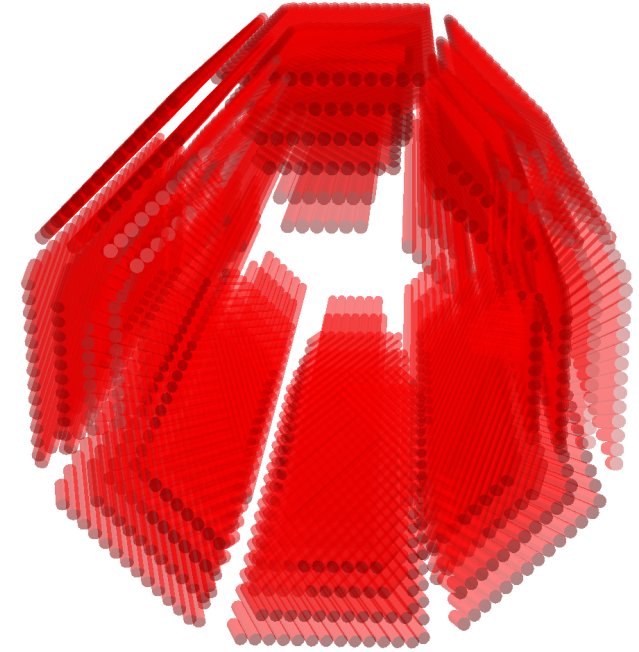
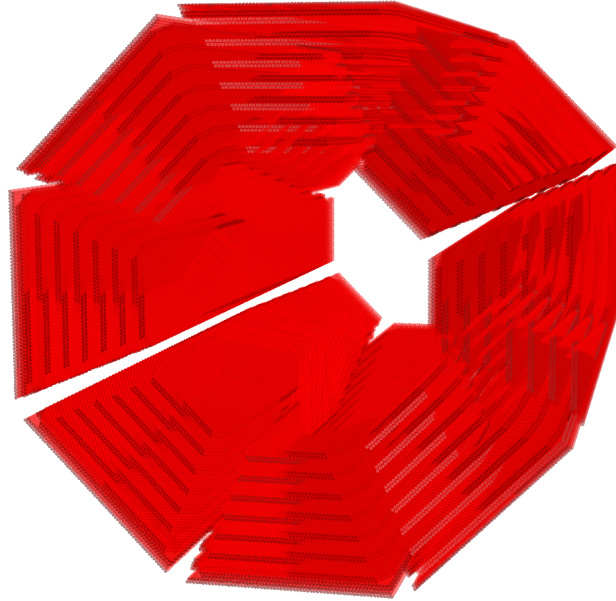
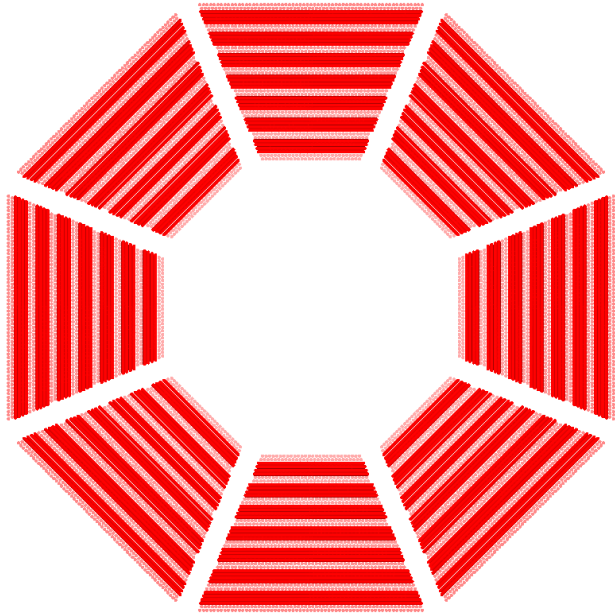


Momentum resolution dependence on straw tube orientation

Ruslan Akhunzyanov
JINR

SPD S&C meeting, Oct 26, 2021

Straw tracker geometry



```
SpdTSTBGeoMapper* mapper = SpdTSTBGeoMapper::Instance();
```

```
mapper->SetStrawModulePars(1, 0., 'e', 1.0, 0);
```

```
mapper->SetStrawLayerPars(1, 0., 'e', 1.0, 0.);
```

```
mapper->SetStrawLayerPars(1, 0., 'o', 1.0, 0.);
```

```
mapper->SetStrawLayerPars(1, deg, 'e', 1.0, 0.);
```

```
mapper->SetStrawLayerPars(1, deg, 'o', 1.0, 0.);
```

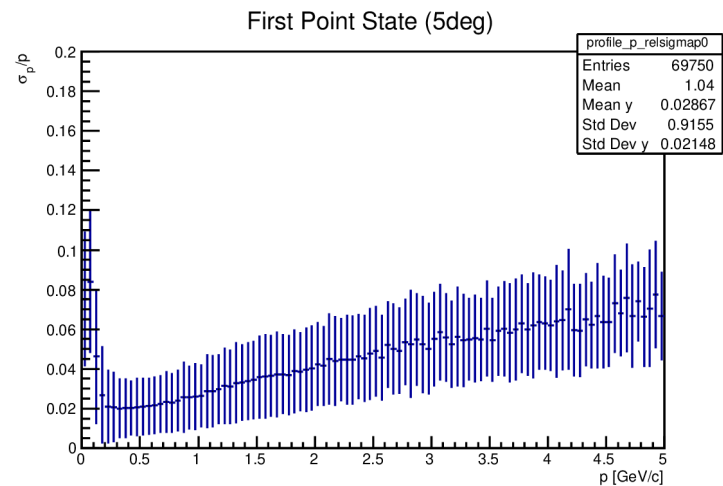
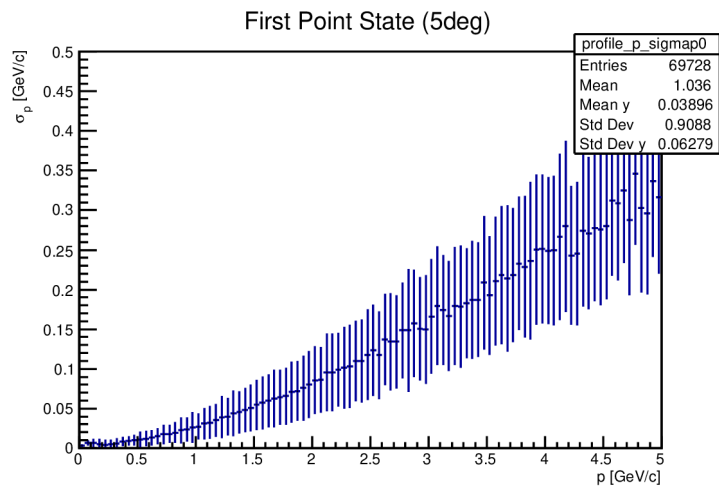
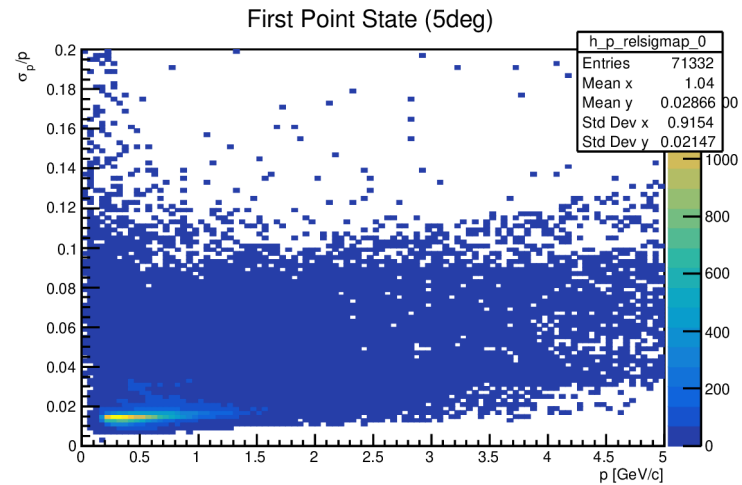
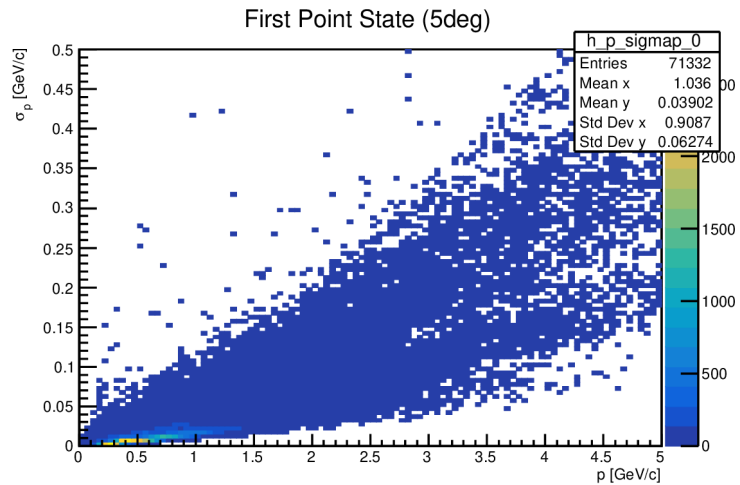
```
mapper->SetStrawLayerPars(1, -deg, 'e', 1.0, 0.);
```

```
mapper->SetStrawLayerPars(1, -deg, 'o', 1.0, 0.);
```

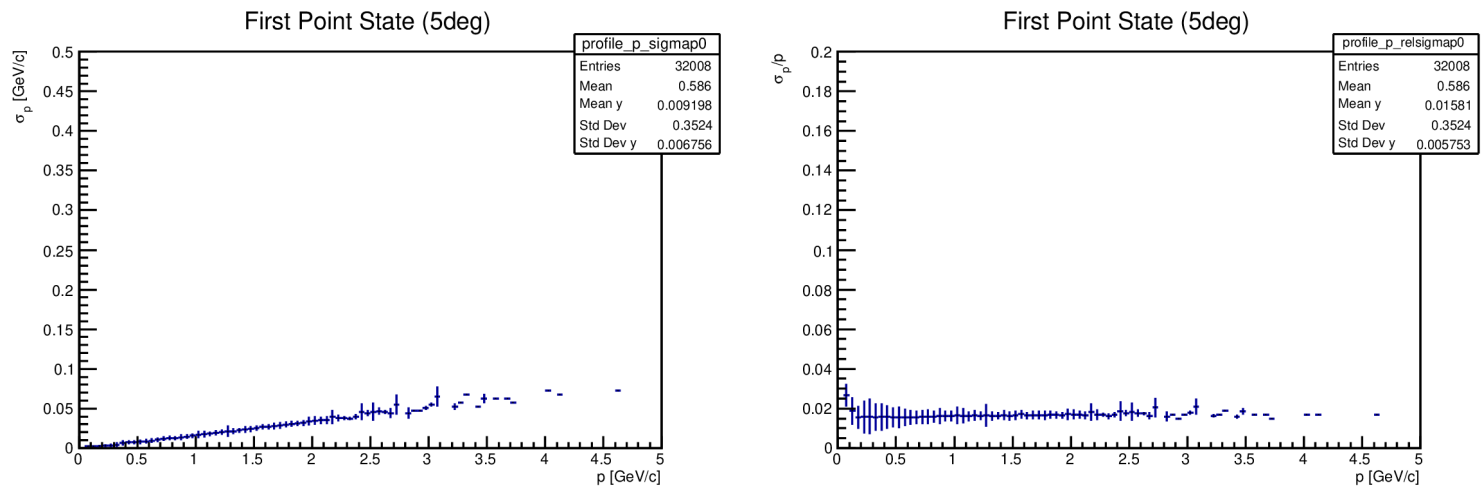
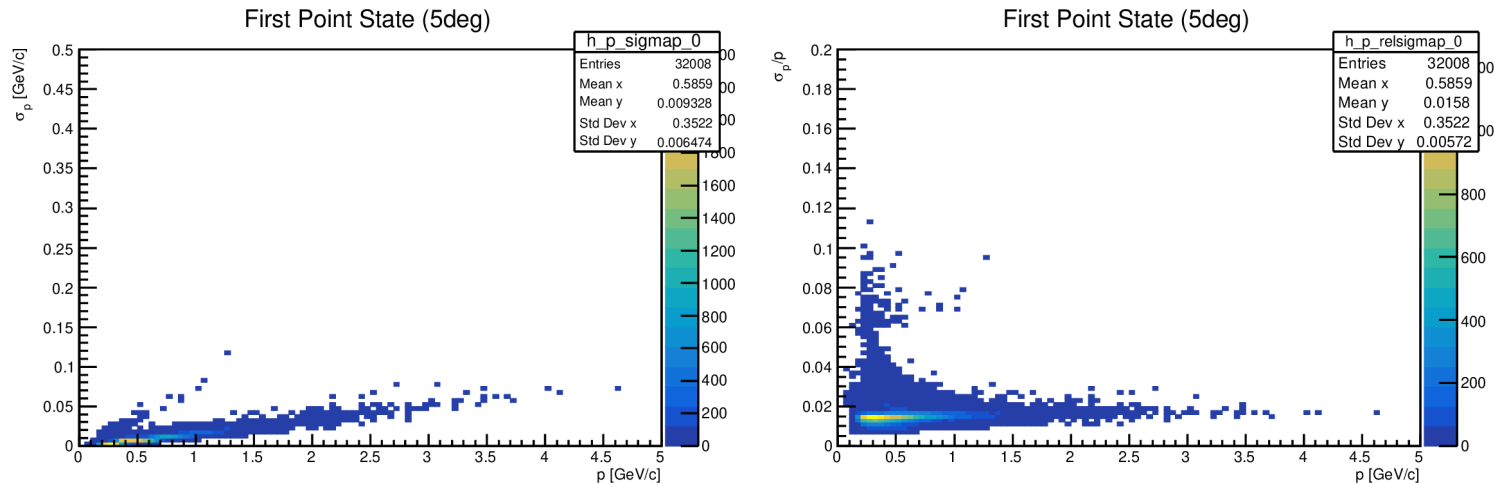
(picture with enlarged tubes and gaps between layers for better visibility)

Angle is varied from 0 to 20 degrees.

