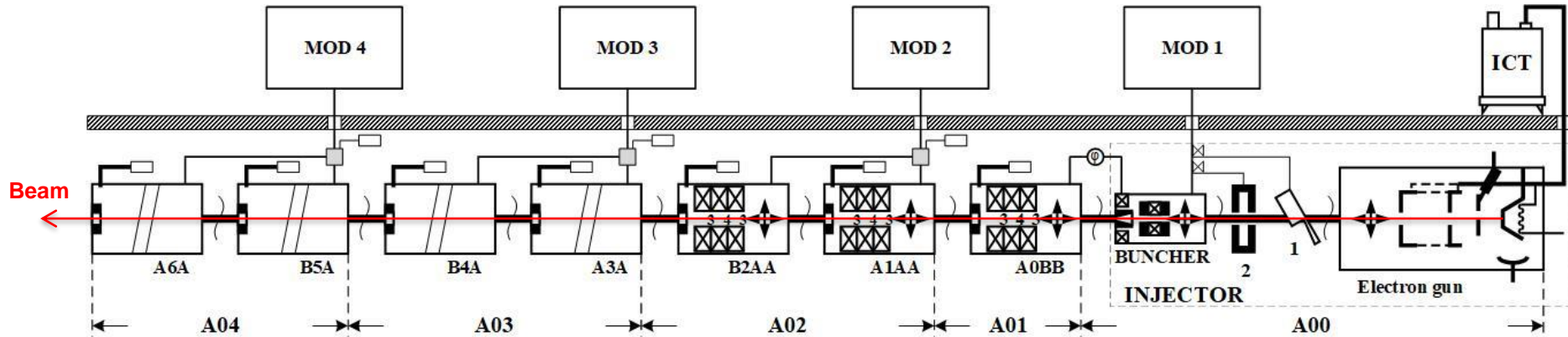# LINAC-200 Control System Status

A.N. Trifonov, M.I. Gostkin, V.V. Kobets, M.A. Nozdrin, A.S. Zhemchugov, P.P. Zhuravlyov

Joint Institute for Nuclear Research, Dubna, Russia
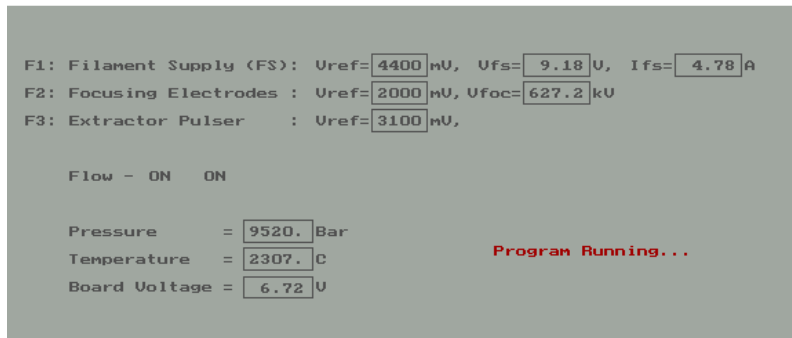
LINAC-200 Electron Accelerator

