Momentum resolution dependence on the polar angle

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Straw tracker geometry



SpdTsTBGeoMapper* mapper = SpdTsTBGeoMapper::Instance();

mapper->SetStrawModulePars(1,

mapper->SetStrawLayerPars(1,
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0., 'e', 1.0, 0);

-deg, 'e', 1.0, 0.); -deg, 'o', 1.0, 0.);

(picture with enlarged tubes and gaps between layers for better visibility)

Angle (α) is varied from 0.1 to 20 degrees.

No vertex detector.

Generation of events

- SpdIsotropicGenerator
- Pions with p = 1 GeV/c.
- Polar angle θ is varied within range ±0.5° from the central value.
- Azimuthal angle ϕ is varied from 0° to 360°.
- 100 events with 100 tracks in each event.
- Scan over values:
 - θ : from 40° to 90° with step 5°.
 - α: 0.1°, 0.2°, 0.3°, 0.5°, 1°, 2°, 5°, 10°, 20°.

Cuts on tracks used in the analysis

- Only tracks from primary vertex.
- Fit parameters exist.
- GetIsAcceptable() (no fit error flags, ndf \ge 3, χ^2 /ndf \ge 2)
- No hits in endcaps.

Angular distributions



Hits distribution



Relative momentum resolutions



Hits distribution



Dependence on the polar angle



Conclusions

- As obtained earlier, the momentum resolution almost does not change starting from the straw angle value = 1°.
- Full momentum resolution increases (or is almost constant) with θ .
- Transverse momentum resolution varies even smaller with the straw angle. It achieves minimum at $\theta = 65^{\circ}$.