With ITS, all tracks

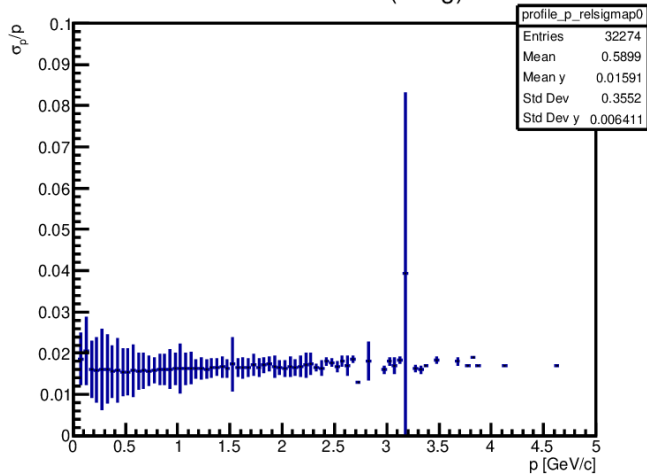


With ITS, only tracks in barrel

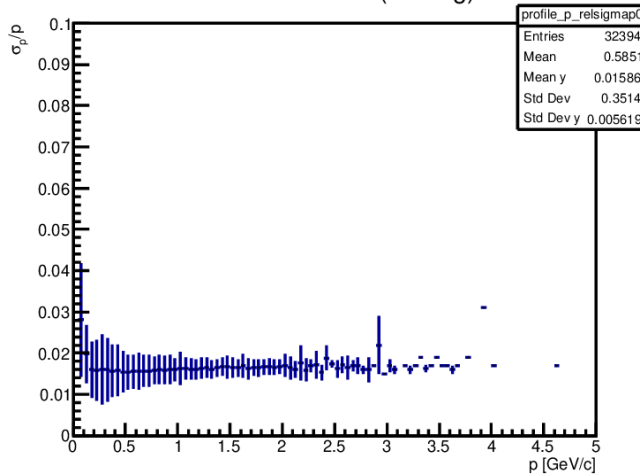


With ITS, only tracks in barrel

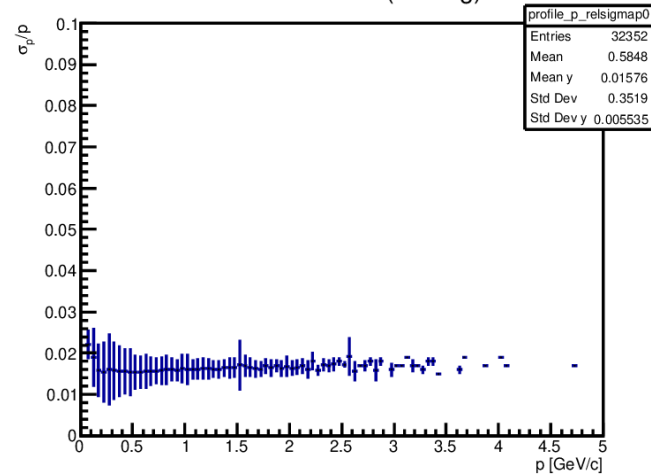
First Point State (0deg)



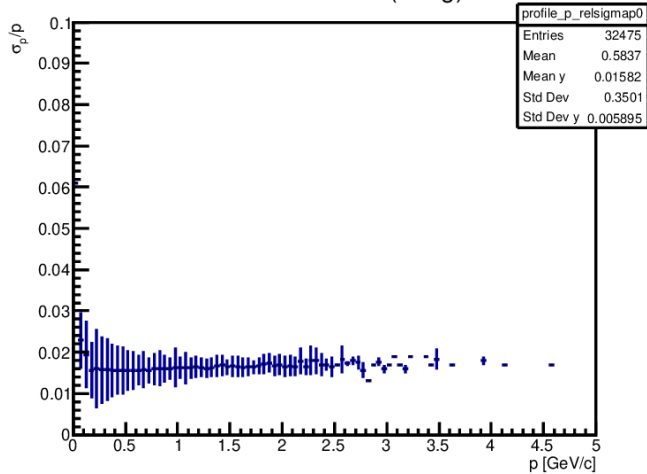
First Point State (0.1deg)



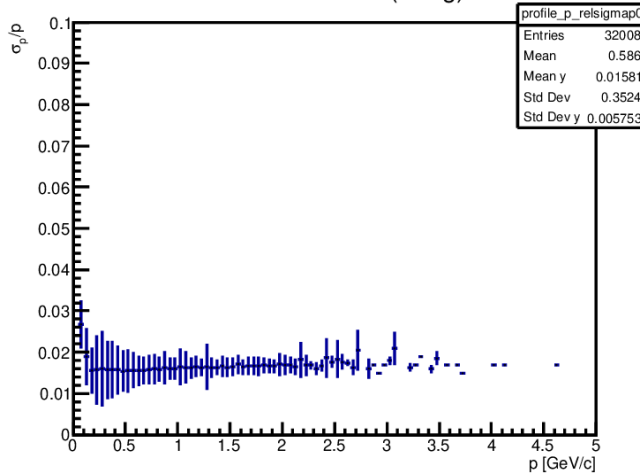
First Point State (0.5deg)



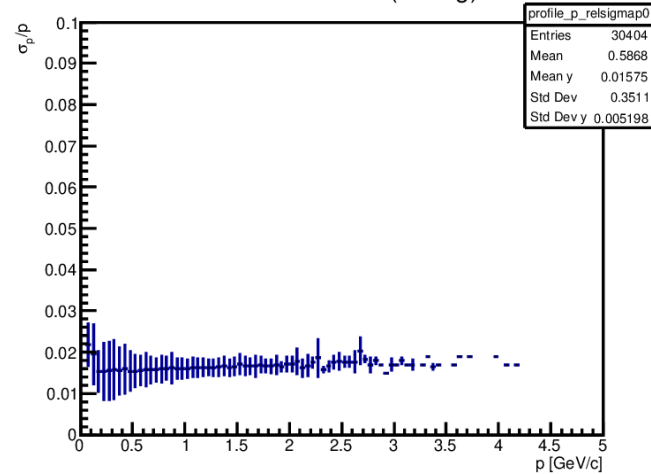
First Point State (1deg)



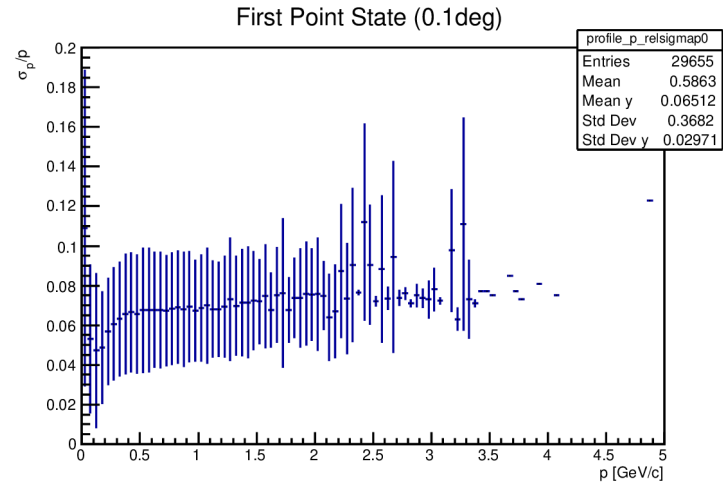
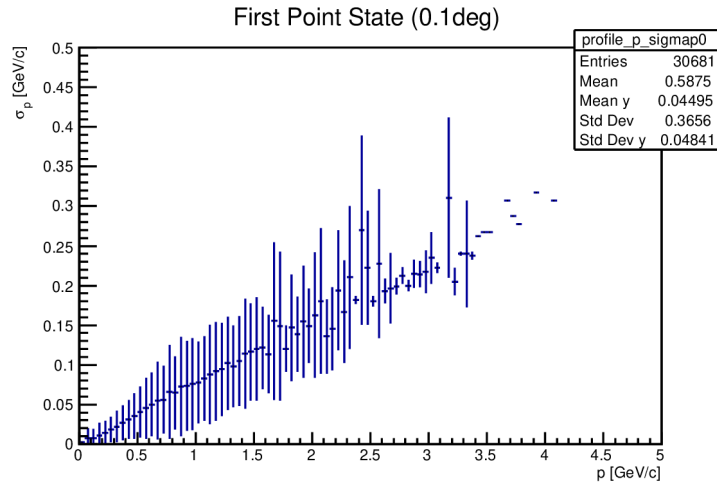
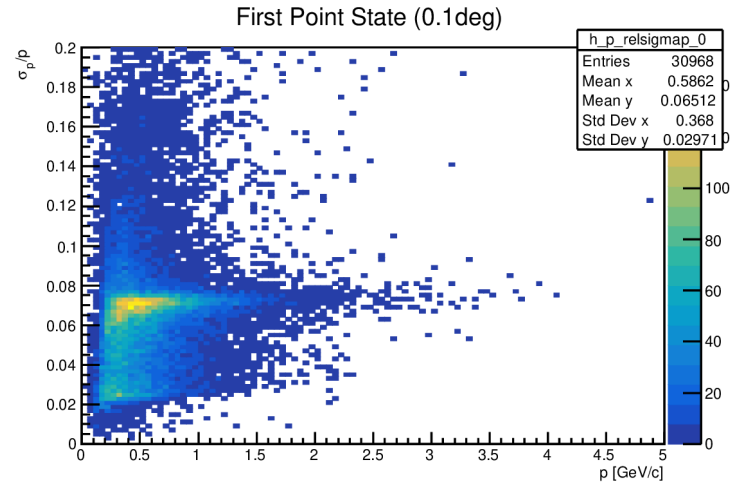
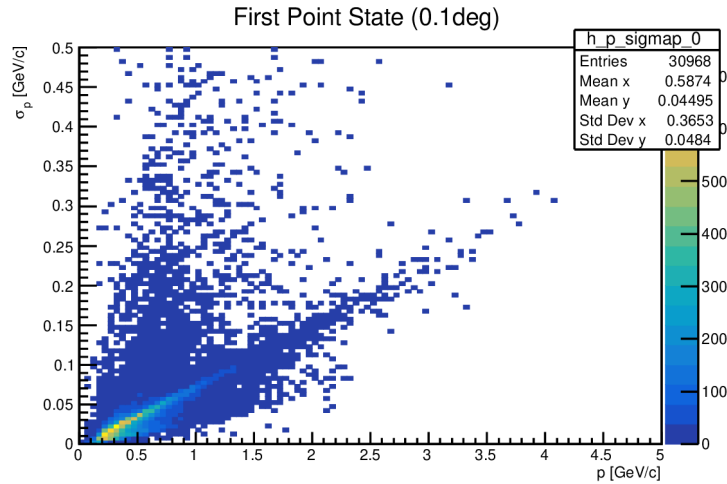
First Point State (5deg)