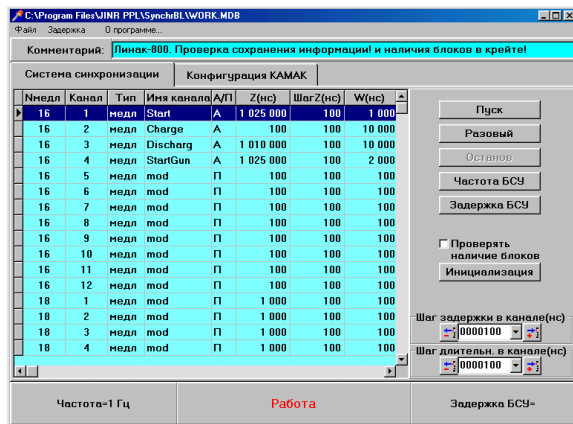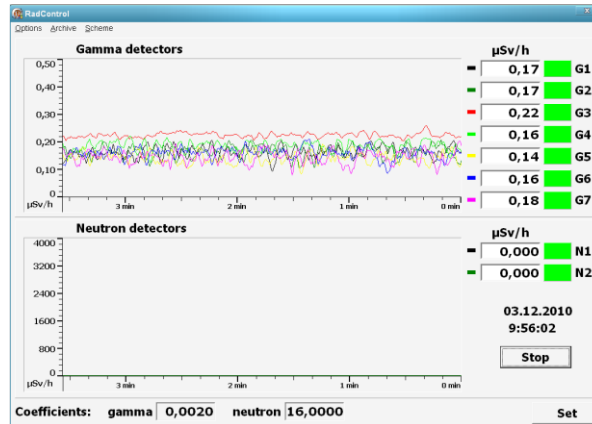| Parameter	Station	
	A01	A04
Electron energy, MeV	5-25	40-200
Pulse duration, µs	0,1-3,5	
Max. pulse current, mA	60	40
Pulse repetition rate, Hz	1-25	

First Control System Upgrade

Electron gun control system software

General view of the temperature control system

Synchronization system software

Radiation control system software


Interlocking and alarm system switchboard

M. A. Nozdrin, "A set of hardware-software control and diagnostic tools for the Linac-200 electron accelerator and the prototype of the JINR photoinjector," Cand. Sci. (Tech. Sci.) Dissertation, Joint Inst. Nucl. Res.
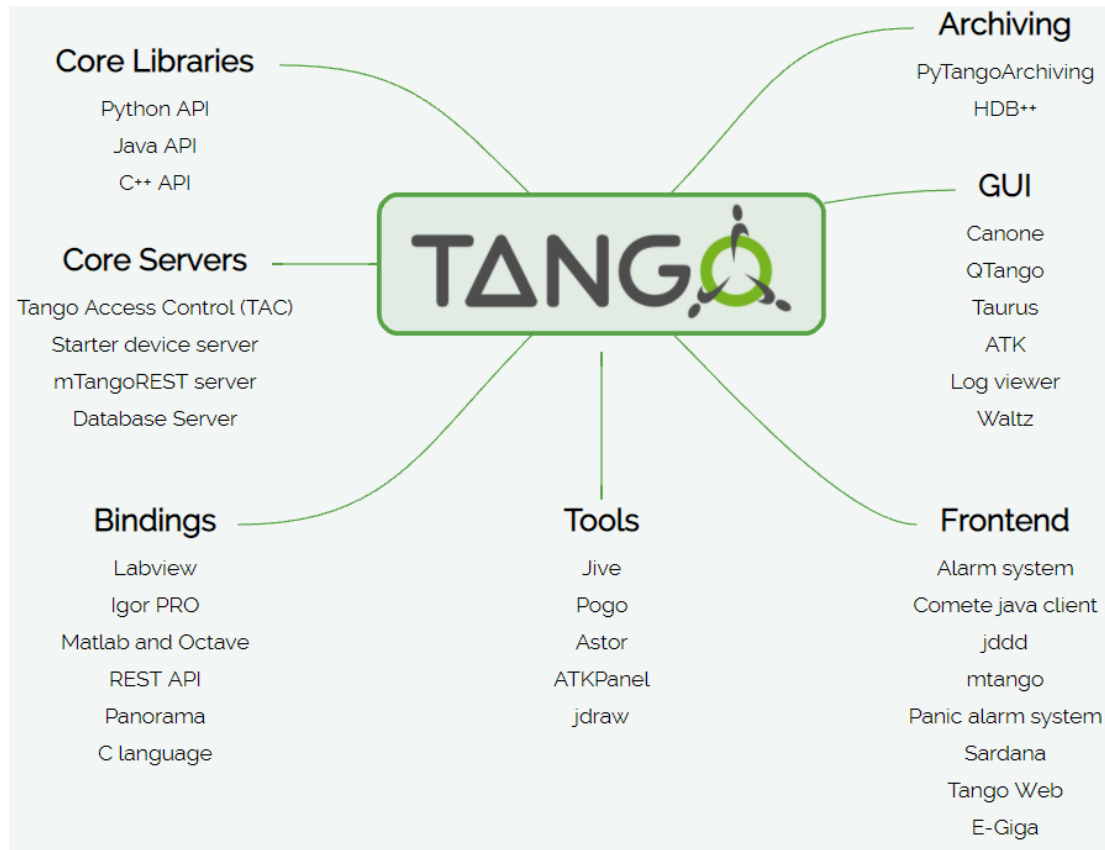
Main requirements for the control system:

