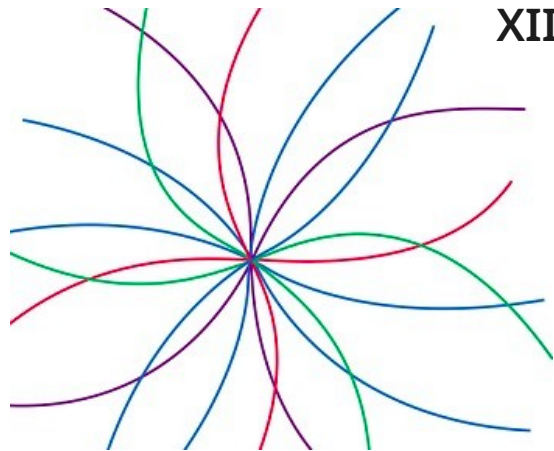


Implementation of task for calibration of TPC gas drift velocity

XII Collaboration Meeting of the MPD Experiment at the NICA Facility



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Belgrade, Serbia

MPD TPC

TPC gas

Gas mixture 90% Ar + 10% CH₄

Operating pressure 2.0 ± 0.1 mbar

(relative to atmospheric)

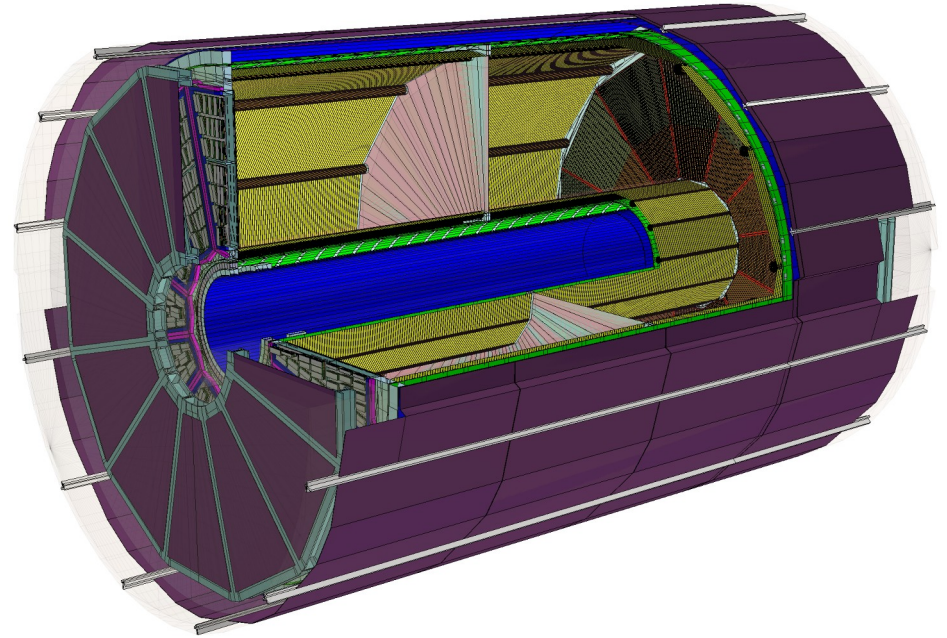
Temperature 25 °C

stability < 0.5 °C

**Electron drift velocity in electric field
140 V/cm and magnetic field 0.5T**

~ 5.53291 cm/ μ s +/- 0.01%

(Garfie++ simulation)



According to TPC TDR v7

Electron Drift Velocity calculation problem

Impact on drift velocity

Temperature

Pressure

Charged areas in gas volume

Read trigger delay

Cumulative delay of all triggers before Read-Out Camera (ROC) starts gathering data

Delay between moment when collision event happens and starting of gathering data by ROC

Time offset of all data

Read-Out Cameras (ROC)