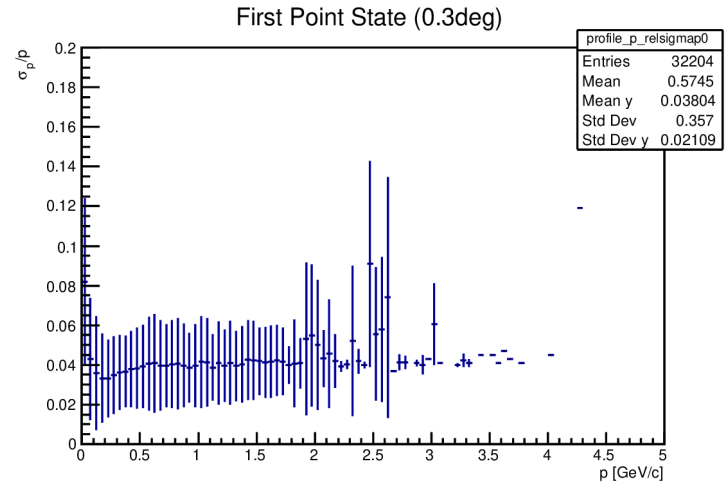
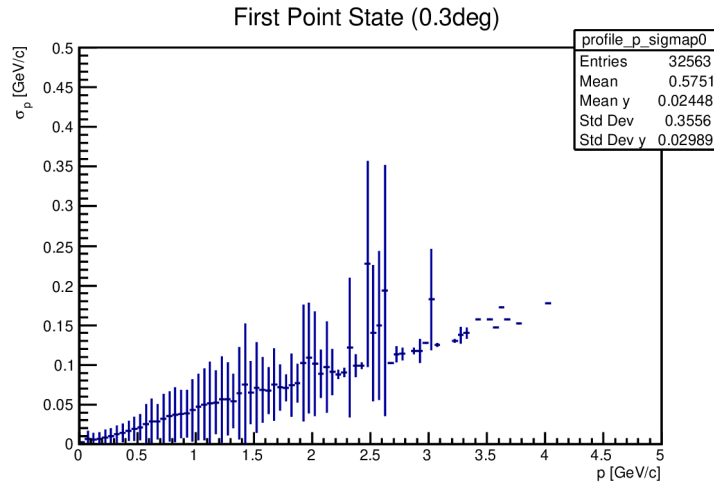
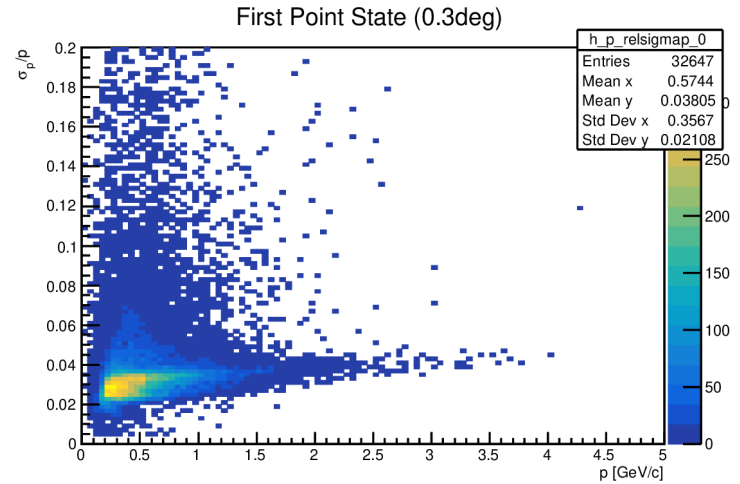
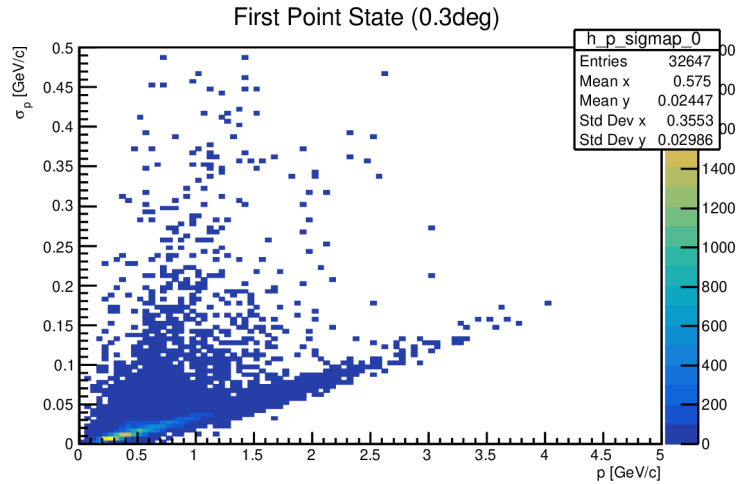
First Point State (20deg)



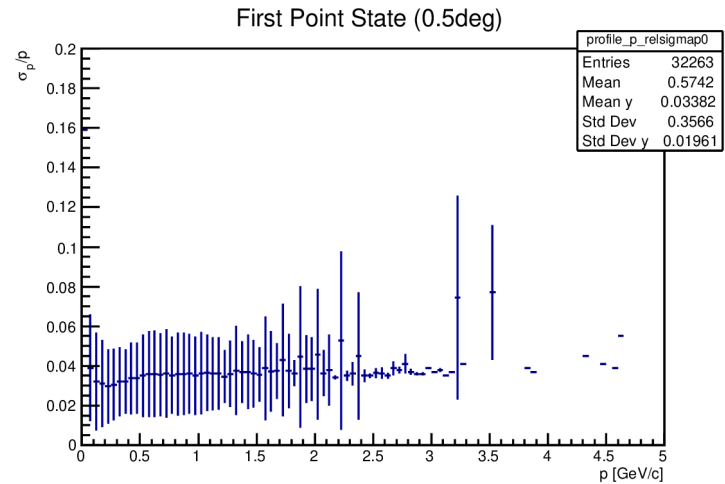
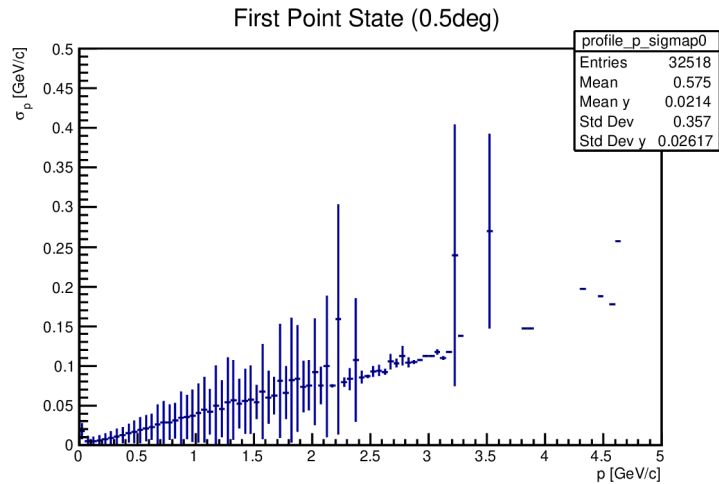
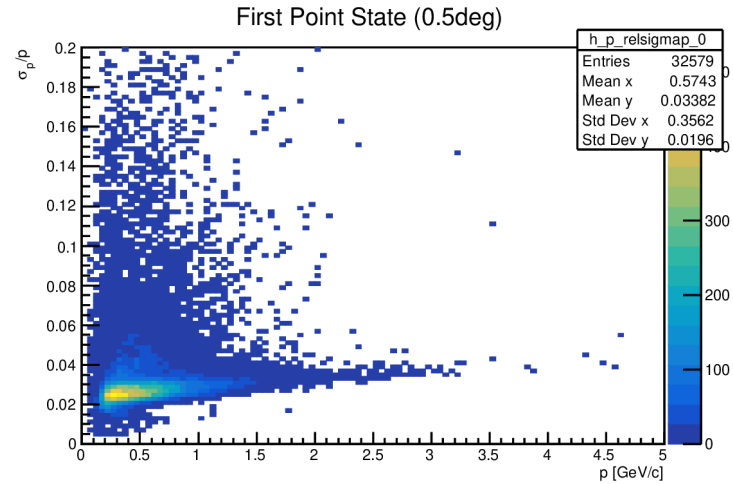
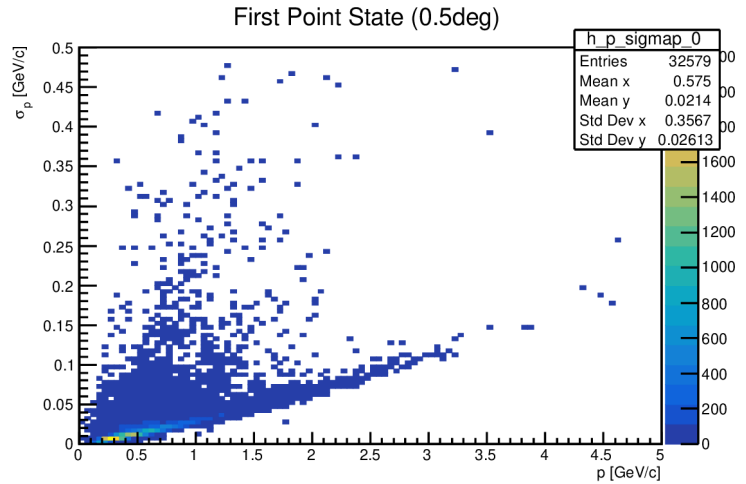
No ITS, only tracks in barrel



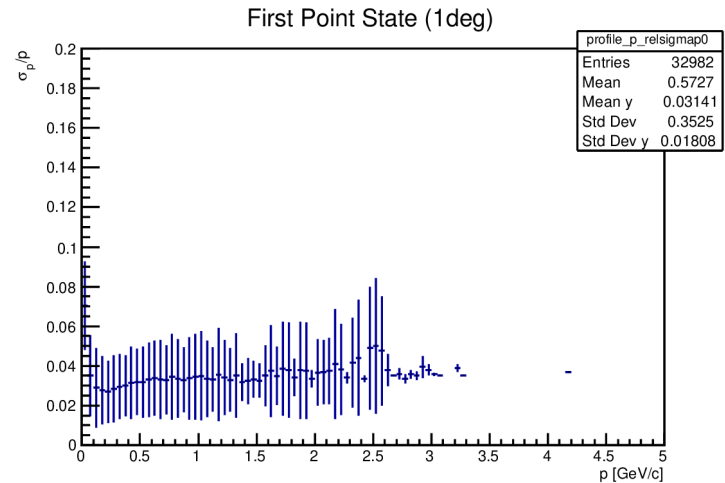
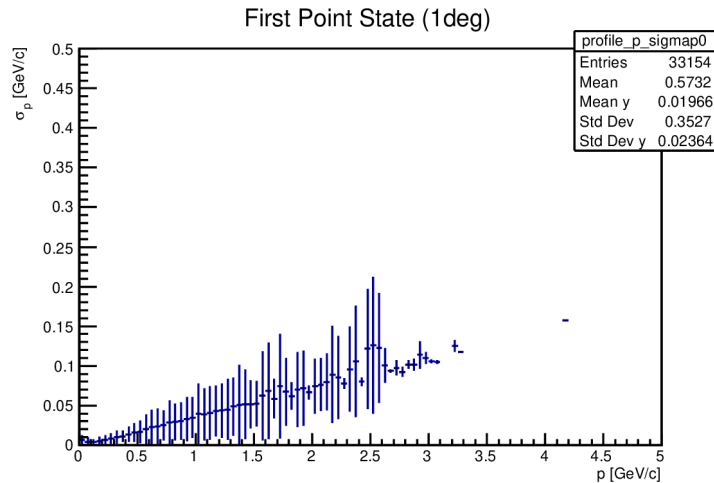
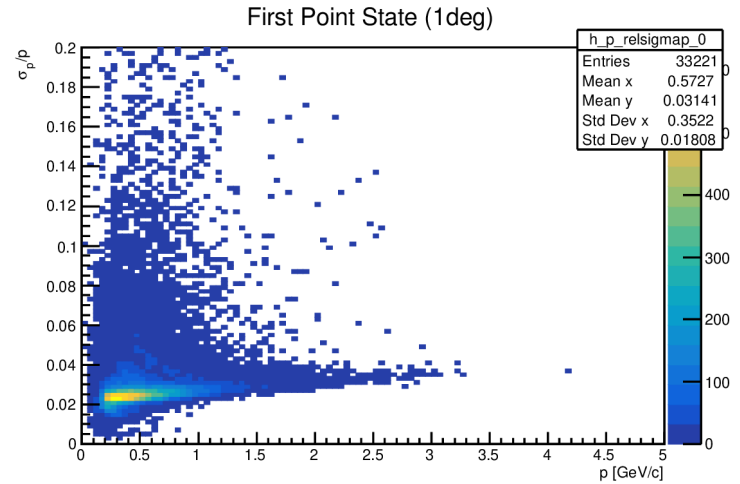
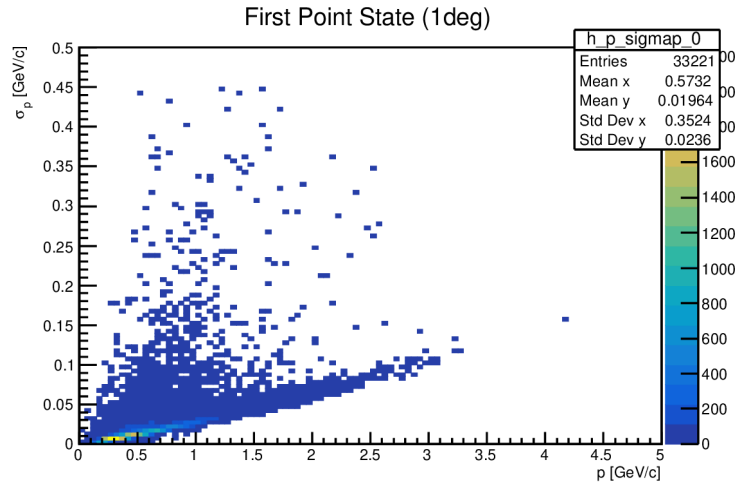
No ITS, only tracks in barrel