- high reliability

- serviceability

- using standard interfaces for communication between components

- possibility of future modifications and extensions

- possibility of using existing developments of the world community
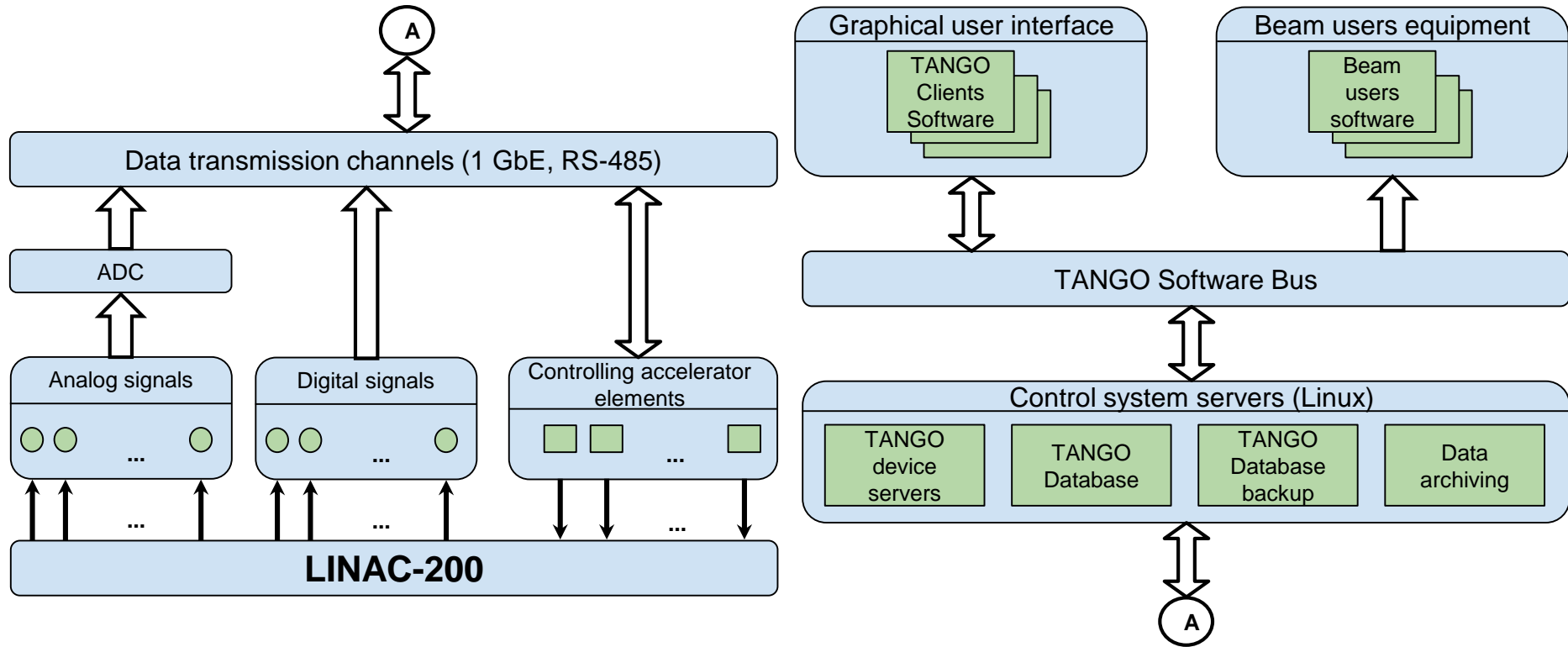
TANGO-based Control System