24 sectors — 24 ROCs

>95000 read-out channels in total

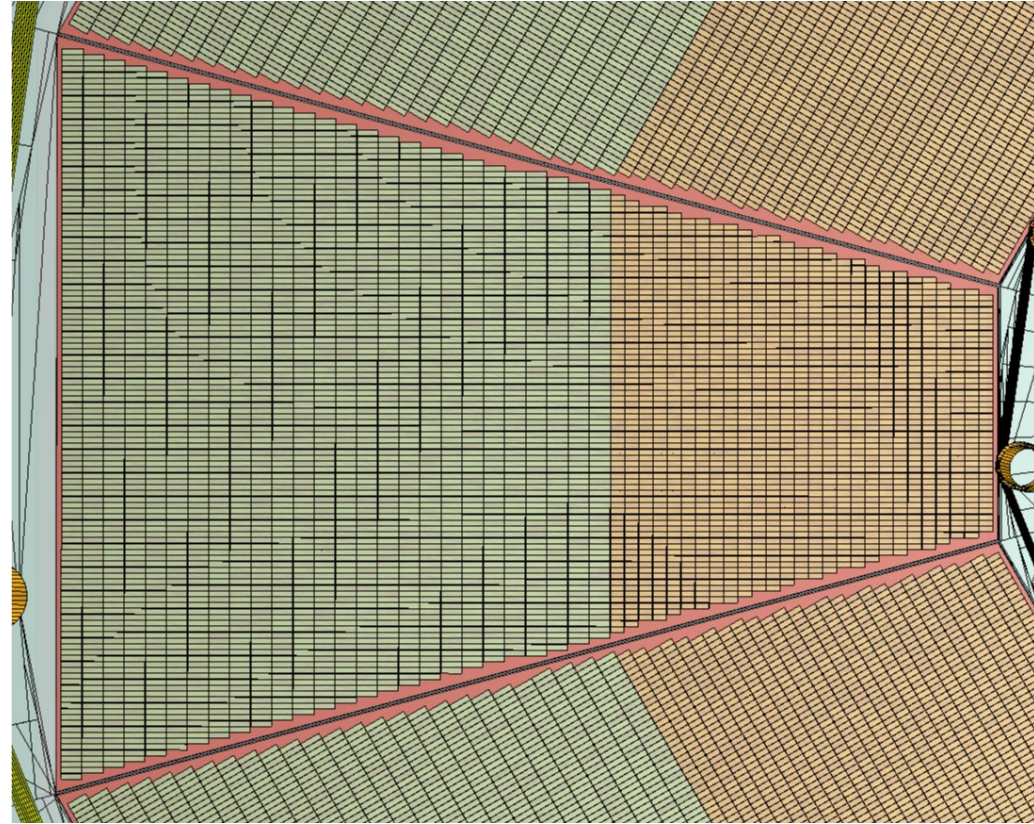
Each ROC

~4000 active pads — read-out channels

Each read-out channel

310 time buckets

10 MHz — 100 ns per bucket



SAMPA electronics (Read-out Cameras)

Read-out channel parameters

100 ns – time bucket, 310 time buckets

>95000 read-out channels in total

SAMPA impulse shape function

$$f(x) = \left(\frac{x-t}{\tau}\right)^N e^{-N\left(\frac{x-t}{\tau}\right)} + Bl$$

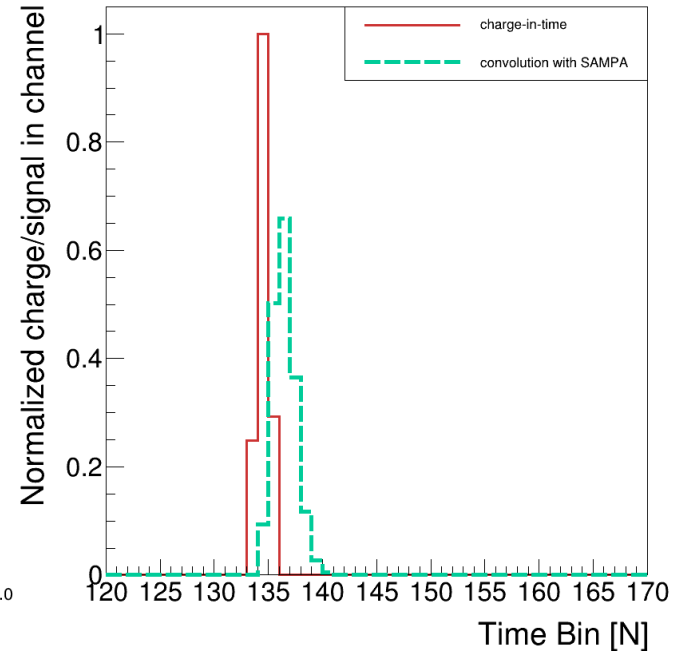
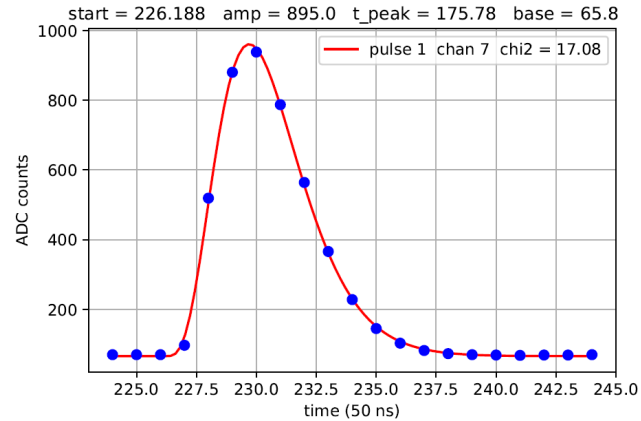
$N = 4$ — shaping order

$\tau = 160$ — peaking time (ns)

