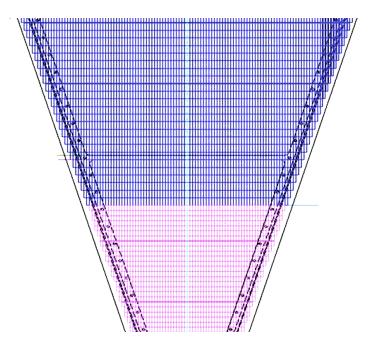
Mostly good agreement

Integrated amplitude can be factorized out and simulated separately from 1st principles



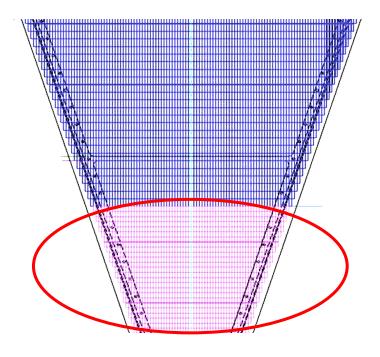
Reconstructed characteristics

- ► The model was integrated into the MPD software which allows to validate the reconstruction-level characteristics as well
- Estimated the speed-up to be of x12
 - Measured on a single core of an Intel Core i7-3770K (3.50GHz) CPU



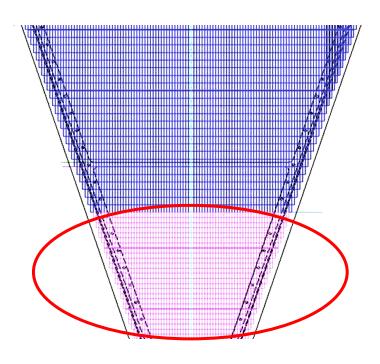
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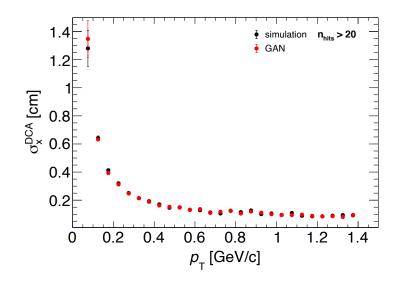
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- Note: the model was only trained on the responses from the short pads, while applied for the whole TPC



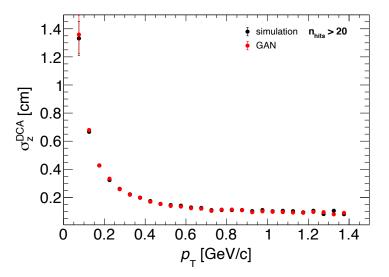
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- ► Simulated central Au+Au collisions at $\sqrt{s_{NN}} = 9$ GeV
- ► Comparison made on pions with |y| < 0.5, $n_{hits} \ge 20$

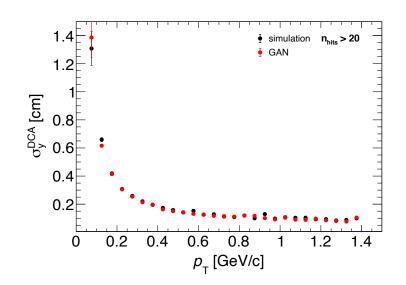




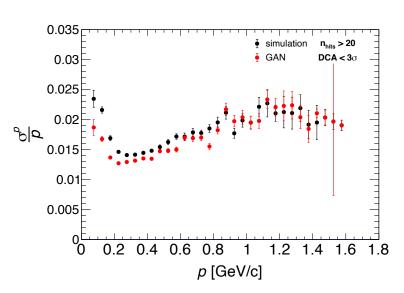
(a) Distance of closest approach resolution along x