Official website: https://www.tango-controls.org/
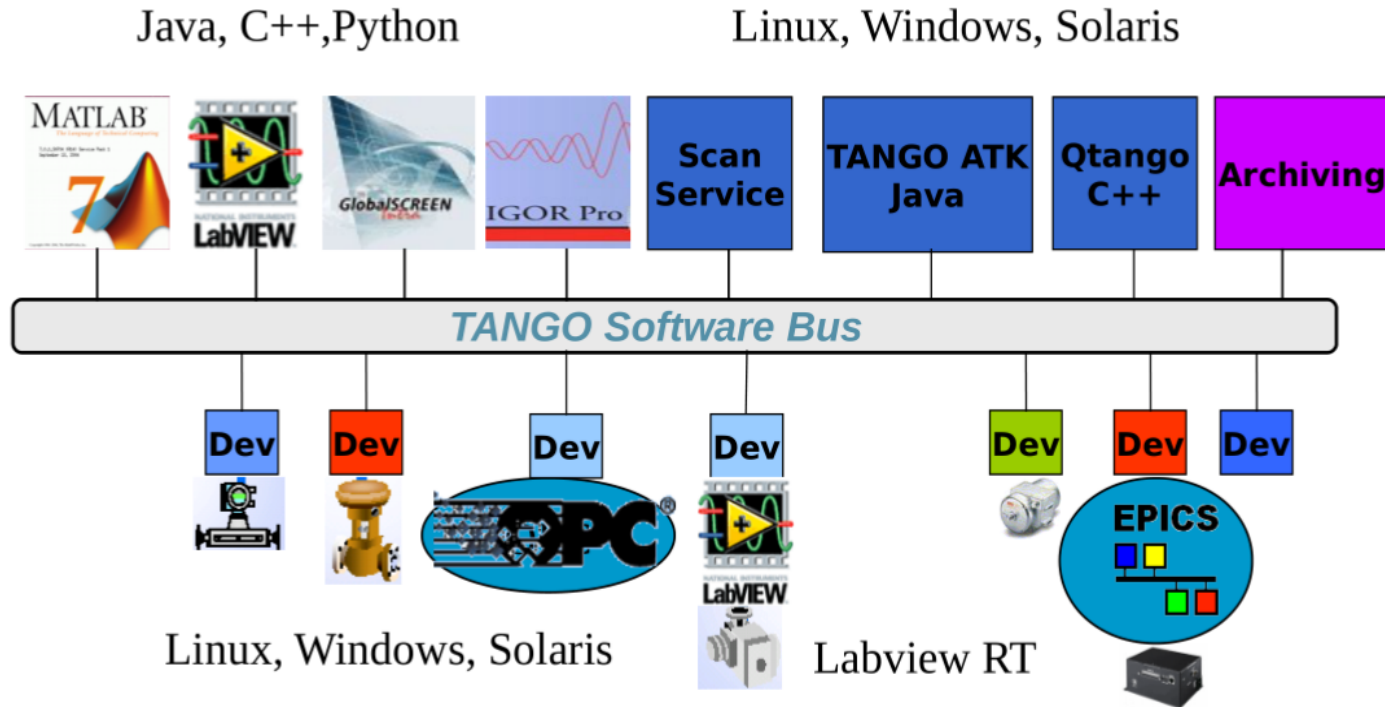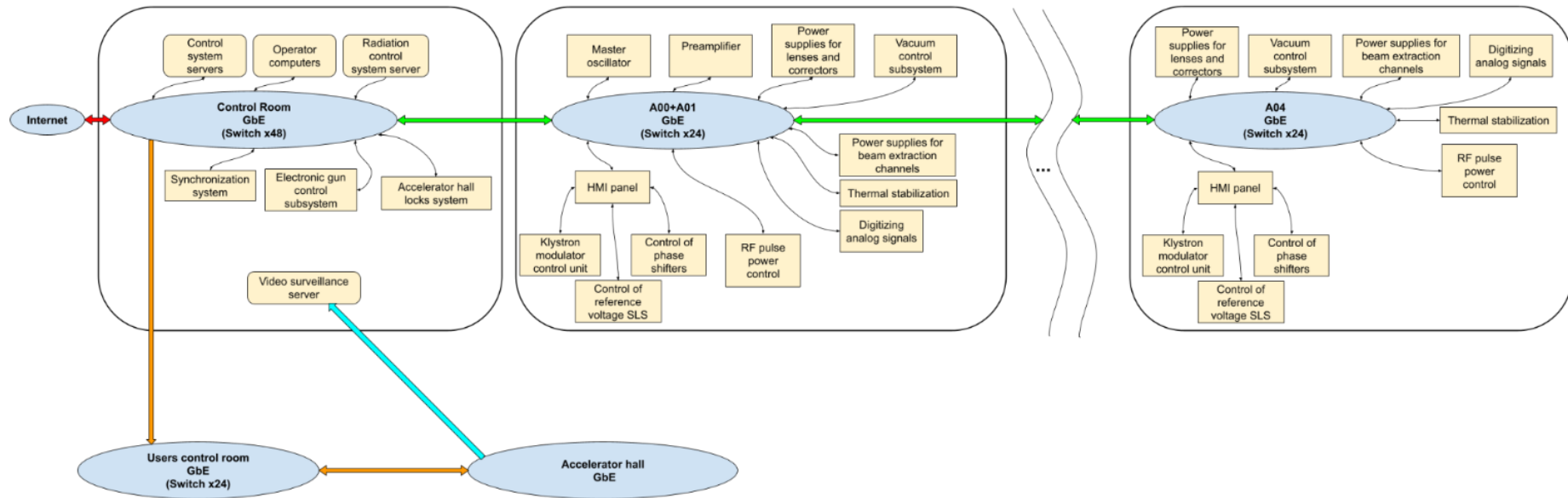
TANGO Ecosystem