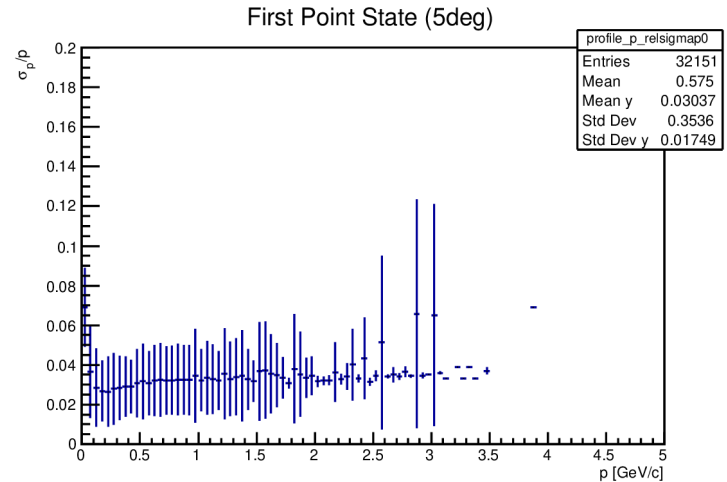
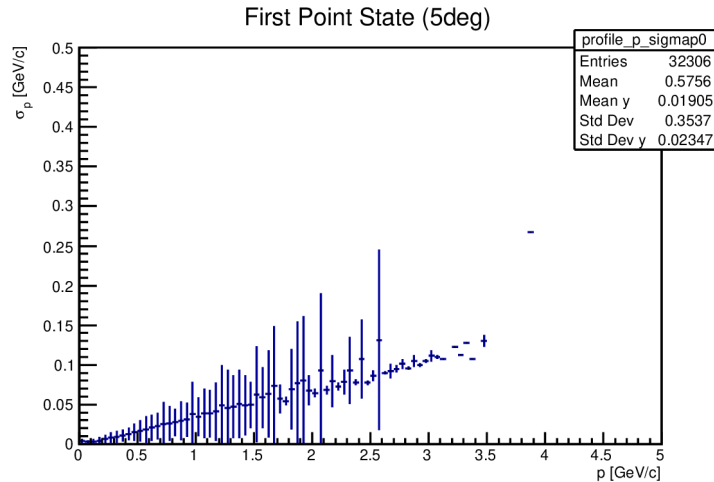
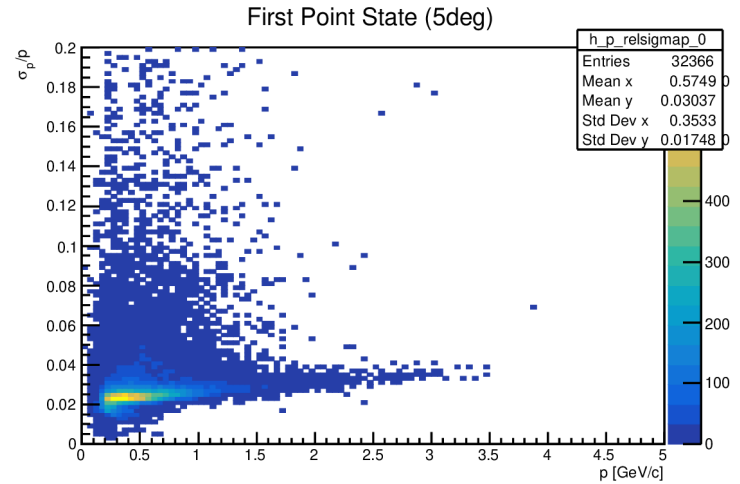
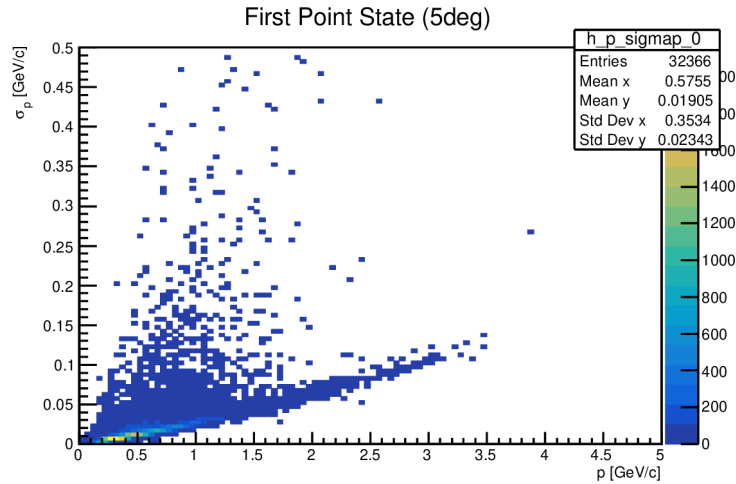
No ITS, only tracks in barrel



No ITS, only tracks in barrel

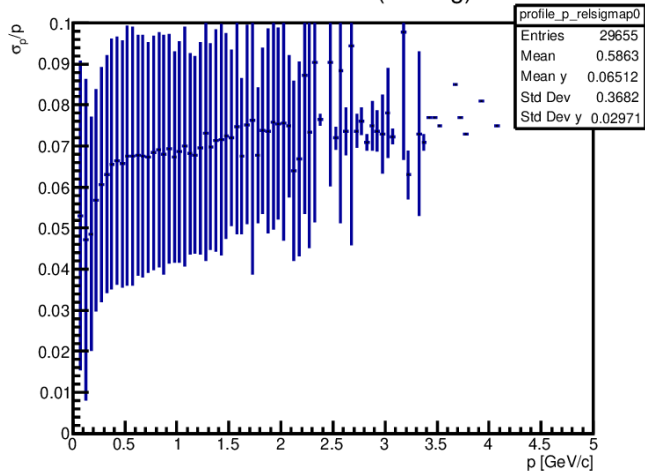


No ITS, only tracks in barrel

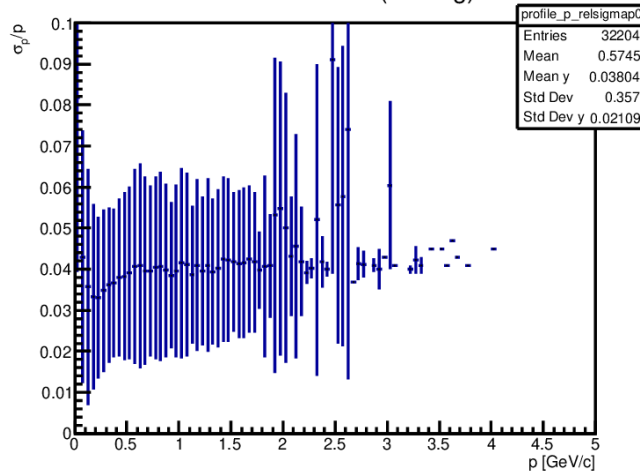


No ITS, only tracks in barrel

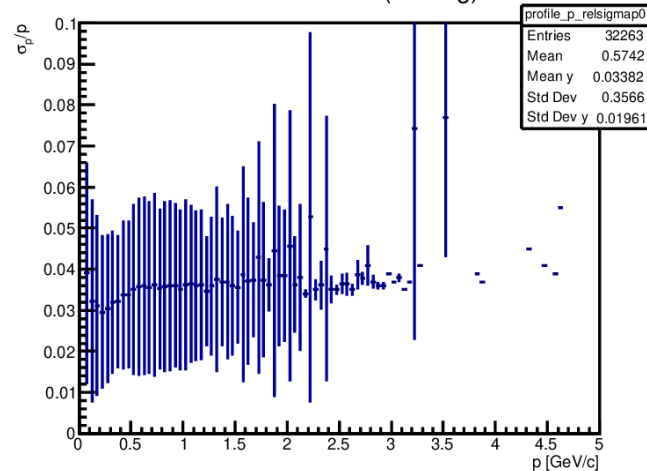
First Point State (0.1deg)



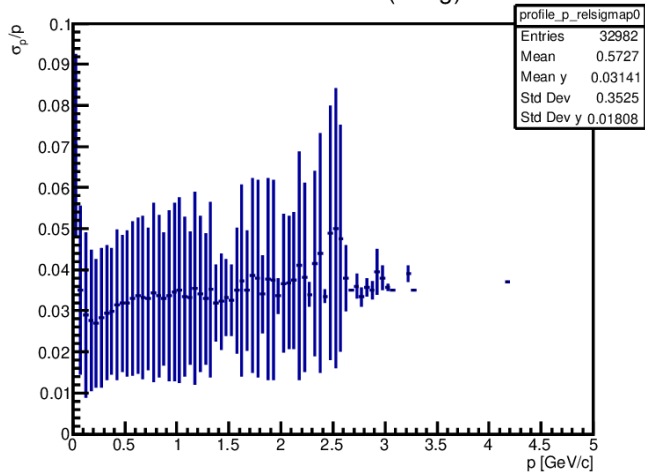
First Point State (0.3deg)



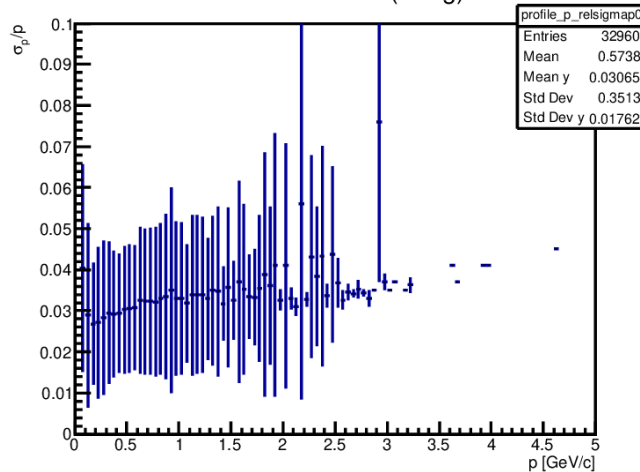
First Point State (0.5deg)



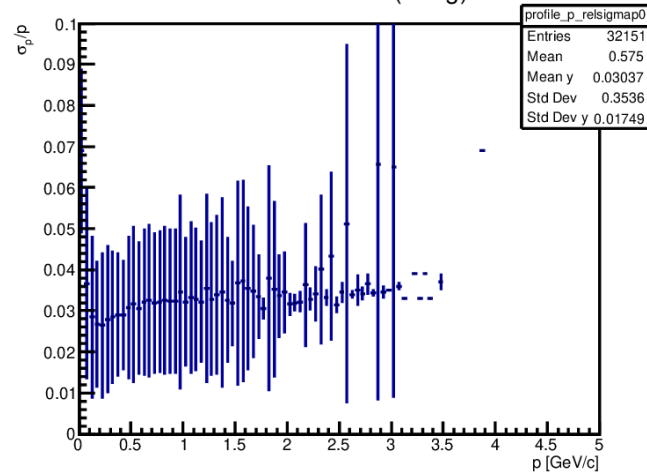
First Point State (1deg)



First Point State (2deg)



First Point State (5deg)

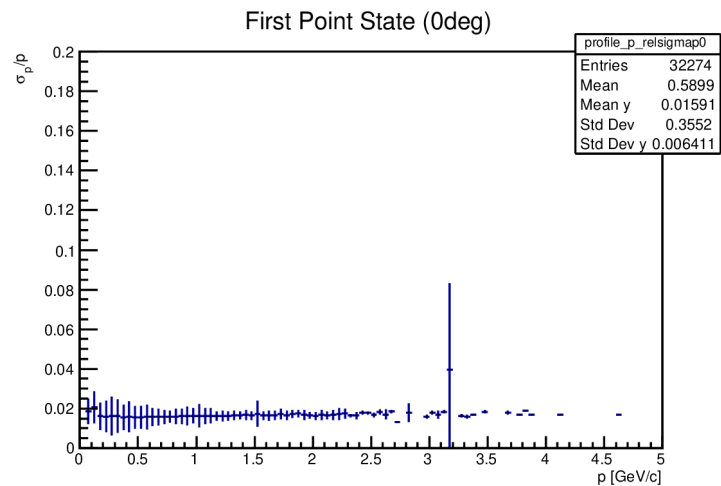
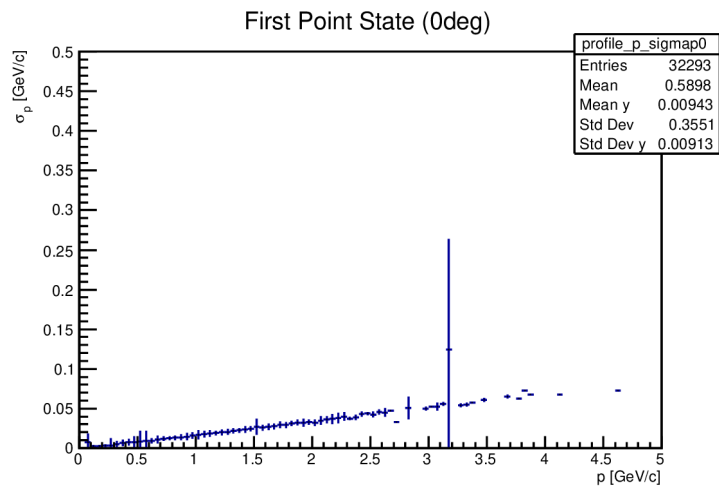
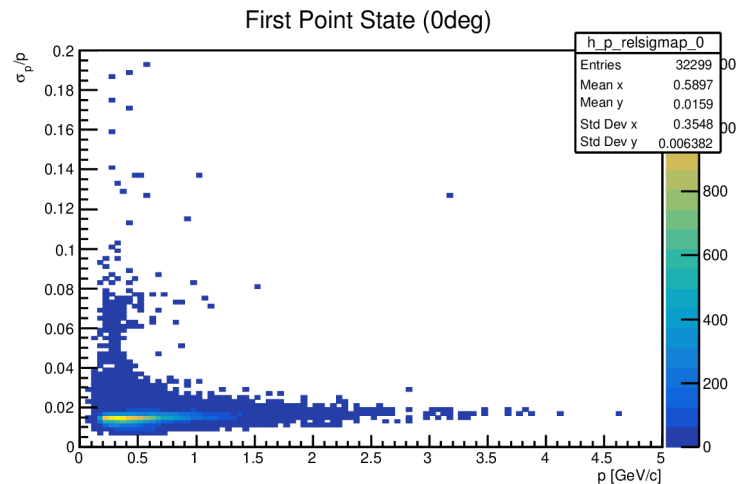
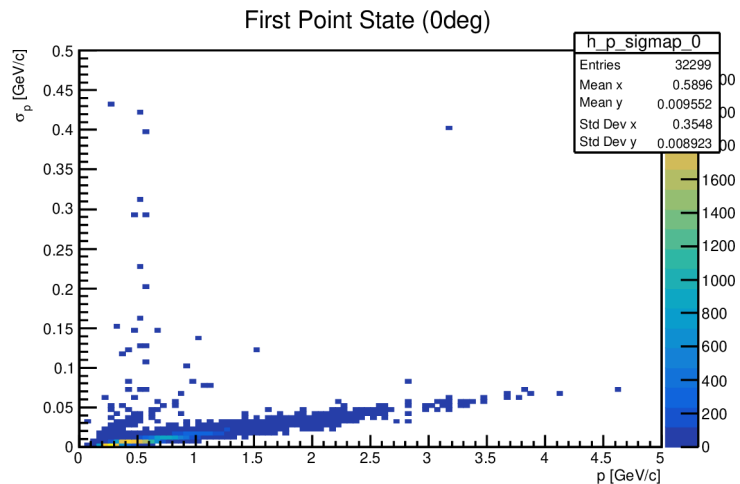