(c) Distance of closest approach resolution along \boldsymbol{z}

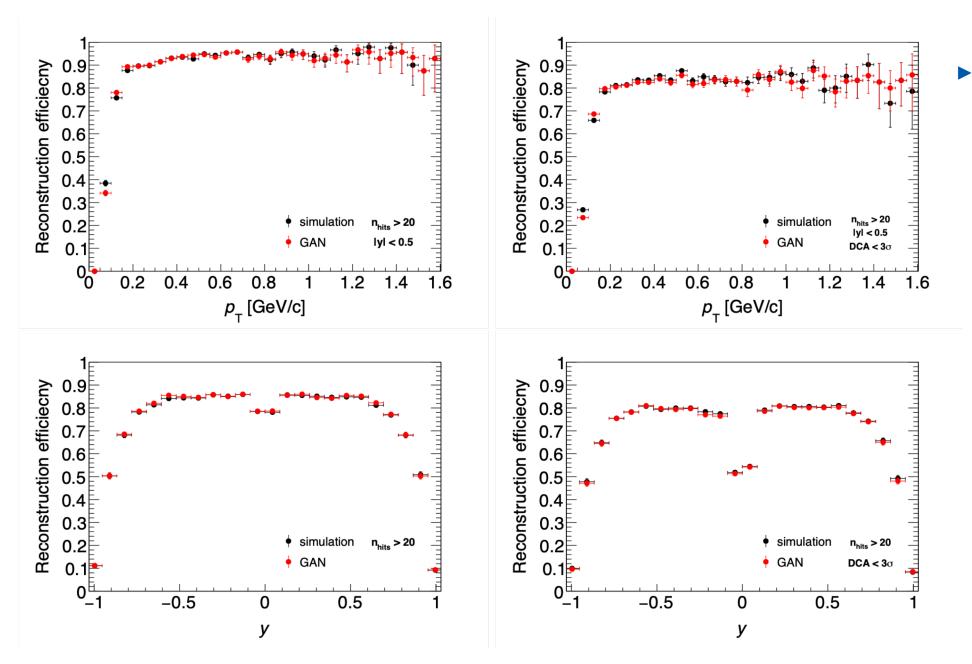


(b) Distance of closest approach resolution along y

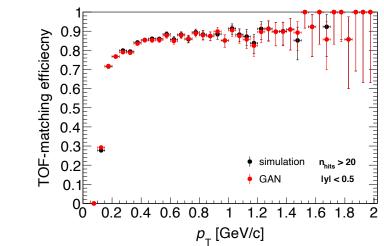


(d) Momentum resolution

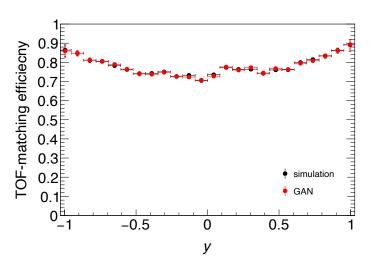
- DCA resolution well reproduced
- Momentum resolution overestimated
 - as one would expect with short pads everywhere



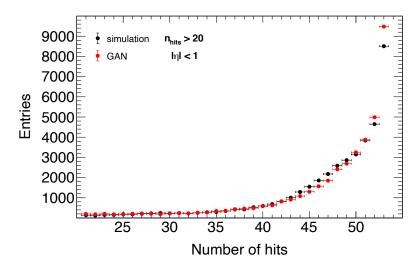
Reasonable
 agreement for the
 reconstruction
 efficiencies



(a) TOF matching efficiency as a function of the transverse momentum



(b) TOF matching efficiency as a function of the rapidity



(c) Distribution of the number of hits per track

- Good agreement in the TOF matching efficiencies
- Overestimated number of hits per track
 - again, as one would expect
 with short pads everywhere