Control System Concept

# Network Infrastructure

Local Control

➢ Local control is available for modulator control units and phase shifters. It's done with the Weintek MT8071iP operator panel.

➢ In addition to displaying the local control graphical interface, the Weintek MT8071iP panel acts as a Modbus server.

Control object ↔ **Hardware** — Modbus RTU RS-485 → **HMI Panel** ↔ Modbus TCP / RTUoverTCP Ethernet ...
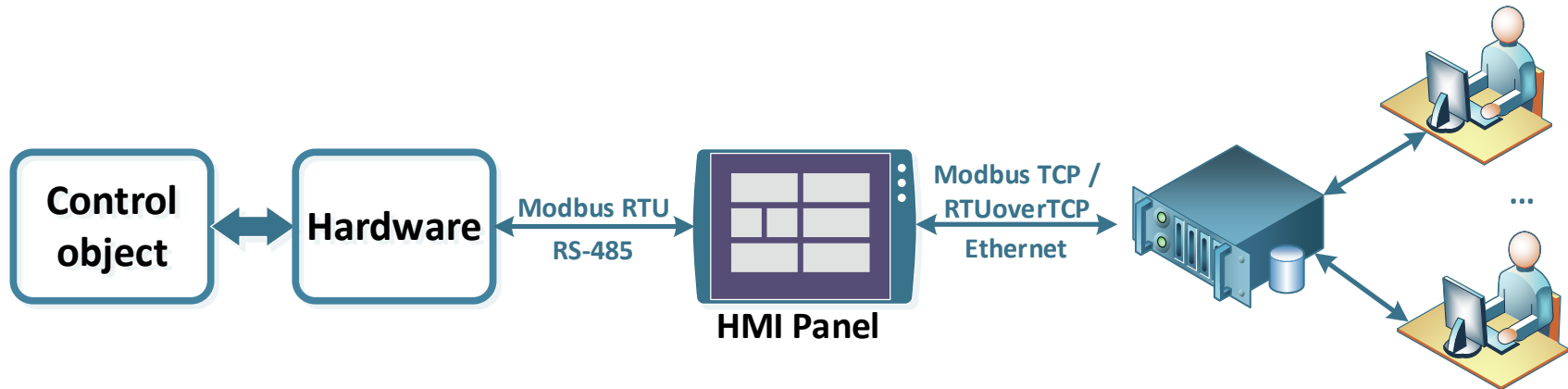
Technology Stack