Conclusions

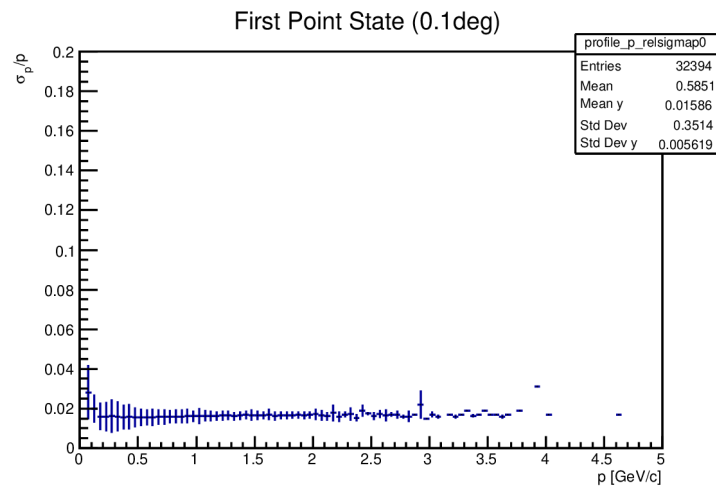
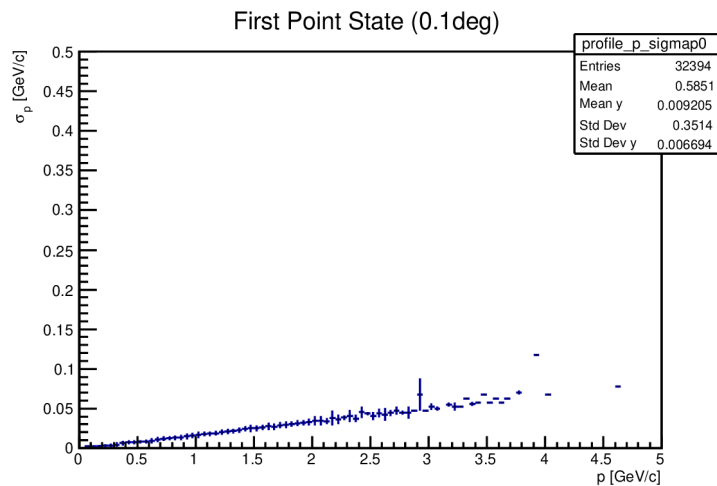
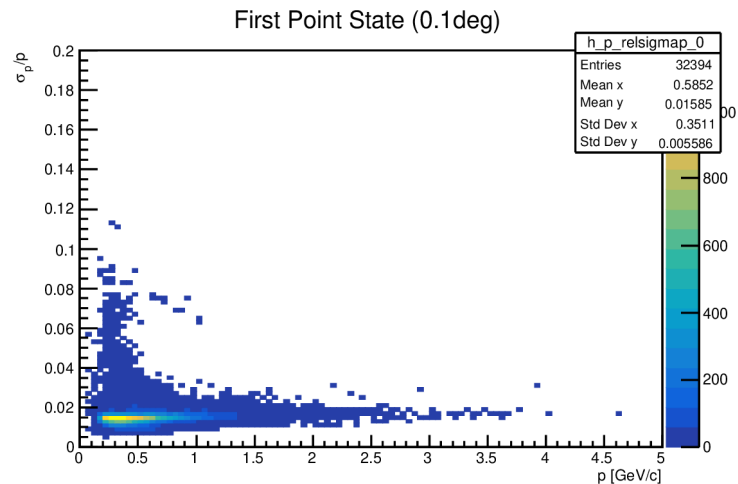
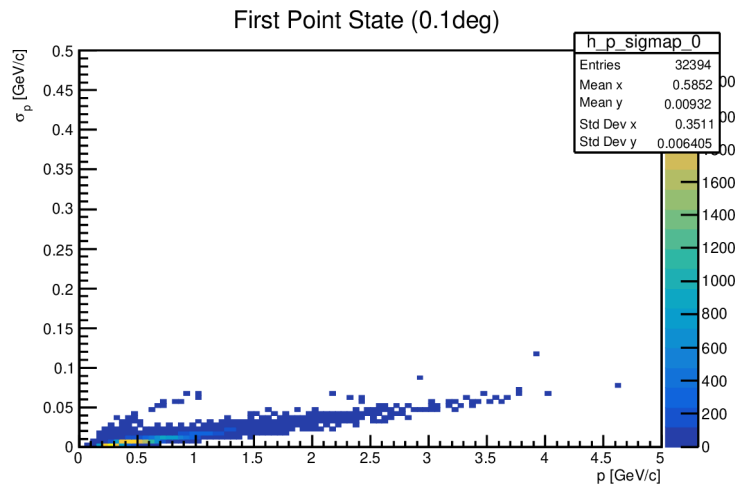
- Momentum resolution (for tracks passing through the barrel) is totally defined by vertex detector (?!) and does not depend on straw tube angle.
- Even without vertex detector, σ_p/p does not change starting from angle $\approx 1^\circ$.

backup

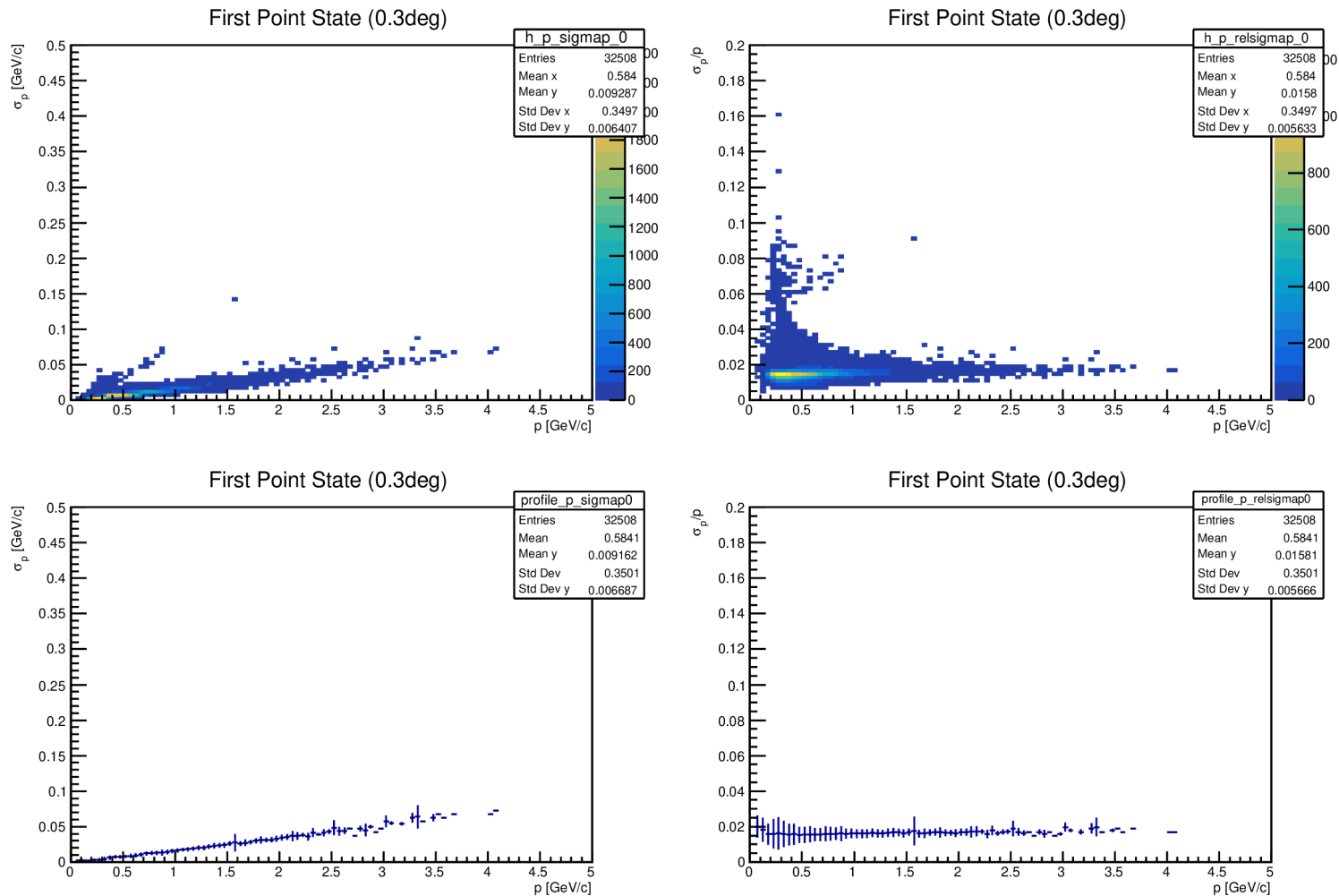
With ITS, only tracks in barrel



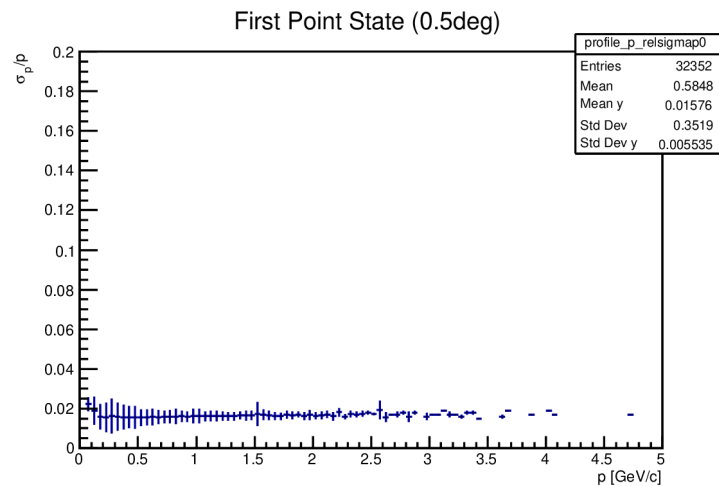
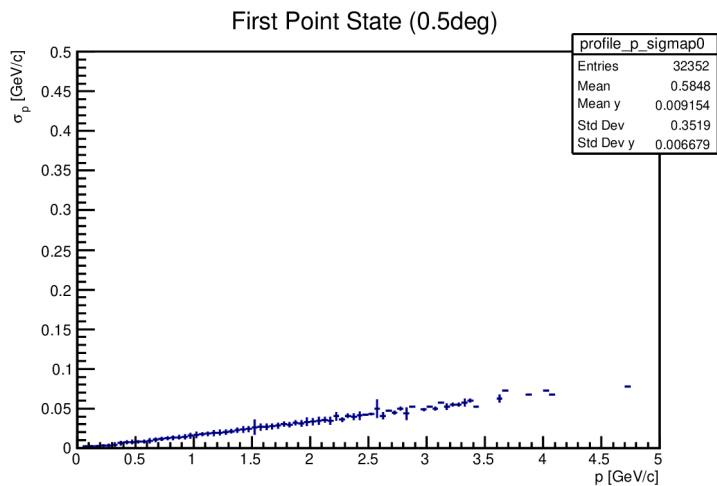
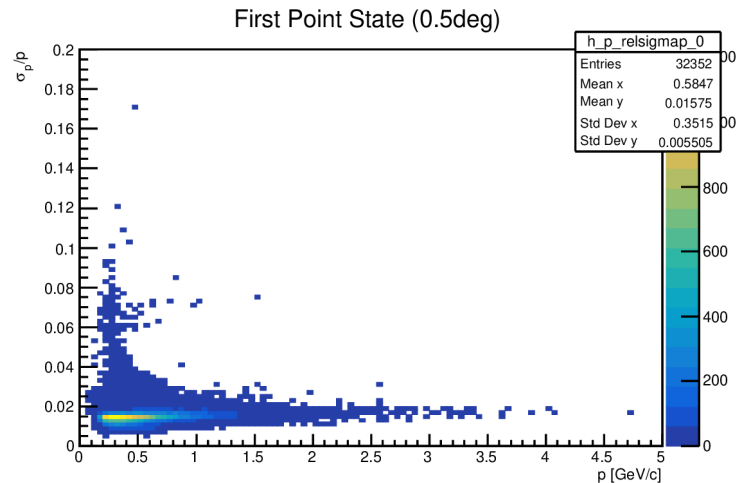
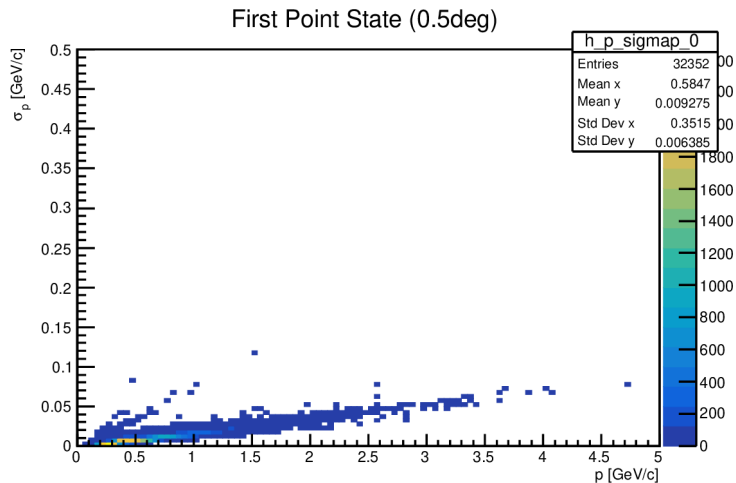
With ITS, only tracks in barrel