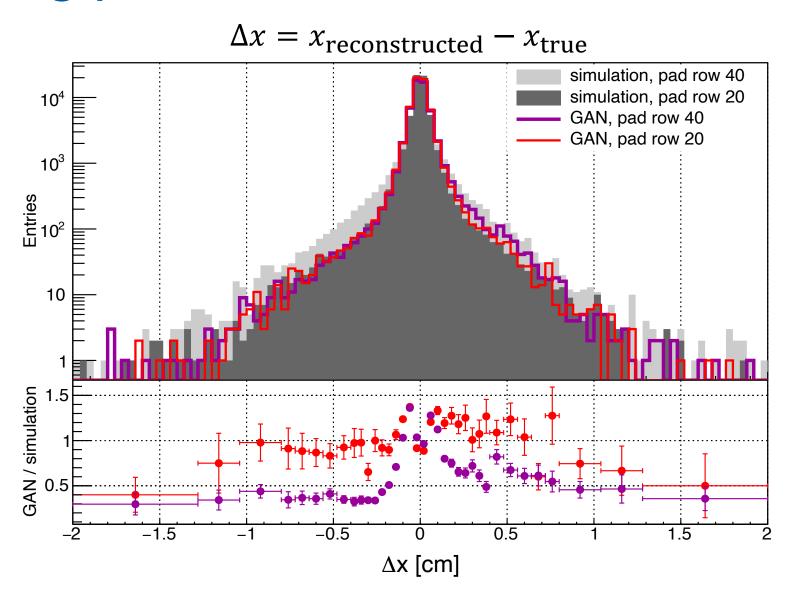
Δx for short vs long pads

- GAN predicts similar Δx for short and long pads
- betailed simulation, pad row 40

 GAN, pad row 20

 The simulation of the part o

Fig. 7. Distributions of differences $\Delta x = x_{\text{reconstructed}} - x_{\text{true}}$ between the reconstructed and true cluster coordinates along the pad row direction. For the short (long) pads from the pad row 20 (40), the detailed simulation results are shown in the dark (light) gray shaded histogram, while the histogram for the GAN prediction is shown with the red (magenta) line. The ratios between the GAN and detailed simulation yields in the same pad rows are shown in the bottom part of the plot.



Summary

- Promising results
 - Reasonable quality according to the simple metrics and reconstruction-level characteristics
- ▶ 12x improvement in speed wrt detailed TPC digitization
- ► These results are submitted to EPJC (https://arxiv.org/abs/2012.04595)

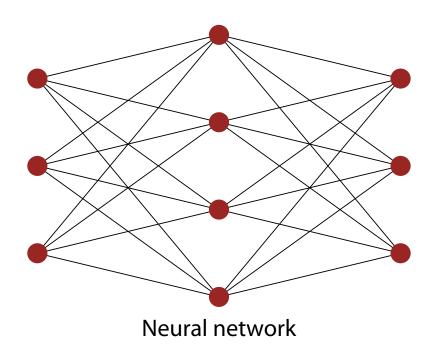
- Major TODOs:
 - Include training on responses from the long pads as well
 - Introduce more input parameters: various particle types and p_{T}

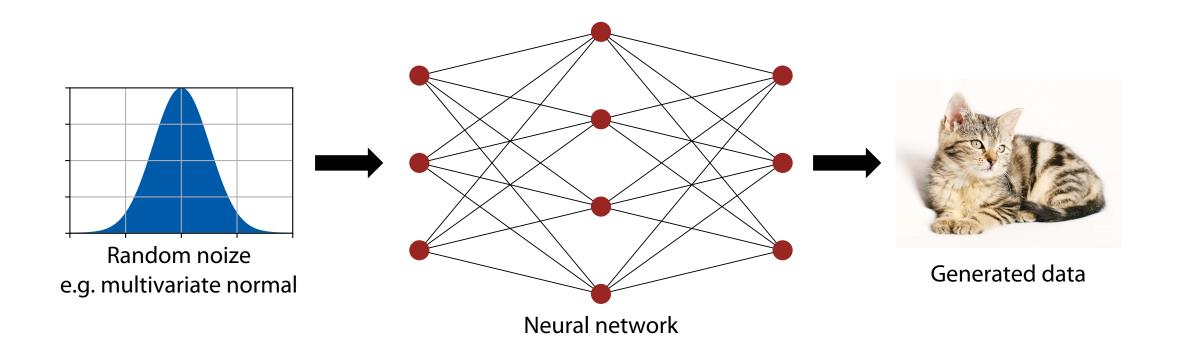
We aim to strengthen the collaboration between HSE and JINR and further improve MPD fast simulation!