$Bl = 0$ — baseline

t — start time

$Ae^{-N} = 20$ (30) — amplitude (fC per mV)



According to article SAMPA Based Streaming Readout Data Acquisition Prototype

Simulation features for testing velocity calculations

Electrons drifting + ROC response

«Digitizing» task in MPDRoot software

Forming charge-in-time distributions for each pad of the TPC

- Transferring electrons from MC track to Pad Plane of ROC with desired electron drift velocity

- Adjust electron drift times taking into account read trigger delay

- Remove electrons that reach ROCs plane before read trigger occurs

Simulation of SAMPA electronics

- Convolution of each charge-in-time distribution with SAMPA impulse shape function

Correction each SAMPA channel output data for peaks shift

Always 160 ns for current simulations

Should be pre-measured on test stands for real hardware

Laser Calibration System

UV laser system

Two pulsed 130 mJ 5-7 ns Nd:YAG lasers

~1 mm diameter

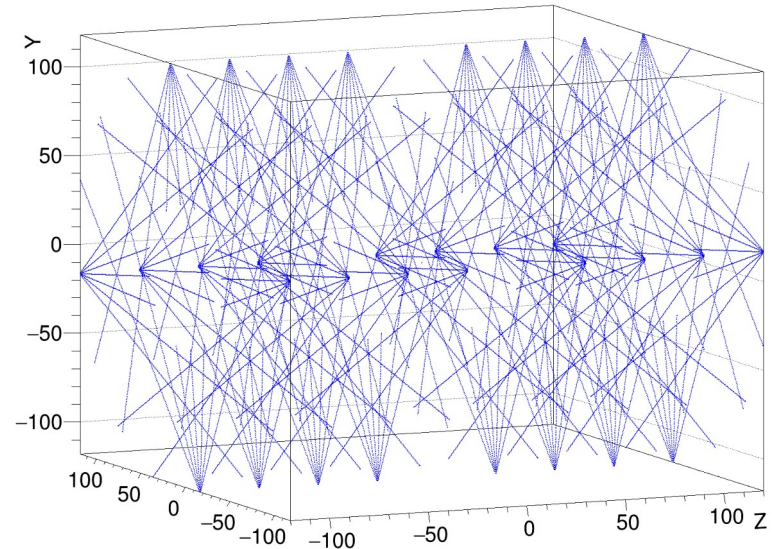
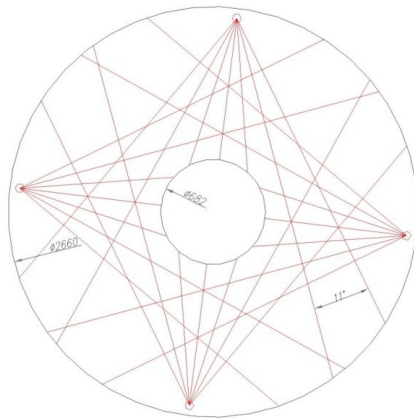
224 laser beams in total

112 "tracks" in each half of the TPC

4 planes of laser beams

30 cm between planes

10 Hz impulses



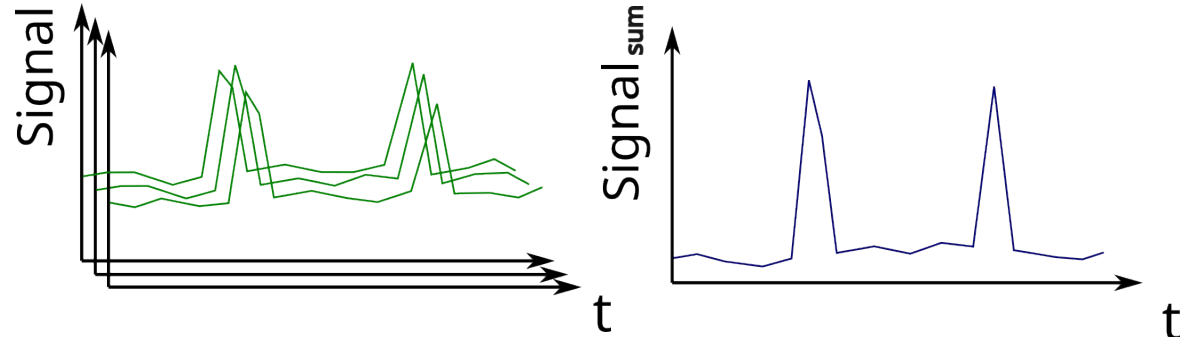
Drift velocity calculation algorithm

Based on cumulative signal-in-time distribution from all channels in sector
Laser grid planes forms high peaks in the distribution

