

Symplectic extension of the Haag-Araki axiomatics and its applications in the physics of causal geodesic structures.

Goal of the work: Create an axiomatic equivalent to the axiomatics of Haag-Araki and Whiteman, based on the principle of causality for sticky sets.

Axiomatics of causality set on local geodesic structure:

Assumption(Axiom) 1.

$$IntI^+(q)IntI_j \overline{CIntI^-(p)CIntI^+(p)}$$

Proof of the Assumption 1.

$$\begin{aligned} IntI^+(q) \overline{IntI(p)} IntI_j \overline{CIntI^-(p)CIntI(p)} \\ = IntI^+(q) \overline{IntI^-(p)CIntI^+(p)CIntI^-(p)CIntI(p)} \\ = IntI^+(q)I^+(p) \overline{IntI^-(p)CIntI^-(p)CIntI(p)CIntI_j} \\ = IntI^+(q)I^+(p) \overline{CIntI_0^+(P)CI^-(q) \cup IntI^+(p)CIntI_j} \\ = IntI^+(q)I^+(p)CI^-(q) \cup IntI^+(p) \cup IntI^-(p) \\ = IntI^+(q) \cap IntI^-(p) \end{aligned}$$

$$I_0^+CI^-(q), I_0^+(P) \neq \emptyset.$$

Axiom 2. This axiom defines the complement of the past set in a globally hyperbolic neighborhood of an eventually periodic point.

$$\begin{aligned} IntI^-(p)CI^-(q)CIntI_j \overline{CIntI(p)}I^+(p) \\ = IntI_j I_0^+CI^-(q)IntI^-(p)IntI^+(q) \\ \cup IntI^+(q)CIntI_j \bigcup \overline{CIntI^+(p)} \cap IntI^-(p)IntI^+(p) \\ \cup IntI^-(q)IntI^+(q)CIntI^+(p)CIntI_j \\ = \bigcup \overline{CIntI^+(p)} \cap IntI^-(p)IntI^+(p) \\ \cup IntI^-(q)IntI^+(q)CIntI^+(p)CIntI_jIntI^+(q) \\ \cap IntI^-(p) \\ = \overline{CIntI^+(p)} \cap IntI^-(p)IntI^+(p)CIntI_jIntI^+(q) \\ \cap IntI^-(p) \\ = \overline{IntI^-(q)CIntI_j \overline{CIntI^+(p)}} \cap IntI^-(p) \cup IntI^+(q) \end{aligned}$$

$$\overline{IntI^-(p)} \cap I^+(q) \neq \emptyset$$

Axiom 3.

$$\overline{IntI(p)}CIntI^+(q) \cap IntI^-(p) \bigcup T \overline{IntI^-(q) \overline{IntI(p)}} \subset IntI^-(q) \cap IntI^+(p)$$

Corollaries from Assumption 1 and properties of nested sets:
1. Time is a Markov process
2. Controlled packed globally hyperbolic sets are completely simple

$$\begin{aligned} IntI_{U \ni v} CI^-(q)CIntI_j T \\ \cup Int[x_p^* \dots, x_{p+1}] \overline{CIntI^+(q)I^+(p)CI^-(q)CI^-(p)CIntI_j} \\ = IntI_{U \ni v} \overline{CI^-(q)IntI^-(p)IntI^+(q)T} \cap IntI_j \\ := [x \dots, x_i]^p CIntI_j \cup IntI[x_p^* \dots, x_{p+1}] = IntI_j \\ := [x^* \dots, x_i]CIntI_j \cup T_{\omega}^* \overline{CIntI^-(p)CIntI^+(p)} \\ = IntI_{U \ni v} CI^+(q)CIntI_j \cup T_{\omega}^* \overline{CIntI^-(p)CIntI^+(p)} \\ = IntI_{U \ni v} CI^+(q)CIntI_j \cup T_{\omega \dots, \omega_0} \\ \cap I_{\omega_0 \dots, \omega} \overline{CIntI^-(p)CIntI^+(p)} \end{aligned}$$