In use today

- Tango version – 9.2.5

- Linux Debian/Ubuntu

- C++, Python3

- PyTango

- Qt5, Qtango

Future plans

- Cumbia

- Taurus

- Web client applications

Linac-200 Control System Subsystems

|	
Electron Gun Control System	400-kV DC triode-type electron gun with a thermionic cathode is used. New software for the electron gun control was developed.
Synchronization System Control	New synchronization system by Dialtek will be used. At the moment, a standalone software is used to control the synchronization system. In the future Tango-based software would be developed.
Control of RF System Elements	Master oscillator, preamplifier, klystrons modulator control units, phase shifters.
Vacuum Control System	The vacuum system is controlled by the B&R PLC model X20CP3584. Interaction with the global control system is carried out through the Modbus TCP protocol.
Precise Temperature Regulation System	Its planned to use the Unichiller 100-H circulators by Huber. A special Pilot ONE unit would be used to control the circulators.
Focusing and Steering Magnets Control	Focusing and steering magnets are powered by the KORAD KA3005P and KA6003P power supplies.

20 KORAD power supplies
- 18 (30 V, 5 A)
- 2 (60 V, 3 A)

Ethernet to RS485 converter

Modules for communication with power supplies
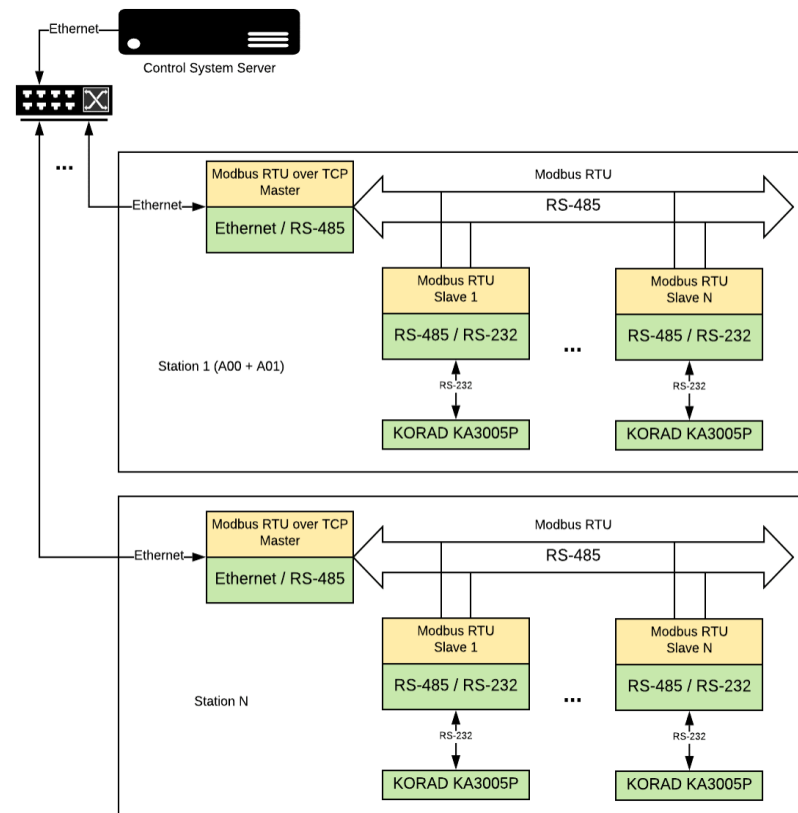
Magnetic element control system layout