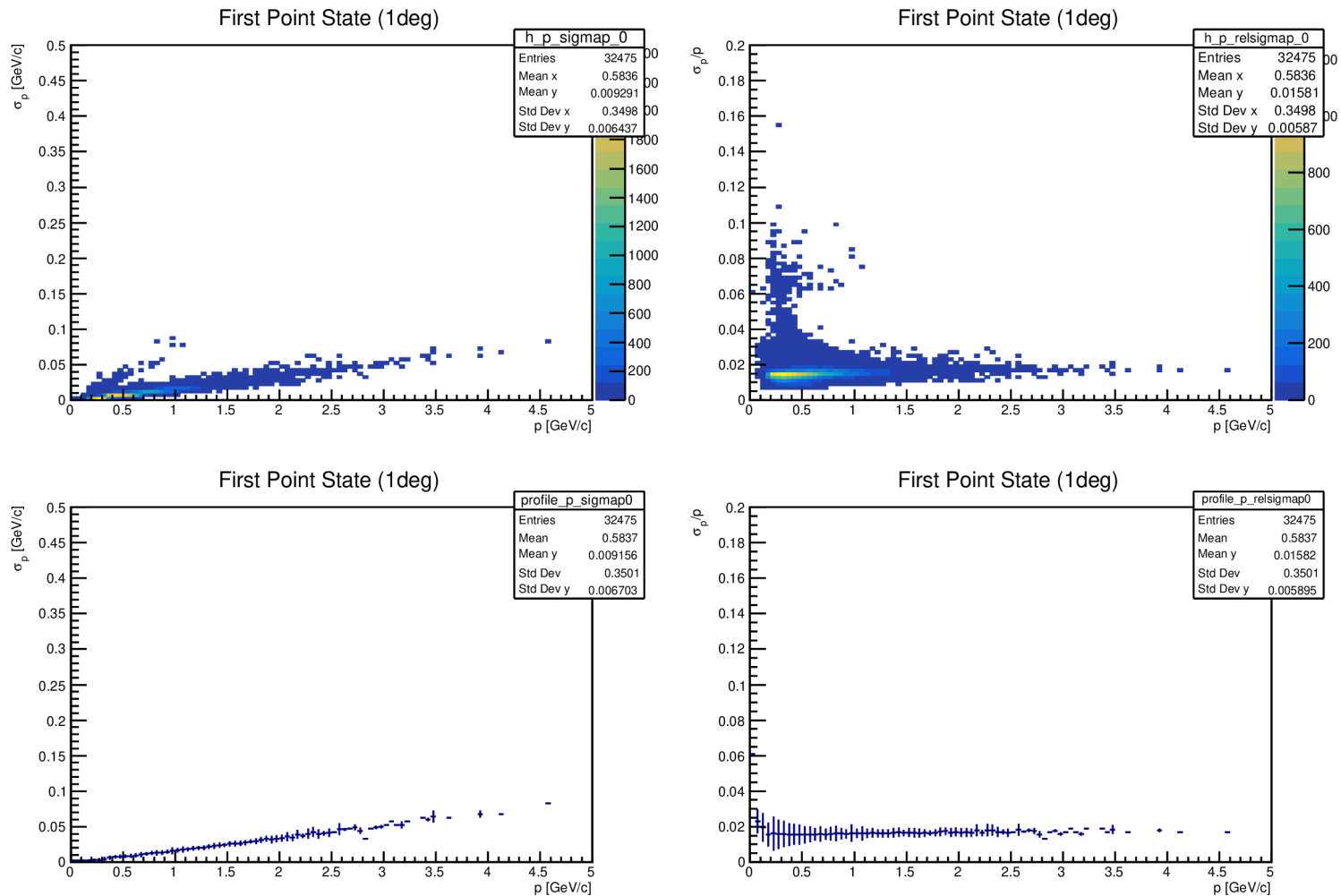
With ITS, only tracks in barrel



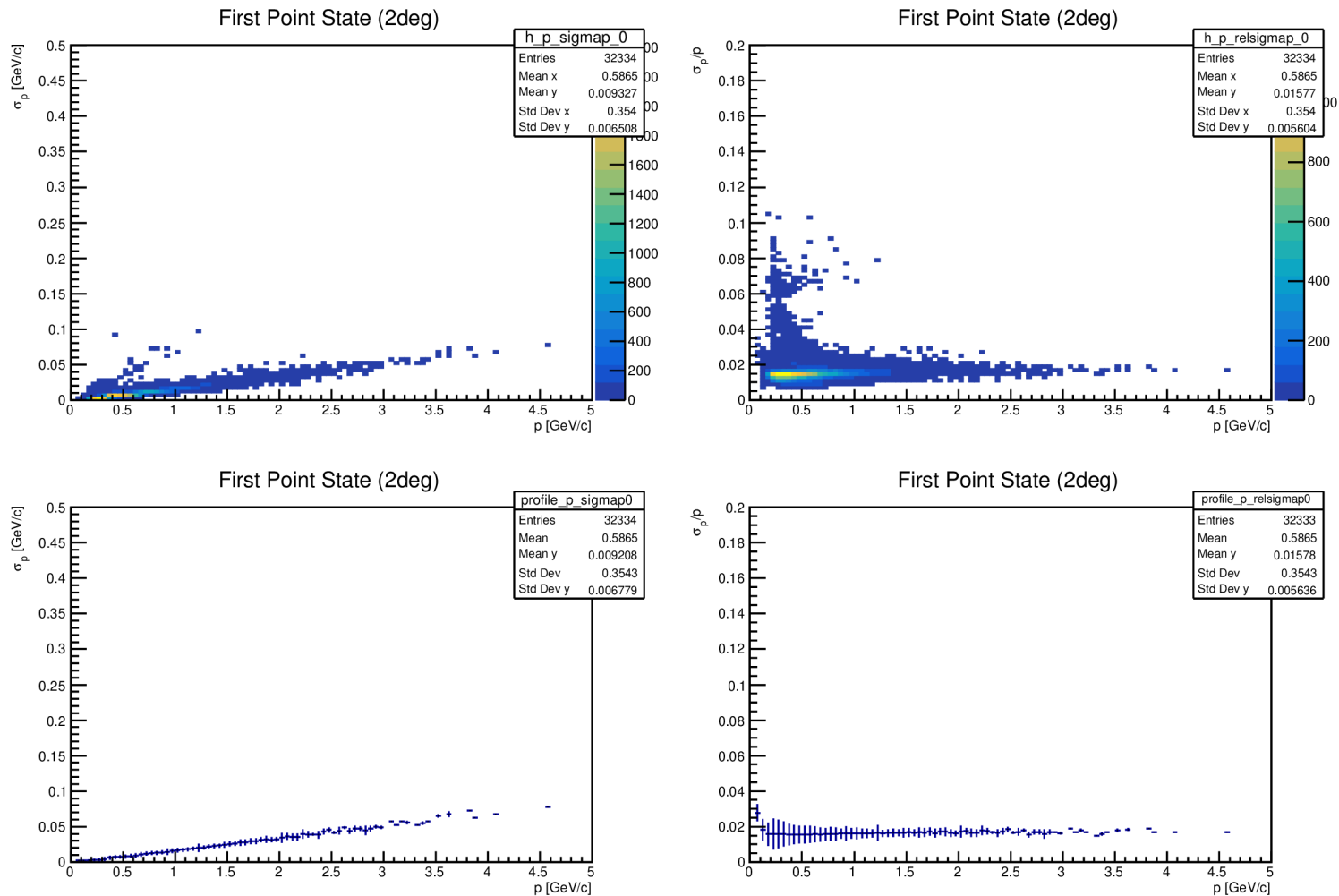
With ITS, only tracks in barrel



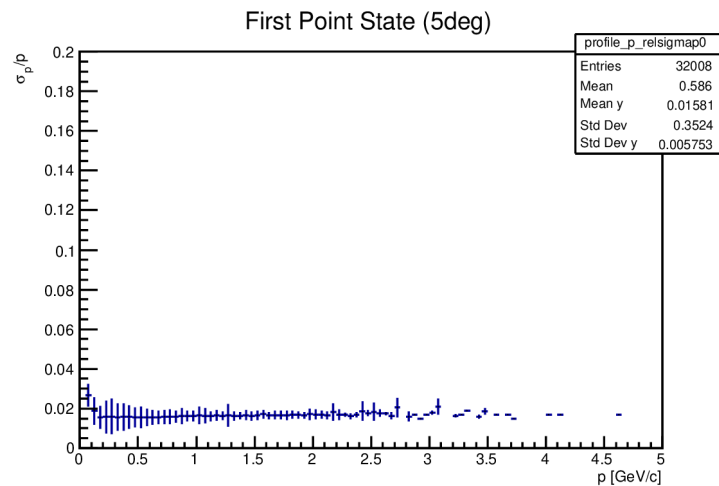
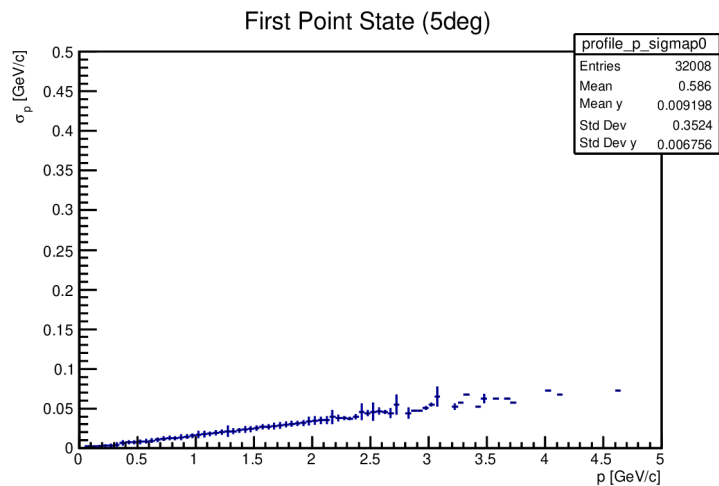
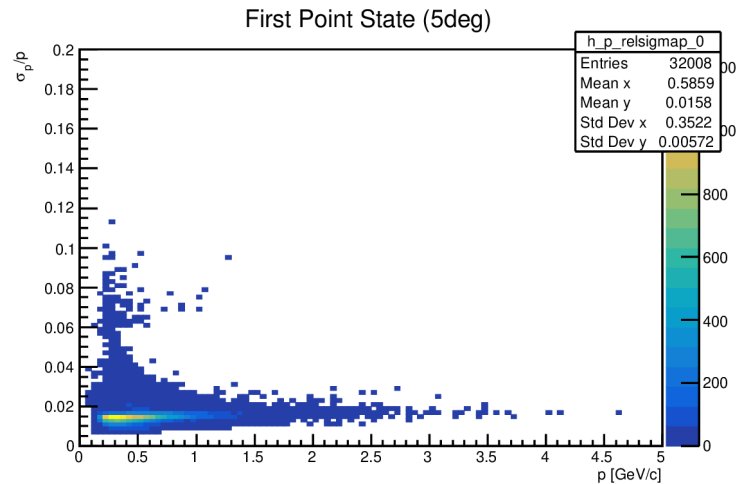
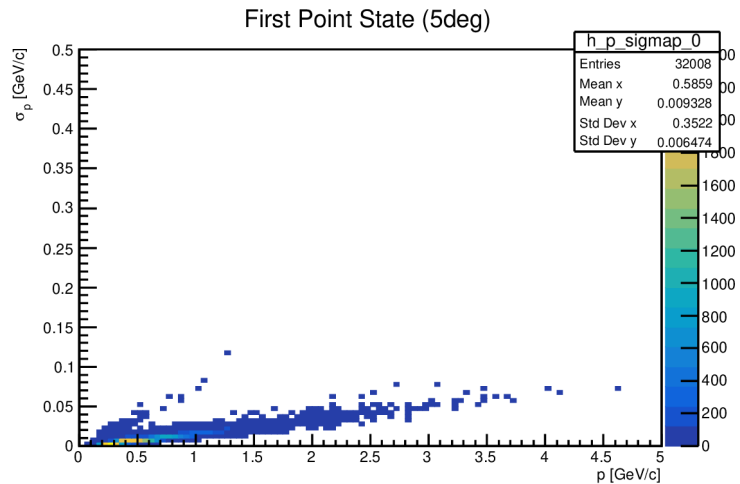
With ITS, only tracks in barrel