Consider, the causal geodesic structure. In the symplectic case, gets

$$\begin{aligned} \frac{\partial}{\partial \tau} g \left(\frac{\partial}{\partial \tau} \cdot \frac{\partial}{\partial s} \right) = \frac{\partial}{\partial \tau} g \left(\frac{\partial}{\partial \tau} \cdot \frac{\partial}{\partial t_j} \right) = \frac{\partial}{\partial \tau} g_j(J(u)) \partial s \partial t = \frac{1}{2} \frac{\partial}{\partial t_j} g(J(u)) \partial s \partial \tau = g \left(J(u) \frac{\partial}{\partial \tau} \frac{D}{\partial s} \frac{\partial}{\partial t_j} \right) \\ = g(u, v) \exp x(q) \partial s \partial u \frac{D}{\partial s} \frac{\partial}{\partial t_j} = g(u - v) \frac{D}{\partial s} \frac{\partial}{\partial t_j} g^{ba}_{ab} = g_j \frac{D}{\partial t} \left(\frac{\partial t}{\partial t_j} \right) \partial s \partial \tau \end{aligned}$$

In tangent space the equation takes the form:

$$\begin{aligned} J(g(u - v_{\cdot}^a)) \frac{D}{\partial s} \frac{\partial}{\partial t_j} g^{ba}_{ab} = J \left(g_j(u - v) \partial t / \partial t \frac{D}{\partial \tau} \right)_b g^{ba}_{ab} \partial s = J \left((u)(v - s) g^{ba}_{ab} \right) \partial \tau s \\ = J \left(\frac{1}{2} u \left(v_{\cdot}^a - \frac{D \partial}{\partial t_j} \right) g^{ba}_{ab} \exp x(q) \right) \partial \tau \partial u = J g_j \left(-\frac{1}{2} \right) \left(\frac{v_{\cdot}^a}{\frac{D \partial}{\partial t}} g^{ba}_{ab} (u - w) \exp x(q) \right) \partial \tau \partial u \\ = J_j g \left(\frac{v_{\cdot}^a}{\frac{D \partial}{\partial t}} g^{ba}_{ab} (u - w) \right) \exp x(q) \partial \tau \partial u \partial s = J_j g * s \left(\left(\frac{v_{\cdot}^a}{\frac{D \partial}{\partial t}} g^{ba}_{ab} (u - w) \right) \right) \\ = \frac{1}{2} \frac{\partial s \partial u}{\partial \tau} J(u) \partial u \partial t = \frac{D}{\partial \tau} \left(\frac{\partial}{\partial s_j} \frac{\partial u}{\partial \tau} J(u) \partial s \partial u \right) = \frac{1}{2} \frac{\partial}{\partial t} J(u) \partial s \partial u \end{aligned}$$

For closed time-like circuit propagator

$$\begin{aligned} \frac{\partial}{\partial \tau} \frac{D}{\partial \tau} g \left(\frac{\partial}{\partial \tau} \cdot \frac{\partial}{\partial s} \right) = \frac{\partial}{\partial \tau} g \left(\frac{\partial}{\partial \tau} \cdot \frac{\partial}{\partial t_j} \right) = \frac{\partial}{\partial \tau} g_j(J(u)) \partial s \partial t = \frac{1}{2} \frac{\partial}{\partial t_j} g(J(u)) \partial s \partial \tau \\ = g \left(J(u) \frac{\partial}{\partial \tau} \frac{D}{\partial s} \frac{\partial}{\partial t_j} \right) = g(u, v) \sup T_{\omega \lambda}^* B(x^*, \cdot) \partial s \partial u \frac{D}{\partial s} \frac{\partial}{\partial t_j} \\ = g(u - v) \frac{D}{\partial s} \frac{\partial}{\partial t_j} g^{ba}_{ab} = g_j \frac{D}{\partial t} \left(\frac{\partial t}{\partial t_j} \right) \partial s \partial \tau \end{aligned}$$

Is it possible to build a weak *- topology on "open light cones"?

