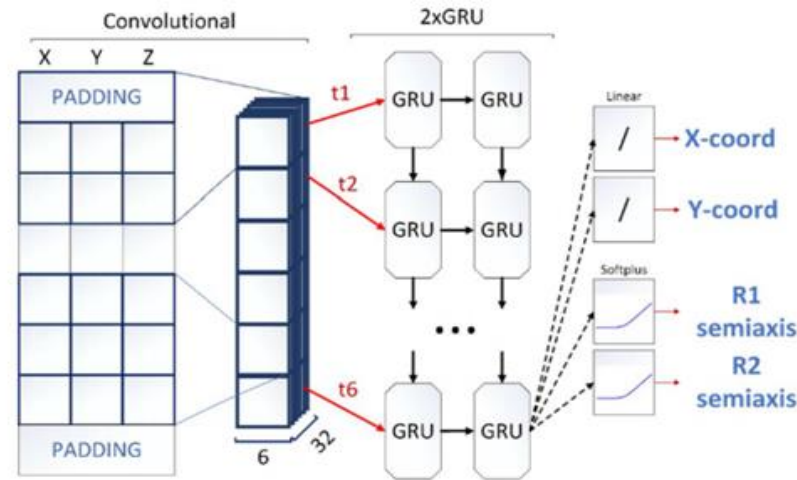


SPD track reconstruction using TrackNet neural network

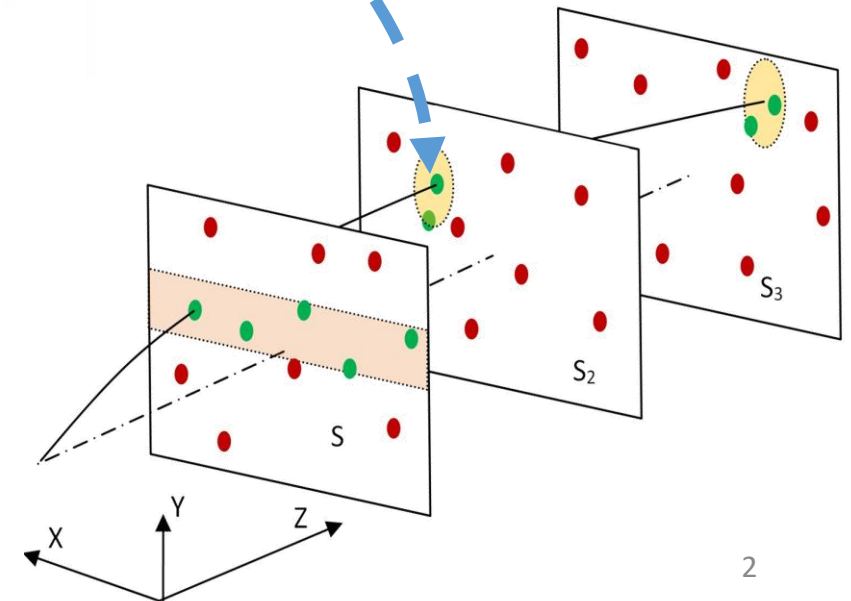
TrackNet

TrackNET is an algorithm for local tracking that allows us to restore each track station by station.

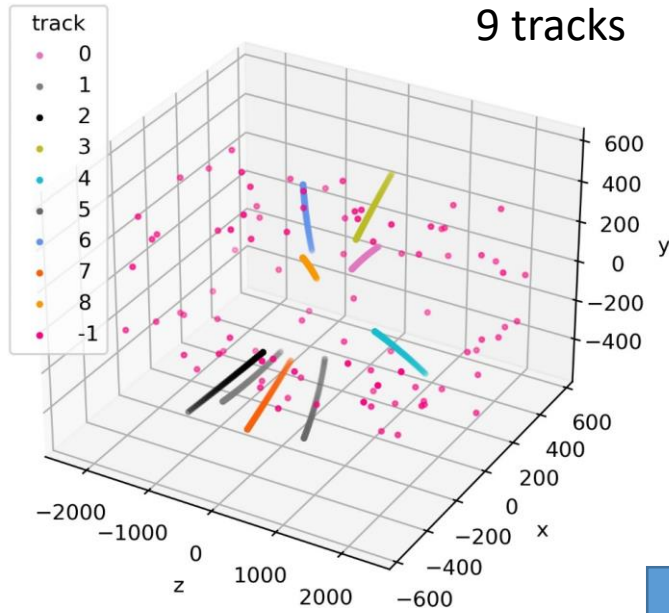
Tracknet uses recurrent architecture to extract temporal features from data and convolutional to get additional features from coordinates of hit.