# Focusing and Steering Magnets Control

Conclusion

The general concept of the global control system which capable of providing launch and control of the main accelerator subsystems has been designed. Tango-based software for individual subsystems of the Linac-200 has been developed.

The accelerator building is undergoing major repairs. After the completion of the first phase of the repair, it is planned to launch the accelerator with a new control system.

Publications

1. A. Trifonov et al. "The Control System of the Linac-200 Electron Accelerator at JINR", in Proc. ICALEPCS'21, Shanghai, China, October 2021, paper TUAR03 (to be published).

2. M. Nozdrin, A. Trifonov, V. Kobets, V. Minashkin, "Linac-200 Gun Control System: Status and Plans" in Proc. ICALEPCS'21, Shanghai, China, October 2021, paper MOPB018 (to be published).

3. А.Н. Трифонов, и др., "Система автоматизированного управления магнитными элементами для фокусировки и коррекции положения пучка ускорителя ЛИНАК-200" // Приборы и техника эксперимента 2021, Т. 3, С. 152–154.
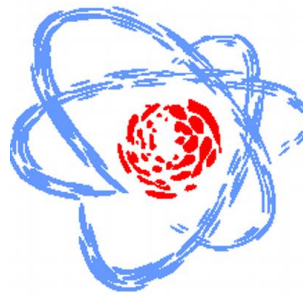
LINAC-200 Control System Status

A.N. Trifonov[1], M.I. Gostkin[1], V.V. Kobets[2], M.A. Nozdrin[3], A.S. Zhemchugov[1], P.P. Zhuravlyov[1]

1 – Dzhelepov Laboratory of Nuclear Problems, Joint Institute for Nuclear Research, Dubna, Russia