$$\begin{aligned} C^{1-y} \rightarrow M^0: \sum I^+ \in (\overline{Int}^-_p p \dot{q}_n(2^n) \# \langle \langle \pi_L^c: \tau_L^t \rangle \rangle [x_p^* x_{p+1}] - q_0) [q^{*i,s}]^{2p+1} \\ \rightarrow Int\{I_i[x_i, x_{i+1}]\}_{i=0}^{p-1} \\ = IntI_{U \ni v} CI^-(q)CIntI_j \cup T \overline{Int[x_p^* x_{p+1}] CIntI^+(q)I^+(p)CI^-(q)CI^-_i CIntI_j} \end{aligned}$$

From here, we get

$$\begin{aligned} C^y \rightarrow M[(Int\{I_i := [x_i \dots, x_{i+1}] C \dot{O}\} (\overline{Int}^-_p p \dot{q}_n(2^n) \# \langle \langle \pi_L^c: T_{\omega \dots, ijkl}^v \rangle \rangle [x_p^* x_{p+1}] - q_0)_{i=0}^{p-1} [q^{*i,s}]^{2p+1})] \\ = C^p (\overline{Int}^-_p p \dot{q}_n(2^n) \# \langle \langle \pi_L^c: T_{\omega \dots, ijkl}^v \rangle \rangle [x_p^* x_{p+1}] - q_0)_{i=0}^{p-1} [q^{*i,s}]^{2p+1}) \end{aligned}$$

$$U \ni N \overline{C \tilde{N} C \tilde{N}}(p) \ni C^p \rightarrow \overline{N^*} \bigcap V$$

Captured of past-geodesic

$$\begin{aligned} \cap \overline{I_{\omega_0 \dots, \omega_n}} = \overline{T \overline{Int}^-_p CIntI_j \cup IntI_{U \ni v} \cap \overline{IntI^-(q)} \cap I^+(p) CIntI_j} \\ T \overline{Int}^-_p CIntI_j \cup IntI_{U \ni v} T_{\omega}^* \overline{N}(\lambda(p)), \cap_{k=0}^n \end{aligned}$$

$$\begin{aligned} (3) \text{there, } T \overline{Int[x_p^* x_{p+1}] CIntI^+(q)I^+(p)CI^-(q)CI^-_i CIntI_j} \\ = \overline{T \overline{Int}^-_p \overline{IntI^+}_i CIntI_j} \bigcup IntI_{U \ni v} \cap \overline{IntI^-(q)} \cap I^+(p) CIntI_j \\ = \overline{T \overline{Int}^-_p \overline{IntI^+}_i CIntI_j} \bigcup IntI_{U \ni v} \bigcap \overline{IntI^-(q)} CIntI_j \\ = \overline{T \overline{Int}^-_p \overline{IntI^+}_i CIntI_j} \bigcup IntI_{U \ni v} \bigcap \overline{I_{\omega_0 \dots, \omega_n}} \\ = \overline{T \overline{Int}^-_p CIntI_j} \bigcup IntI_{U \ni v} \cap_{k=0}^n T x(\overline{\omega}) \overline{CIntI^-(q)} \\ = \overline{T \overline{Int[x_p^* x_{p+1}] I_{\overline{U}}^+(p)}} \bigcup \overline{T^{-k} \cap_{k=0}^n IntI_{U \ni v} C I_{\overline{U}}(q)} \end{aligned}$$

$$\begin{aligned} \overline{Pd}(U, V) = \max_{supp a^c \in m_{\xi}(\alpha \in A)} (\min|x - y|) + \max_{\alpha_c} (\min||x - y||^2) = (\overline{Pdiam}U + \overline{Pdiam}V) \\ = \overline{Pdiam}_H(\overline{A})_{supp a^c \in m_{\xi}(\alpha \in A)} + \overline{Pdiam}V_{supp a^c \in m_{\xi}(\alpha \in A)} \\ = \overline{Pdiam}_H(U^{\psi_i}) + \overline{Pdiam}V_{supp a^c \in m_{\xi}(\alpha \in A)} \end{aligned}$$