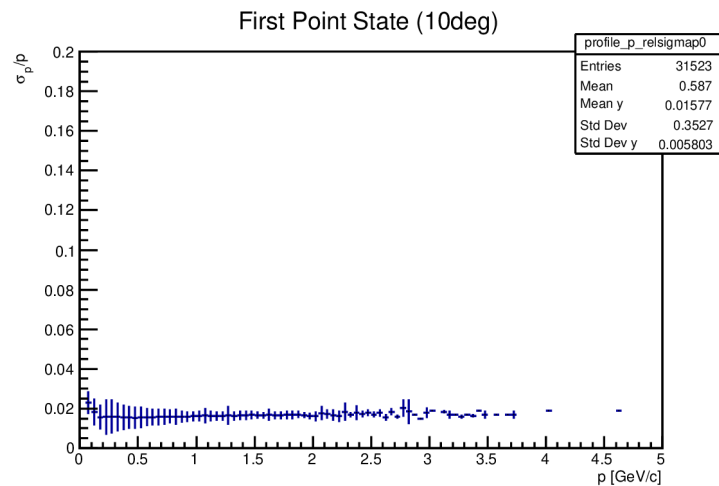
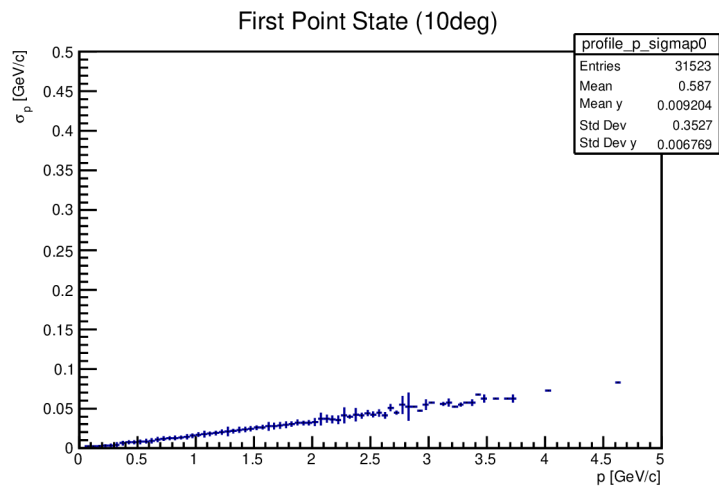
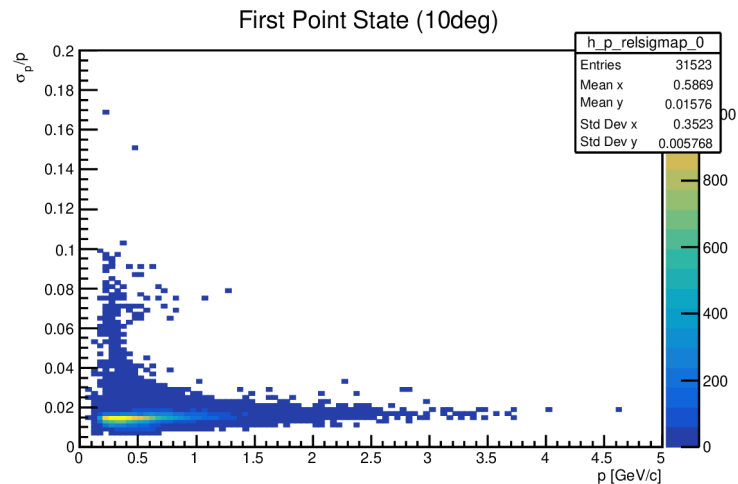
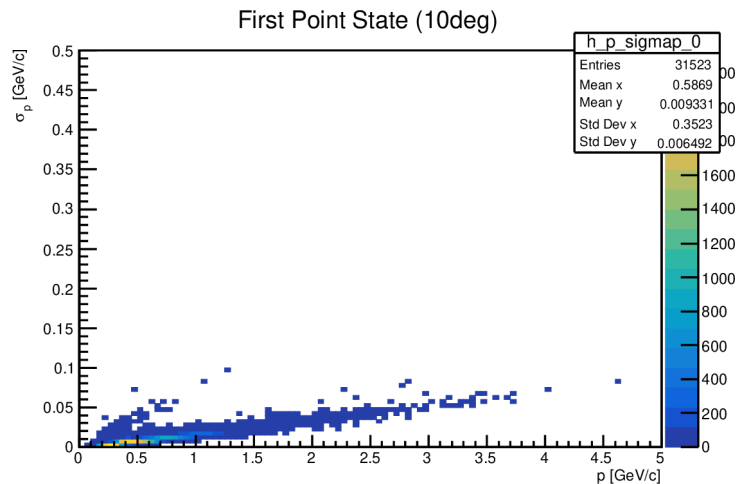
With ITS, only tracks in barrel



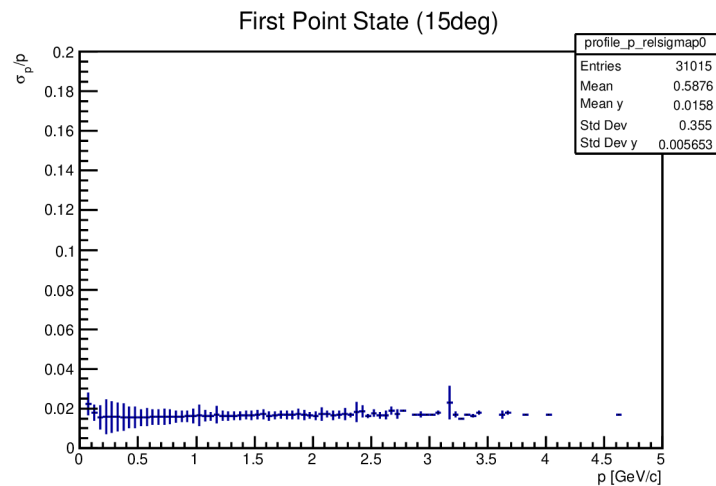
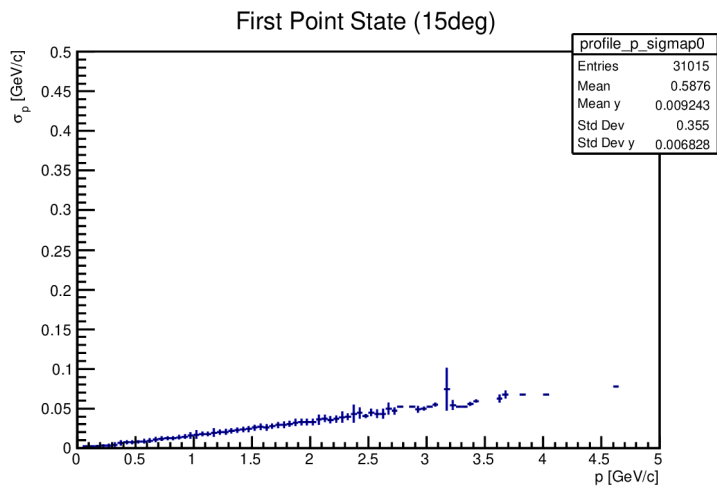
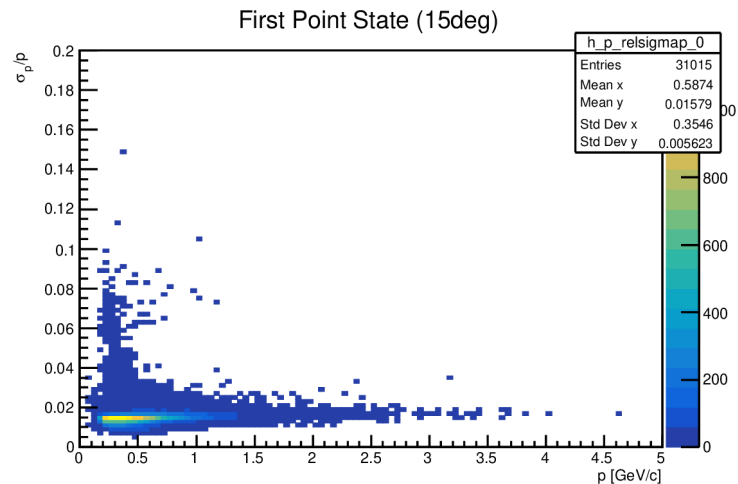
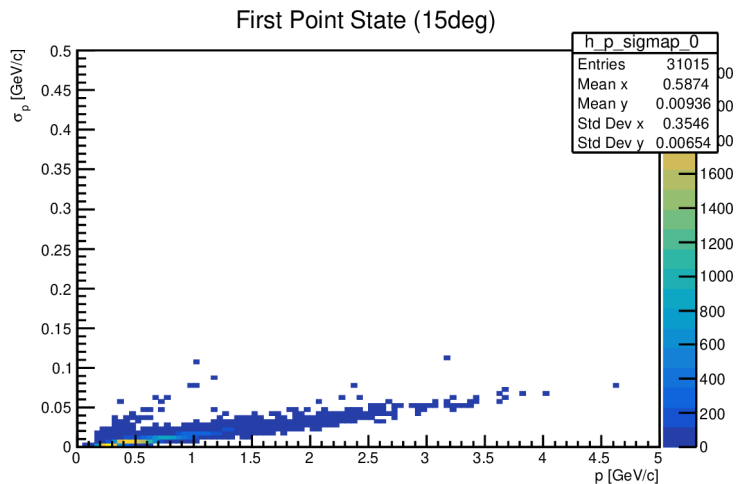
With ITS, only tracks in barrel



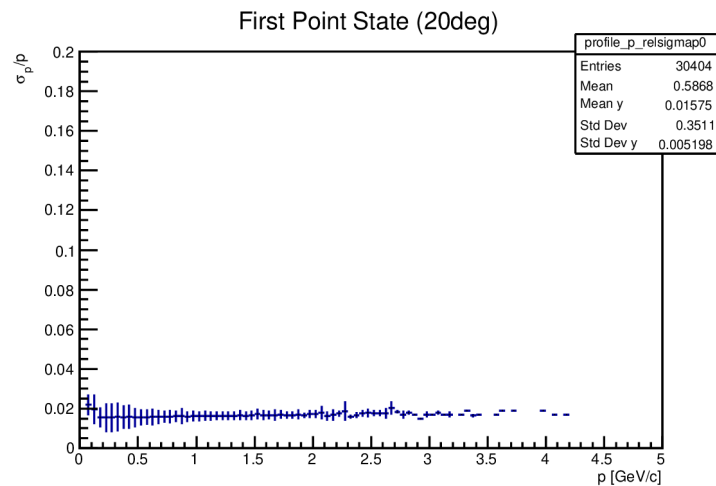
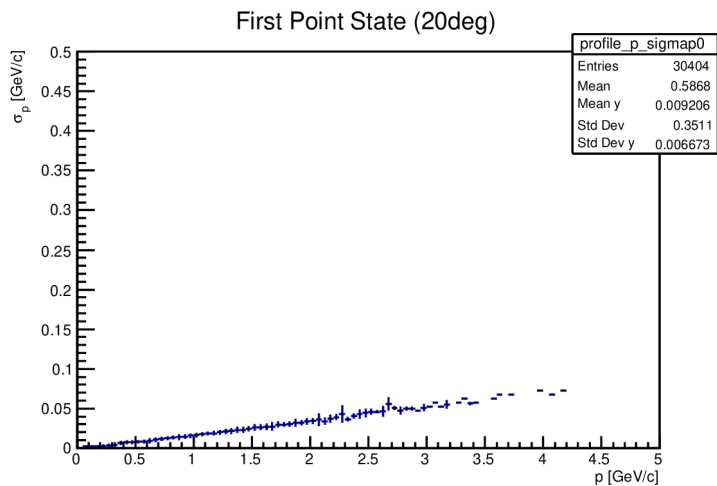
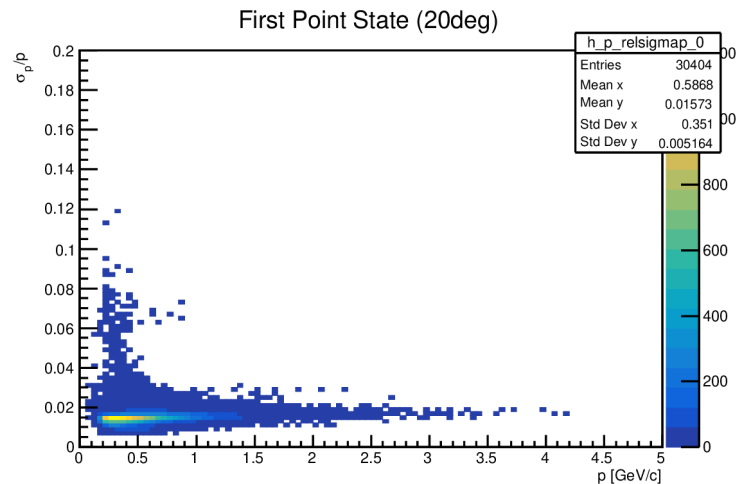
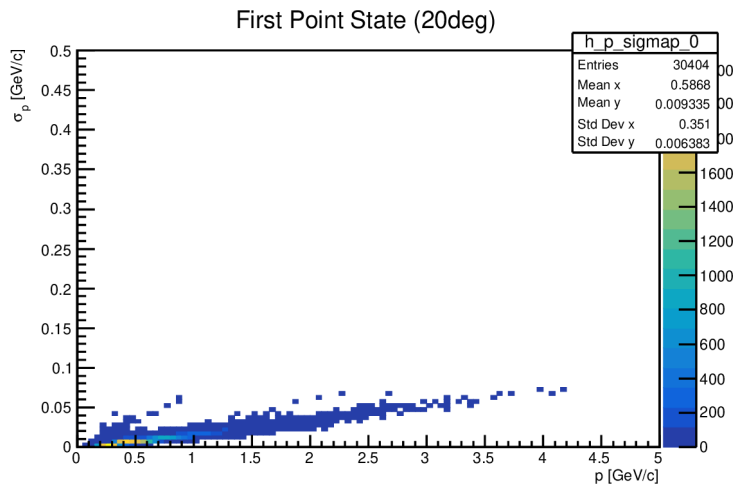
With ITS, only tracks in barrel