The prediction is ellipse in which we search for next candidate hit. So, one by one, we construct candidate tracks, and even if early ellipses contain wrong hits, consequential construction of ellipses leads to discarding of such candidates.



Tracking process

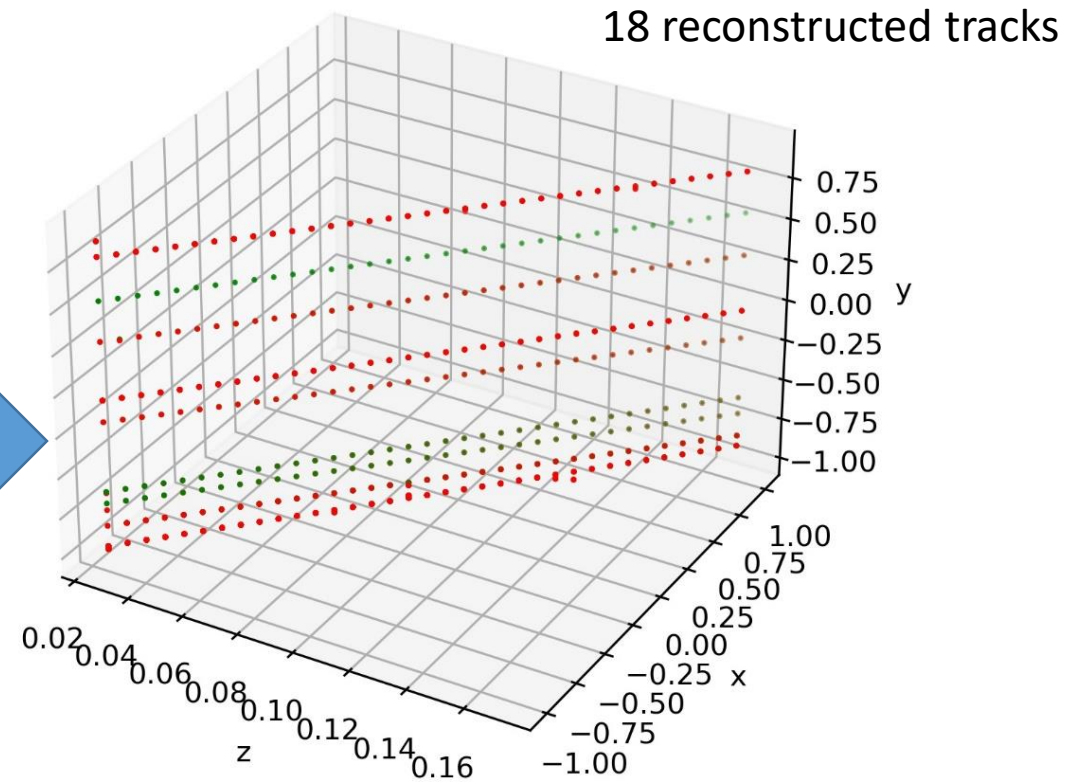


Preprocessing each event:

- Convert to cylindrical coordinates
- Normalized coordinates



Model was trained using Ariadne library algorithms



We decide that the track is restored only if 100% of the hits were determined correctly.

Results

The quality of track recovery is assessed using two metrics: recall and precision.

Recall is the percentage of true tracks that have been restored completely.

Precision reflects the proportion of true tracks among all tracks found by the model.

Inference speed on a **single Nvidia Tesla V100**

Recall	0,93
Precision	0,16

Mean gpu time per event 0.1952 sec
5.12 events per second

Increasing Precision

1. To fit a helical line to each track using the maximum likelihood method.
2. Calculate for each received line χ^2 .
3. Using the average value + 3 sigma as a criterion for dropping out, discard the extra tracks.