For periodically point on the elliptic set

$$\begin{aligned} U(\psi: A \rightarrow \hat{A})_i = U(sup\psi \overline{B}(x^*(A, \alpha_c), \varepsilon_0) \rightarrow U \sup \psi \overline{B}(x^*(A, \alpha_c), \varepsilon_0)) U C^y \rightarrow \\ C^p (\overline{Int}^-_p p \dot{q}_n(2^n) \# \langle \langle \pi_L^c: T_{\lambda}^* \overline{N}(p) \cap \overline{N}_{k=0}^n \dot{N} CIntI^p I_{-i} \rangle \rangle [x_p^* x_{p+1}] - q_0)_{i=0}^{p-1} [q^{*i,s}]^{2p+1}) \end{aligned}$$

$$\text{Equivalent operator-valued function } T_{\lambda}^* \overline{N} = A(\varphi) e^{-n \varepsilon \omega} = A(\varphi) e^{\frac{k^2}{4}}$$

$$\begin{aligned} (1) T_{\lambda}^* \overline{supBN} J^{\pm}(O)_{IntV \ni N} \cap IntI_{U \ni v} : \exp x_p^{(q)} = T_{\lambda}^* \overline{sup} (B d_0^{\pm} I_0^{\pm}(x^*(A, \alpha_c), \varepsilon_0))_{IntI^-(U \ni v)} \\ = T_{\lambda}^* \overline{sup} d_0^{\pm} (B I_0^{\pm}(x^*(A, \alpha_c), \varepsilon_0))_{IntI^-(U \ni v)} \\ = \overline{sup} \overline{B} \left(J_{U^+ \cap U^-} \left(x^* \left(\frac{\partial}{\partial \tau} g \left(\frac{\partial}{\partial \tau} \cdot \frac{\partial}{\partial s} \right) = \frac{\partial}{\partial \tau} g \left(\frac{\partial}{\partial \tau} \cdot \frac{\partial}{\partial t_j} \right) = \frac{\partial}{\partial \tau} g_j(J(u)) \partial s \partial t = \frac{1}{2} \frac{\partial}{\partial t_j} g(J(u)) \partial s \partial \tau \right. \right. \right. \\ \left. \left. \left. = g \left(J(u) \frac{\partial}{\partial \tau} \frac{D}{\partial s} \frac{\partial}{\partial t_j} \right) = g(u, v) \exp x(q) \partial s \partial u \frac{D}{\partial s} \frac{\partial}{\partial t_j} = g(u - v) \frac{D}{\partial s} \frac{\partial}{\partial t_j} g^{ba}_{ab} = g_j \frac{D}{\partial t} \left(\frac{\partial t}{\partial t_j} \right) \partial s \partial \tau, \alpha_c \right), \varepsilon_0 \right) \right)_{u_1 \dots u_n} \\ = T_{\lambda}^* \overline{sup} \left(B I_0^{\pm} \left(x^* \left(\left(\frac{1}{2} u \left(v_{\cdot}^a - \frac{D \partial}{\partial t_j} \right) g^{ba}_{ab} \right), \alpha_c \right), \varepsilon_0 \right) \right)_{IntI^-(U \ni v)} \\ = T_{[\omega \dots, \omega]_n} \overline{sup} \left(B I_0^{\pm} \left(x^* \left(\left(\frac{1}{2} u \left(v_{\cdot}^a - \frac{D \partial}{\partial t_j} \right) g^{ba}_{ab} \right) g_{\sigma_j} \right), \varepsilon_0 \right) \right) \end{aligned}$$

Proof of the equivalence of the formalism of the area-preserving plane transformation with infinite hierarchical structure and causal sets

For transition between different level of dynamic system

- $IntI^+(q)IntI_j \overline{CIntI^-(p)CIntI^+(p)} \sim I_0^{\pm}$
- $I^-(q)C \overline{IntI}_p \cap I(q)^+ IntI^i \quad IntI_j CI^+(p)$
- $IntI_j CInt\{I_i[x_i, x_{i+1}]\}_{i=0}$
- $IntI_i := [x_{\cdot}, x_i]^p CIntI_j \cup Int[x_p^*, x_{p+1}] =$
 $IntI_{U \ni v} CI^-(q)IntI^-(p)IntI^+(q)T \cap IntI_p = IntI_{\omega \dots, \omega_0} \cup IntI_{\omega_0 \dots, \omega}$
- $[x_p^*, x_{p+1}] = T_{\omega}^* \overline{CIntI^-(p)CIntI^+(p)}$