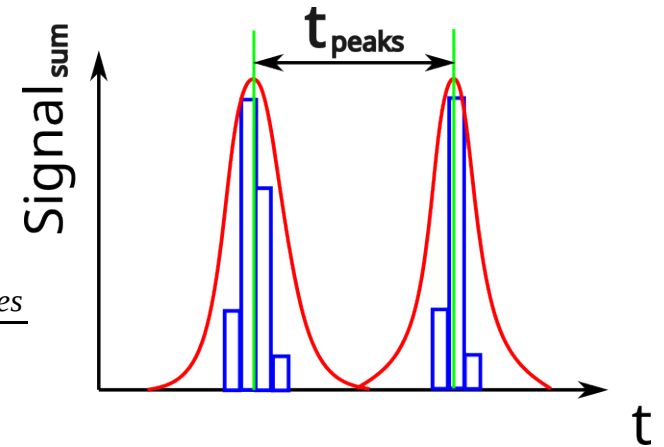
The peaks determines position of laser grid planes

Drift time between positions of laser planes provides velocity information

Difference between measured and «expected» position of laser grid provides trigger delay information



$$V_{drift} = \frac{Z_{between\ laser\ planes}}{t_{peaks}}$$



Drift velocity calculation codes

Points of interest for each TPC sector

Drift velocity calculation along all drift length

- 3 points between pairs of laser planes

- interpolated/extrapolated velocity value for each hit

Read trigger offset calculation

- with taking into account actual drift velocity

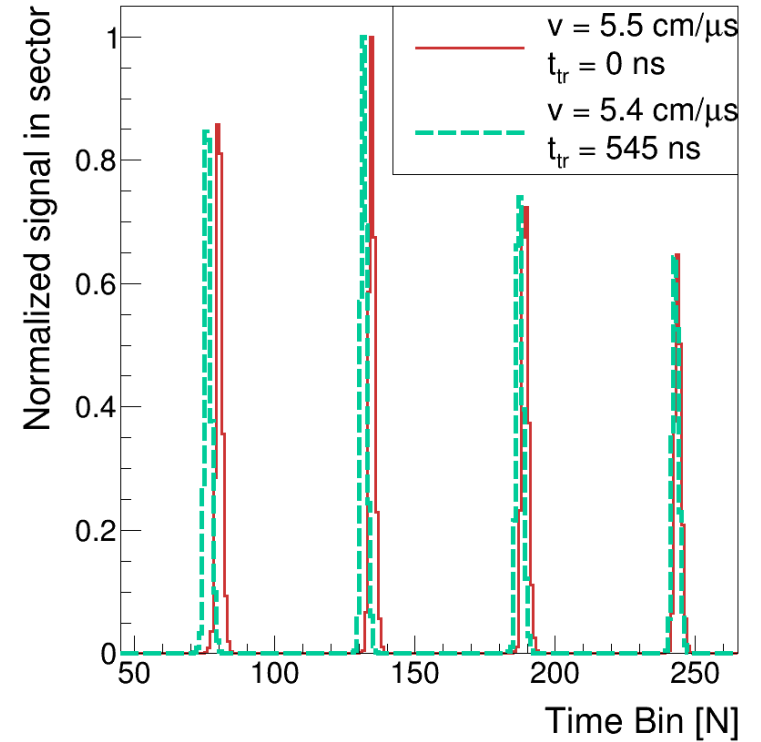
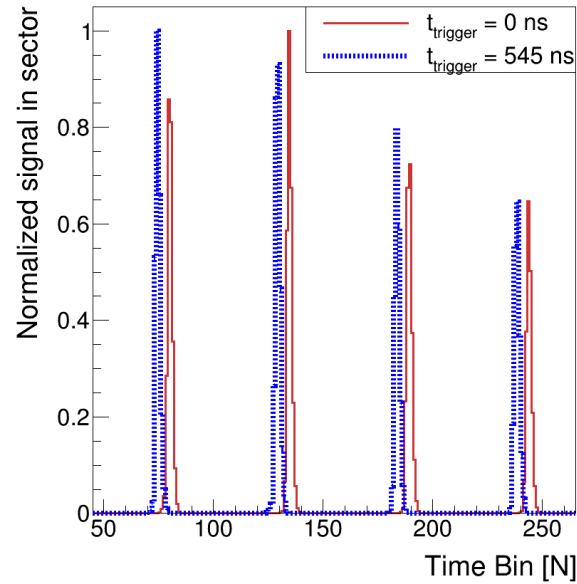
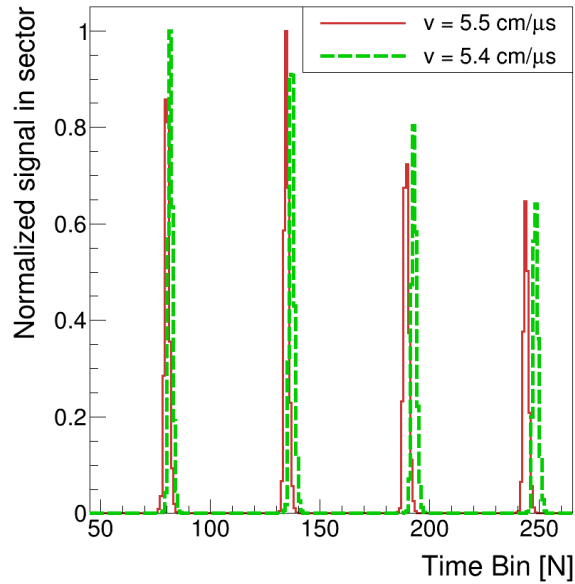
Fast algorithm