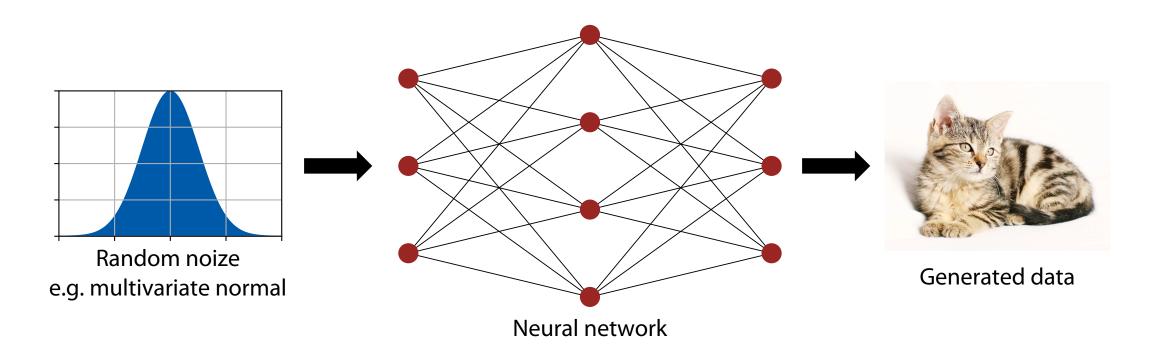
Thank you!

Backup

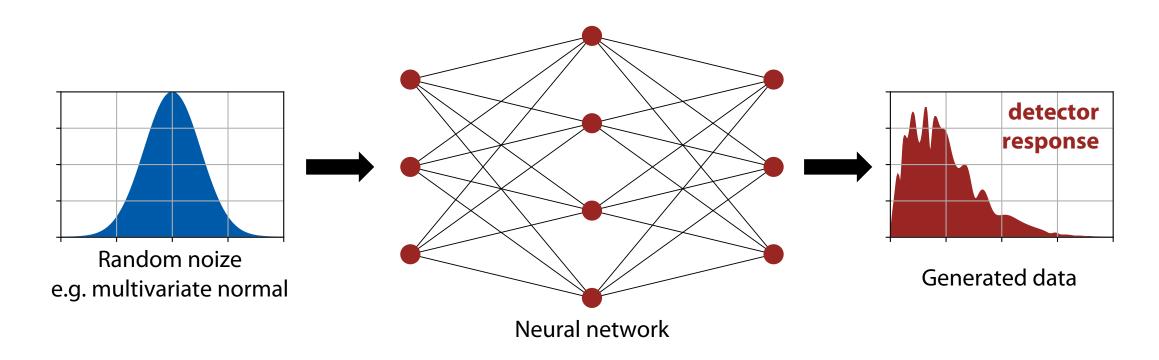
Generative Adversarial Networks







► This makes the generated object being a **differentiable function** of the network parameters

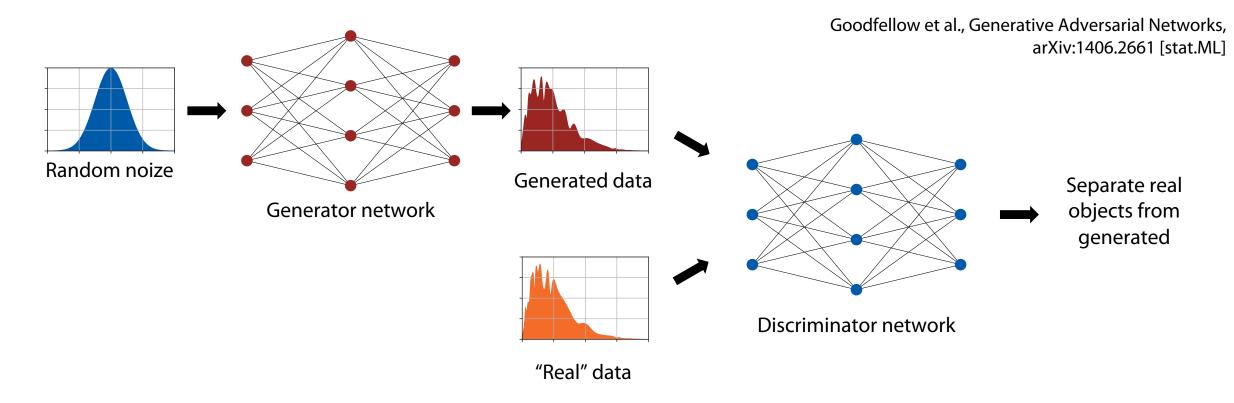


► This makes the generated object being a differentiable function of the network parameters

How to train such a generator?