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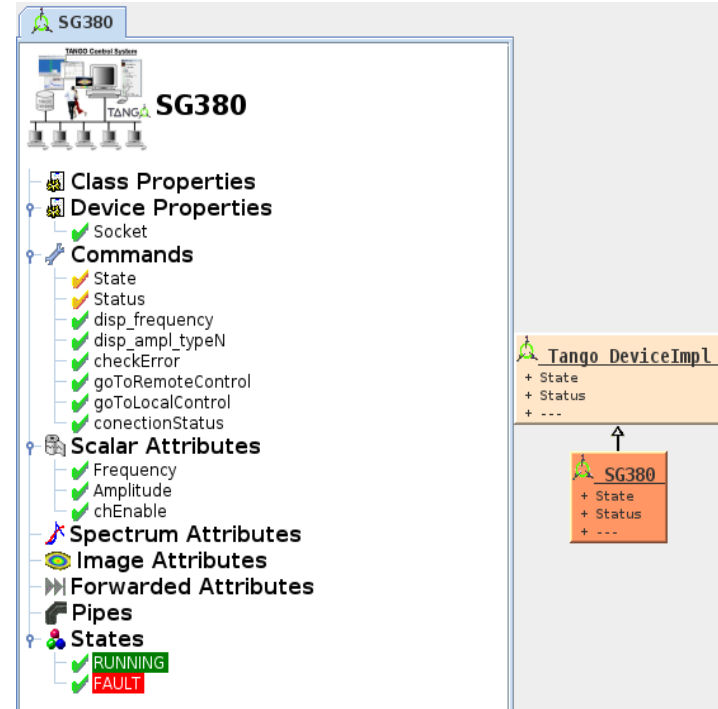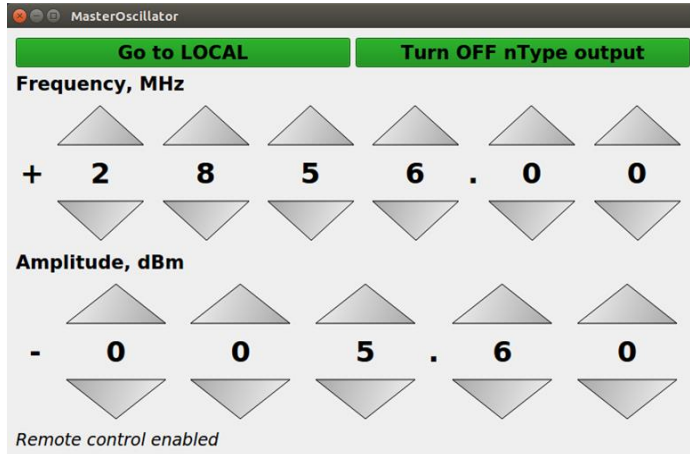3 – University Centre, Joint Institute for Nuclear Research, Dubna, Russia
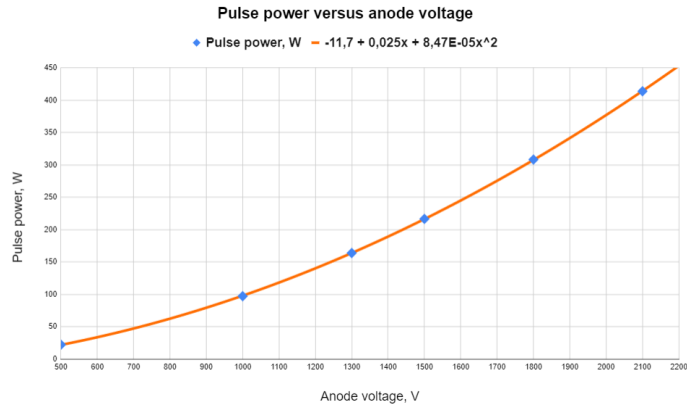
Contact details:
Aleksei Trifonov
e-mail: trifonov@jinr.ru

Backup slides

Master oscillator

Pulse power versus anode voltage

◆ Pulse power, W — -11,7 + 0,025x + 8,47E-05x^2
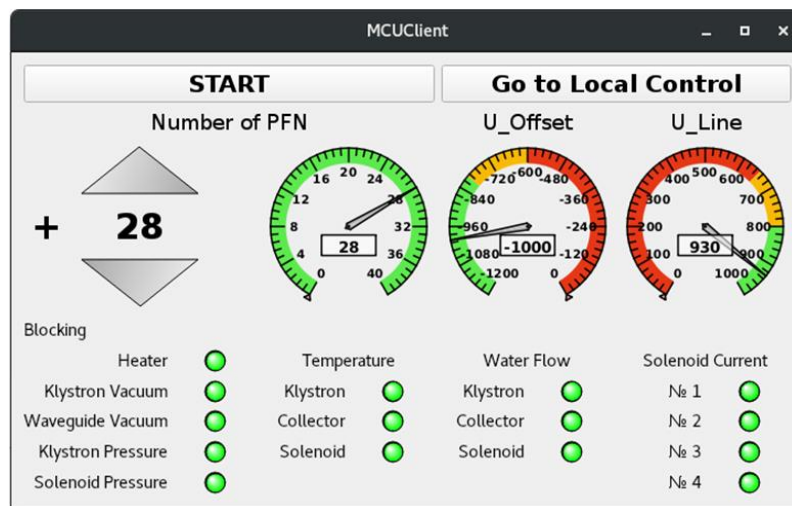

Preamplifier

Turn OFF output

Output voltage setting, V

+ 1 6 2 0

Output voltage, V   1620

Pulse power, W   260

Modulator control unit

Communication

PyModbus based device server for communication via Modbus protocol.

Support RTU, TCP and RTUoverTCP communication formats.