Real time calculations for slow control and based on RAW data

Calculations of velocity map of each event less than 100 ms (10Hz)

- now ~70-75 ms, single thread for all sectors (Intel Core i7-8700), codes allow multi-thread per sector

Simulations – laser grid only



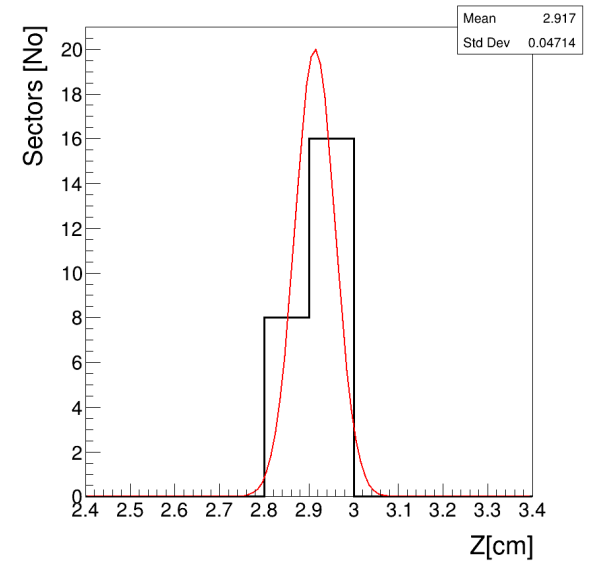
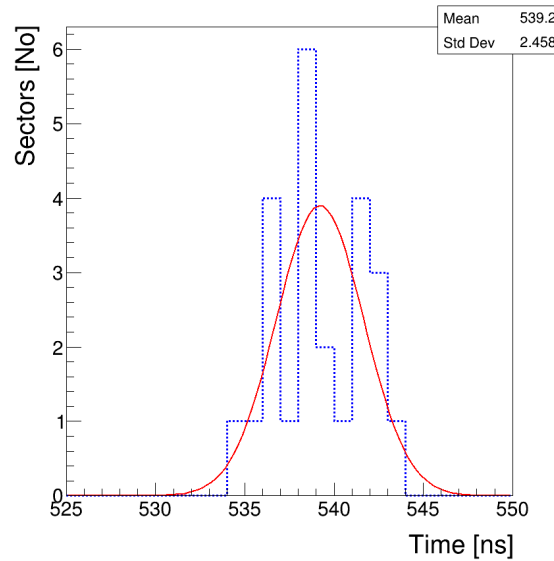
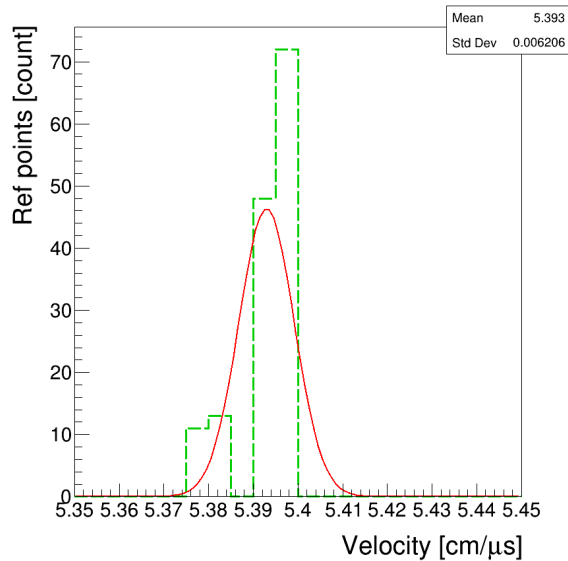
Simulations – laser grid only (2)

Statistics - 500 events of laser grid

$V_{\text{drift}} = 5.4 \text{ cm}/\mu\text{s}$ $t_{\text{trigger}} = 545 \text{ ns}$ (~ 3 cm offset)