- Generated object is a differentiable function of the network parameters
- Need a differentiable measure of similarity between the generated objects and real ones
 - Can optimize with gradient descent
- How to find such a measure?

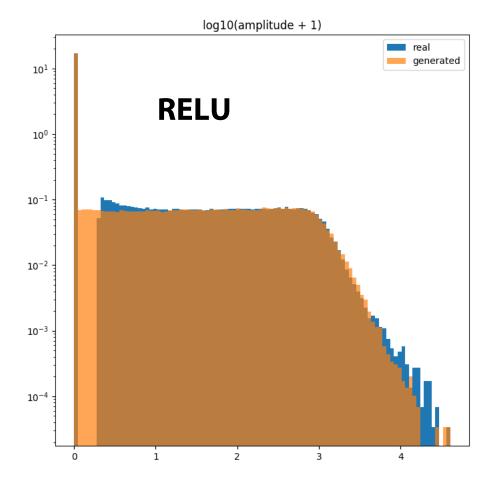
Adversarial approach



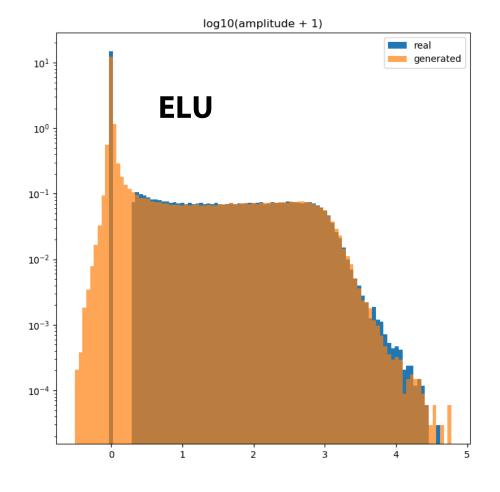
 Measure of similarity: how well can another neural network (discriminator) tell the generated objects apart from the real ones

Output layer activation functions

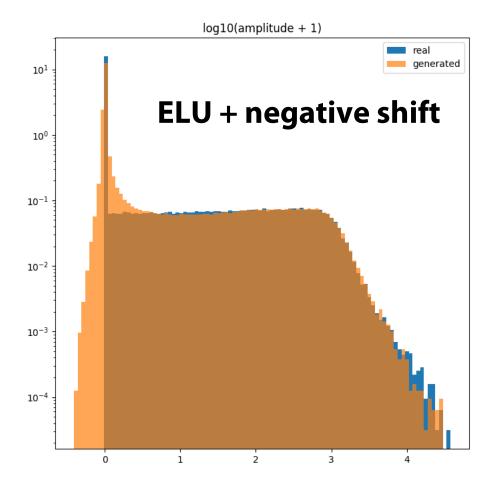
- The signal we're training on is set to 0 for signals below 1
- Problematic for a GAN to learn
- May be able to handle with a proper output layer activation



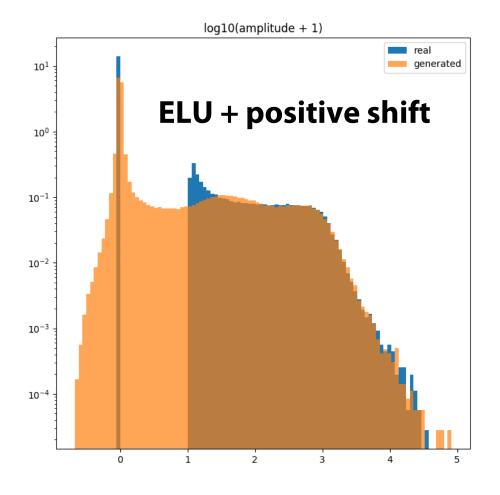
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