Traceless tensor of momentum- energy- matter

$$\begin{aligned} \sup T_{\omega \lambda}^* T_{\omega \lambda}^* \overline{B^{Z(r)} \times Z(r)} \left(x^*, \dim U^{\psi_i} \left(J_{U_{\psi_i}^+ \cap U_{\psi_i}^-} \right) \max: \# \langle \langle \pi_L^c: \tau_L^t \rangle \rangle \left(C_p^*(A) \ni N^* \ni M \right. \right. \\ \left. \left. \ni \dot{U} + 2 \sum_{n=1}^{\infty} (N + C)^{1-y} - q_0, \varepsilon_0 \right) \right) \\ = \sup T_{\omega \lambda}^* T_{\omega \lambda}^* \langle \langle \pi_L^c \rangle \rangle N C \dot{N} C_p^*(A) \ni M \ni \dot{U} : \overline{B^{Z(r)} \times Z(r)} \left(x^*, \dim U^{\psi_i} \left(J_{U_{\psi_i}^+ \cap U_{\psi_i}^-} \right) \right) \\ = \sup T_{\omega \lambda}^* (J(w_G(U, \omega))) \end{aligned}$$

This proves the symplectic nesting

$$T \overline{N}(p) M_{\omega \lambda} \ni v \text{ there } M_{\omega \lambda} \ni v$$

$$\begin{aligned} (4) T_{\lambda}^* \overline{N}(p) \cap V = \overline{Int}^-_p T x(\overline{\omega}) = \overline{Int}^-_p T_{\omega \dots, \omega} x^q CIntI_j \cup IntI_{U \ni v} := \\ T_{\lambda}^* \overline{N}_{k=0} \overline{T}_{[\overline{\omega}]_s} \frac{1}{\lambda} CIntI_{U \ni v} CIntI_j CI_{U \ni v}^+ \cup T_{\omega \lambda}^* CIntV \ni N C U \ni N^* C \tilde{N} = \\ \overline{T}_{[\overline{\omega}]_s} \frac{1}{\lambda} CIntI_{U \ni v} CIntI_j CI_{U \ni v}^+ CIntV \ni N \cup T_{\omega \lambda}^* C U \ni N^* C \tilde{N} \ni M = IntT^p M_{\omega \lambda} \ni \\ T_{\lambda}^* \overline{N}(\lambda(p)), \cap_{k=0}^n \dot{N} CIntI_{U \ni v} \cap Int^p I_{-i} C I_{U^-} = T_{\lambda}^* \overline{N} \cap_{k=0}^n \dot{N} CInt^p I_{-i} C I_{U^-} IntI_{U \ni v} = \\ T_{\lambda}^* \overline{N} \cap_{k=0}^n \dot{N} CInt^p I_{-i} C I_{U^-} IntI_{U \ni v} C T \overline{Int[x_p^* x_{p+1}] CIntI^+(q)CIntI_j} = \\ T_{\lambda}^* \overline{N}(p) \cap_{k=0}^n \dot{N} CInt^p I_{-i} C I_{U^-} \cap C T \overline{Int[x_p^* x_{p+1}] T \overline{Int}_{U \ni v} \cap IntV \ni N \in IntI_{\overline{U}} \in CI^-(q) CIntI_j} = \\ \cap T \overline{Int[x_p^* x_{p+1}] T \overline{Int}_{U \ni v} \cap_{k=0}^n T x_{[\overline{\omega}]_s} \overline{q} \ni IntV \ni N = T_{\lambda}^* \overline{N}(p) \cap_{k=0}^n \dot{N} CInt^p I_{-i} = IntI_{U \ni v} T_{\omega \dots, \omega}^* x^q \ni IntV \ni N = \\ IntI_{U \ni v} T_{[\omega \dots, \omega]_n}^* I_0^{\pm} = T_{\lambda}^* \overline{N}(p) \cap V. \end{aligned}$$