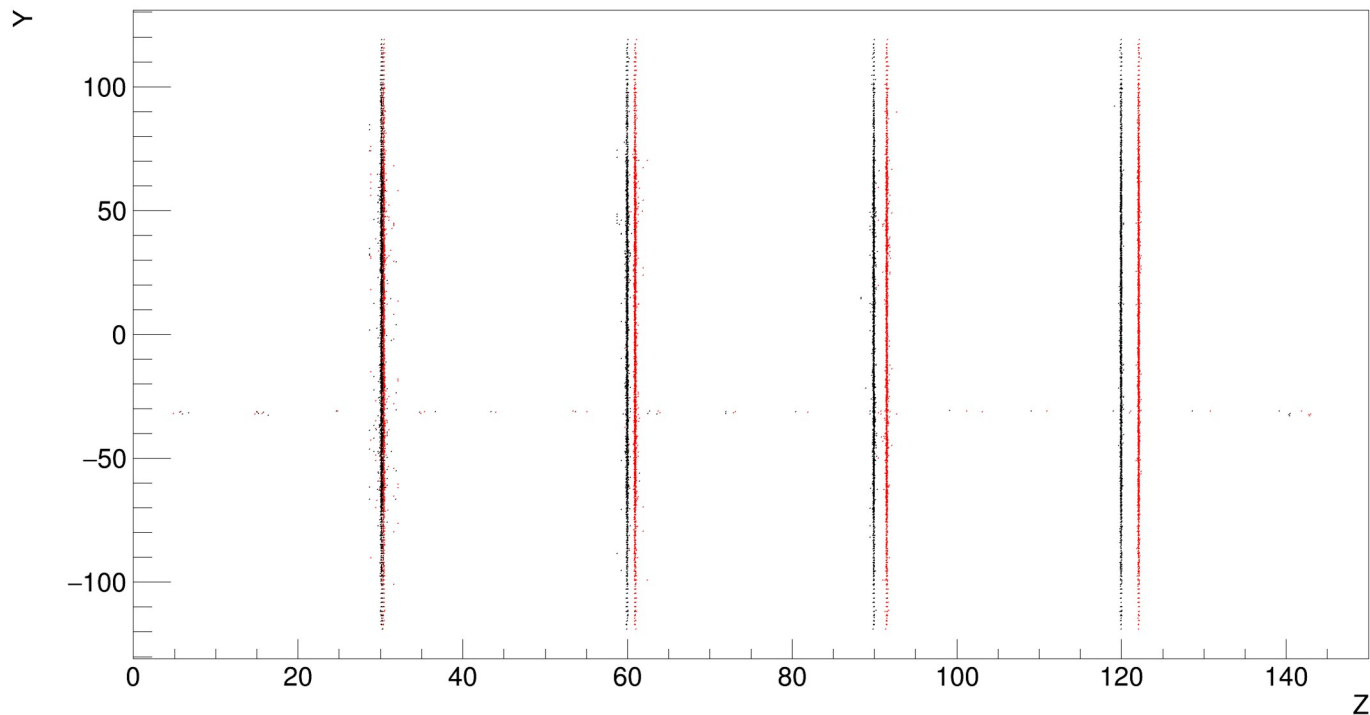
144 velocity reference points = 24 sectors * 6 reference points