With ITS, only tracks in barrel



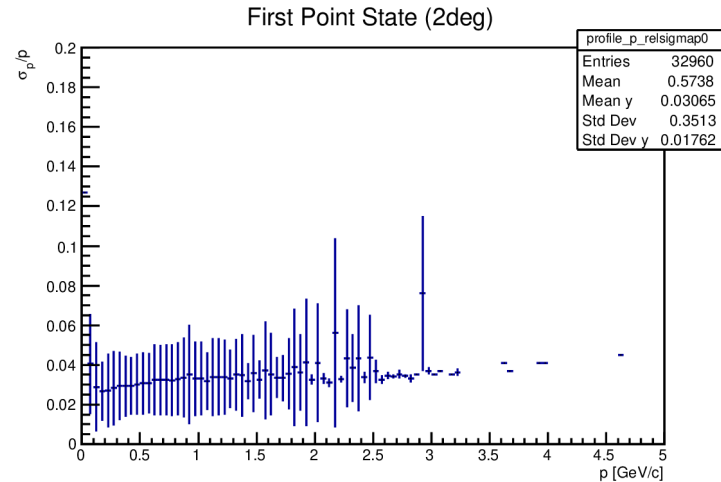
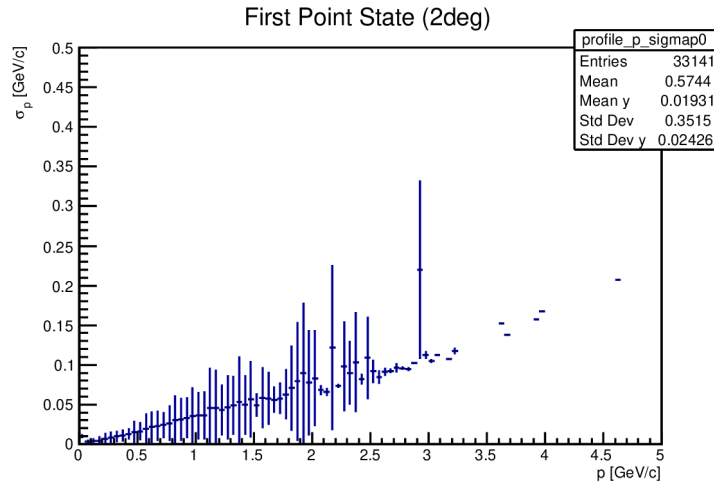
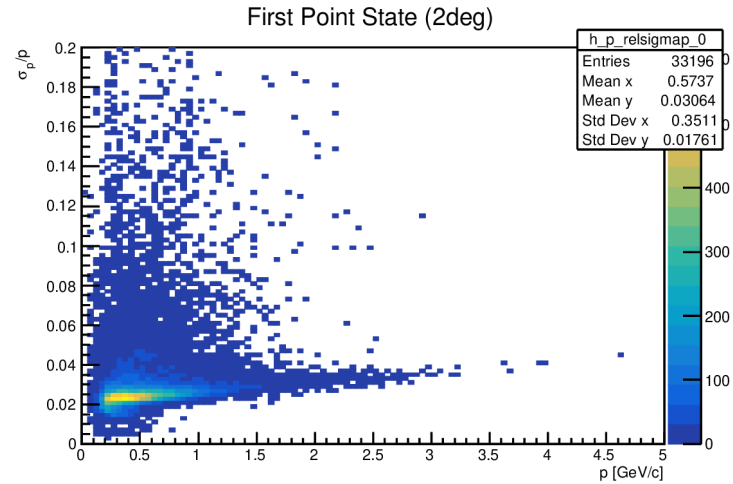
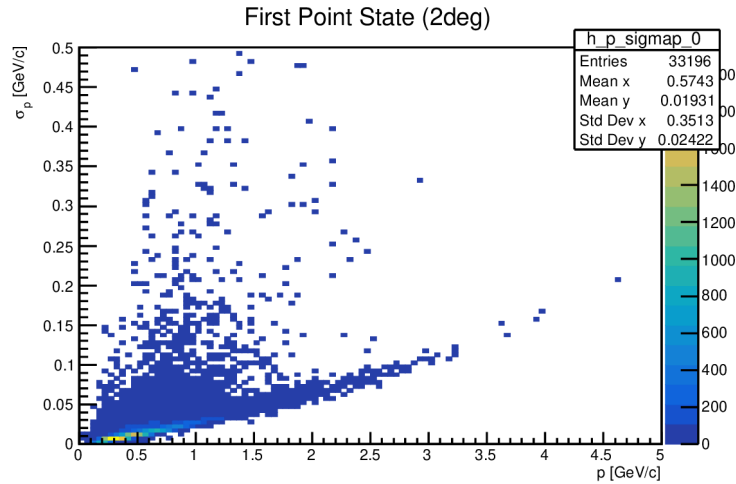
With ITS, only tracks in barrel



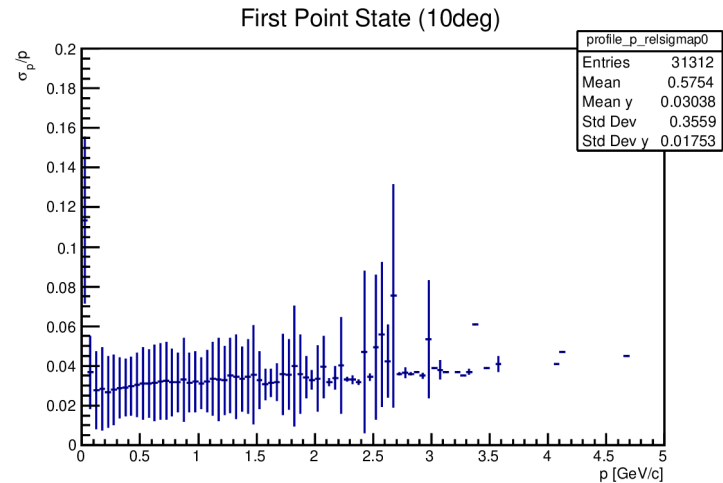
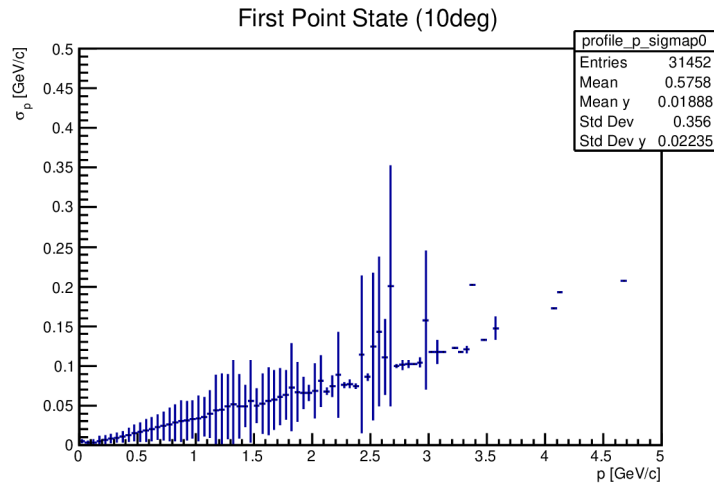
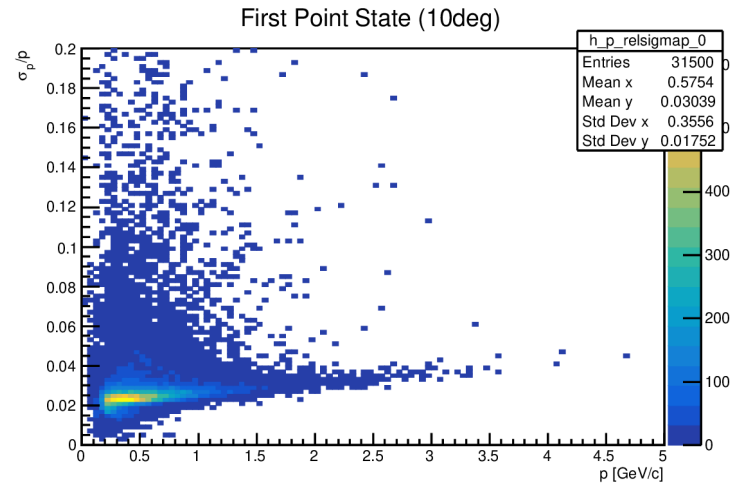
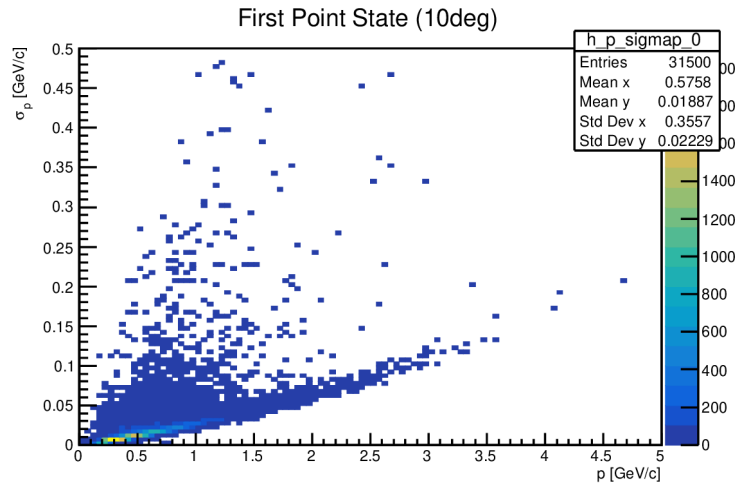
No ITS, only tracks in barrel

0deg — job crashes!

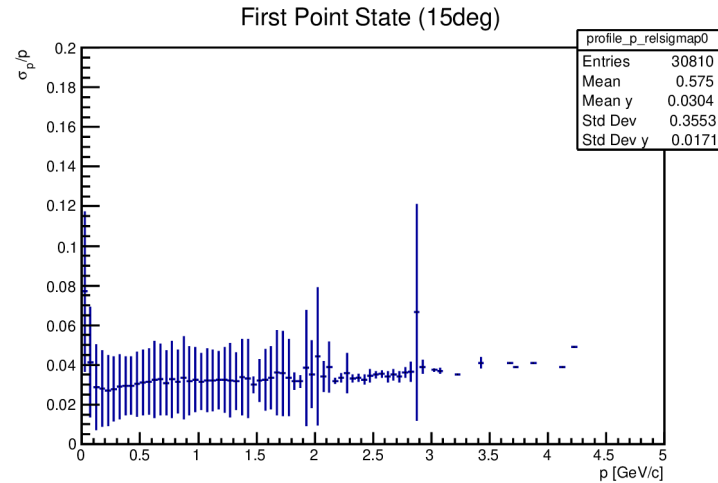
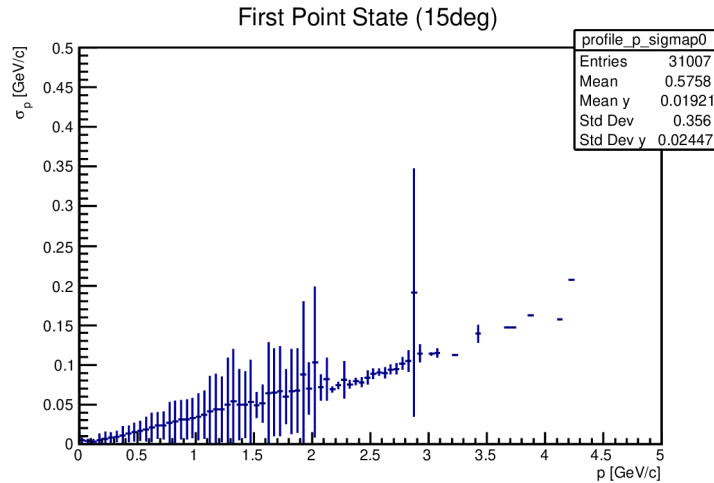
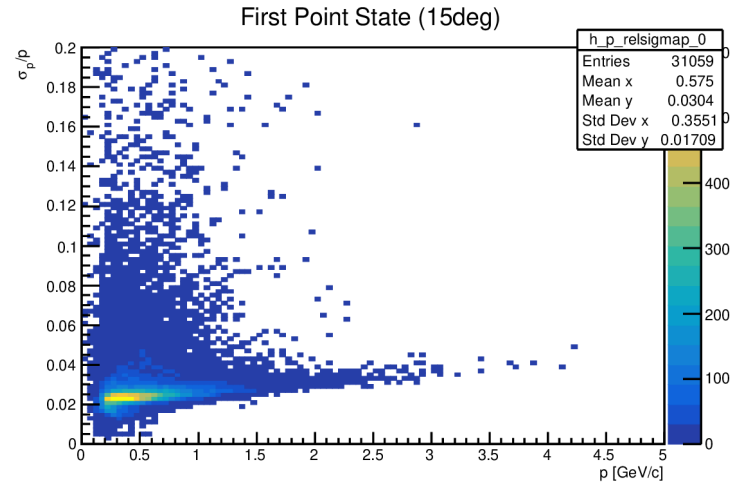
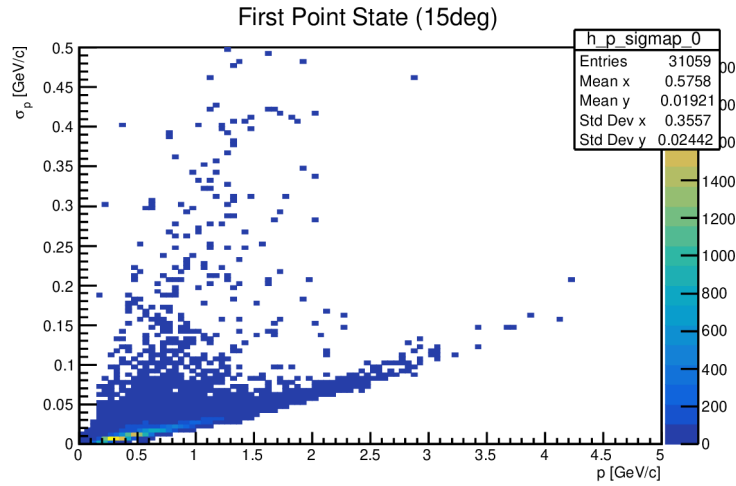
No ITS, only tracks in barrel



No ITS, only tracks in barrel



No ITS, only tracks in barrel



No ITS, only tracks in barrel