4 points — each laser plane, 1 point — HV electrode, 1 point — ROC pad plane

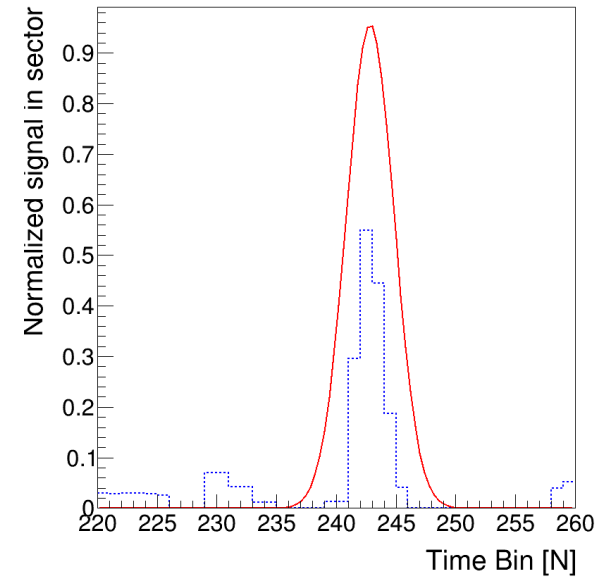
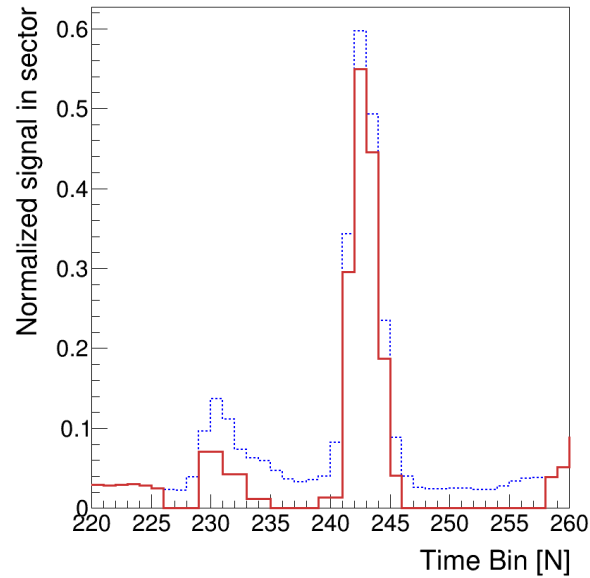
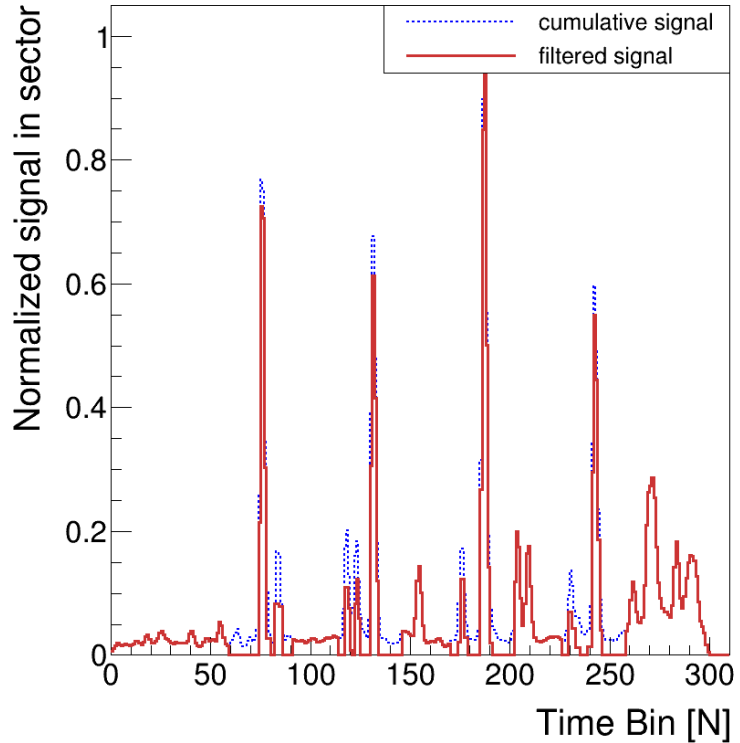


Simulations – laser grid only (3)

Example correction $v_{\text{drift}} = 5.4 \text{ cm}/\mu\text{s}$ $t_{\text{trigger}} = 545 \text{ ns}$



Simulations – laser grid mixed with event



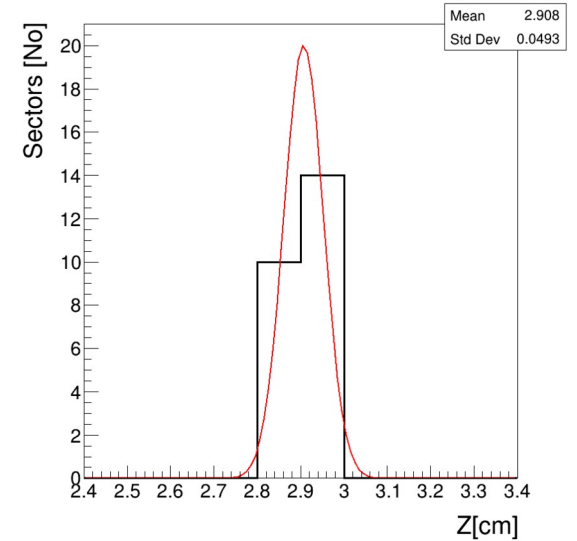
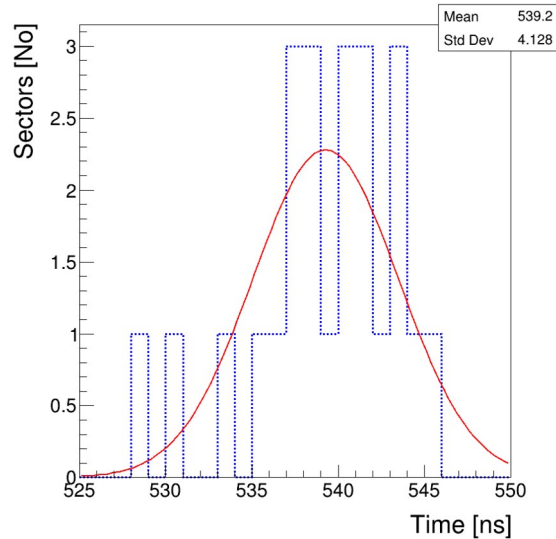
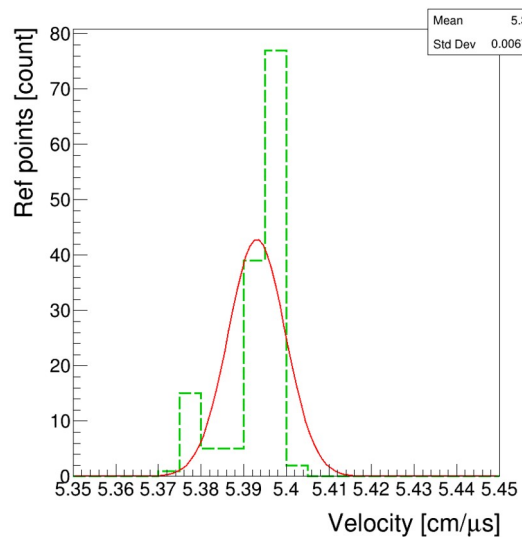
Simulations – laser grid mixed with event (2)

Statistics - 500 events of laser grid

$V_{\text{drift}} = 5.4 \text{ cm}/\mu\text{s}$ $t_{\text{trigger}} = 545 \text{ ns}$ (~ 3 cm offset)

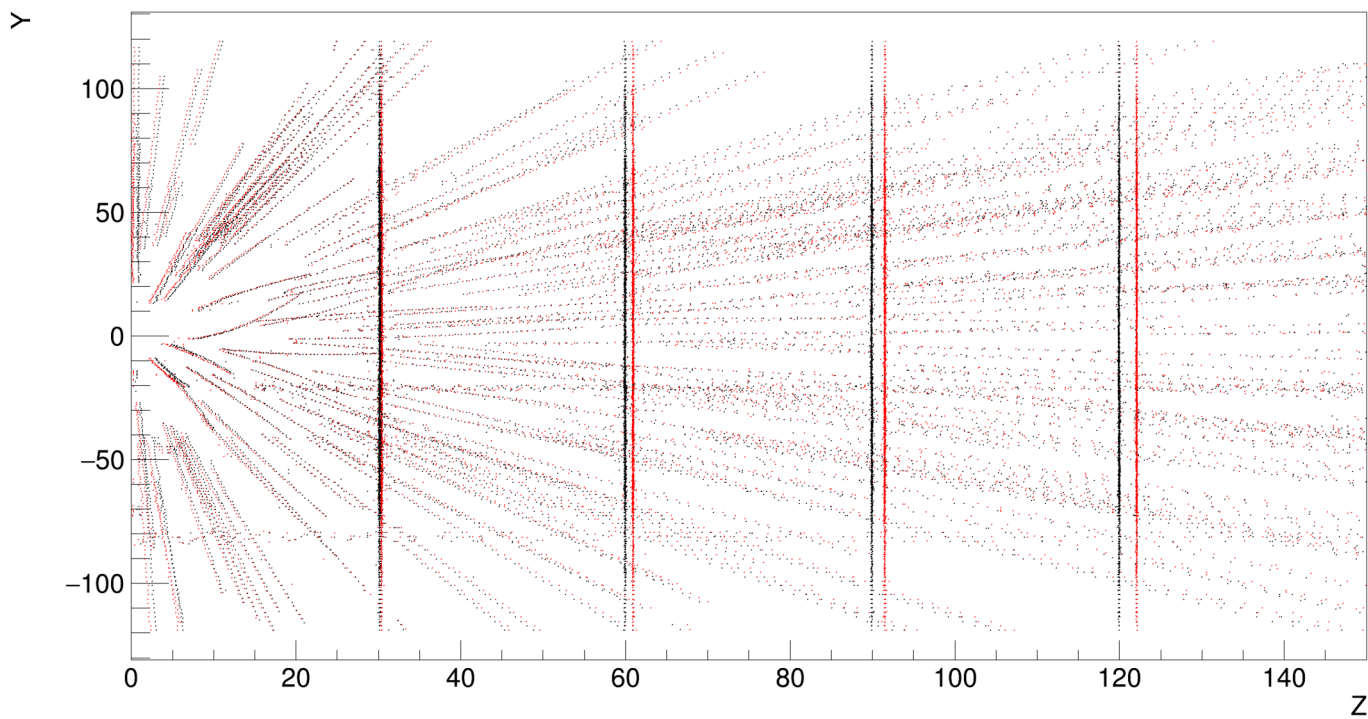
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Simulations – laser grid mixed with event (3)

Example correction $v_{\text{drift}} = 5.4 \text{ cm}/\mu\text{s}$ $t_{\text{trigger}} = 545 \text{ ns}$



Future Plans

Near

Read-Write velocity calibration parameters to DB (now in XML)

Quantity estimations of how calibration impacts on track reconstruction

Medium-far

Study impact of charged areas on drift velocity

Correction of ZR distortions of drift velocity

According papers of STAR experiment velocity near inner tube is different from velocity in most of volume of TPC

Codes adaptation to real hardware (there is no working experimental ROC now)

That`s it

Thank you
for attention!

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