

# Understanding track fitting options

Artem Ivanov

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# Initial conditions

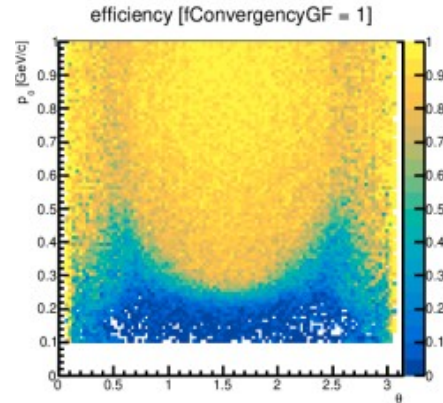
## Generated sample

$\phi$  90 degree

$\theta \in [0-90]$  degree

$p \in [0.1; 1.0, \text{step}=0.05 \text{ GeV}]$

positive pions



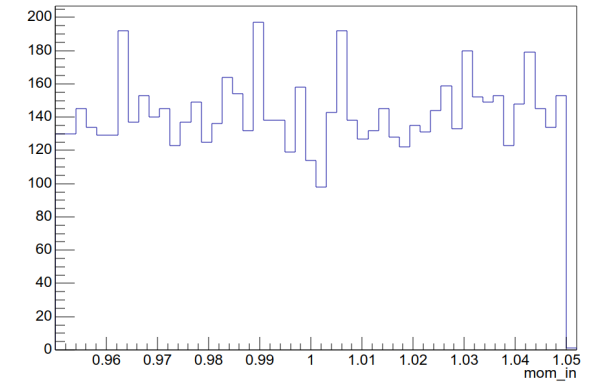
GetConvergency() (*Class SpdTrackFitPar*)

0 = fit not convergency

-1 = fit converged partially

1 = fit converged fully No failed hits

Initial momentum to GenFit2

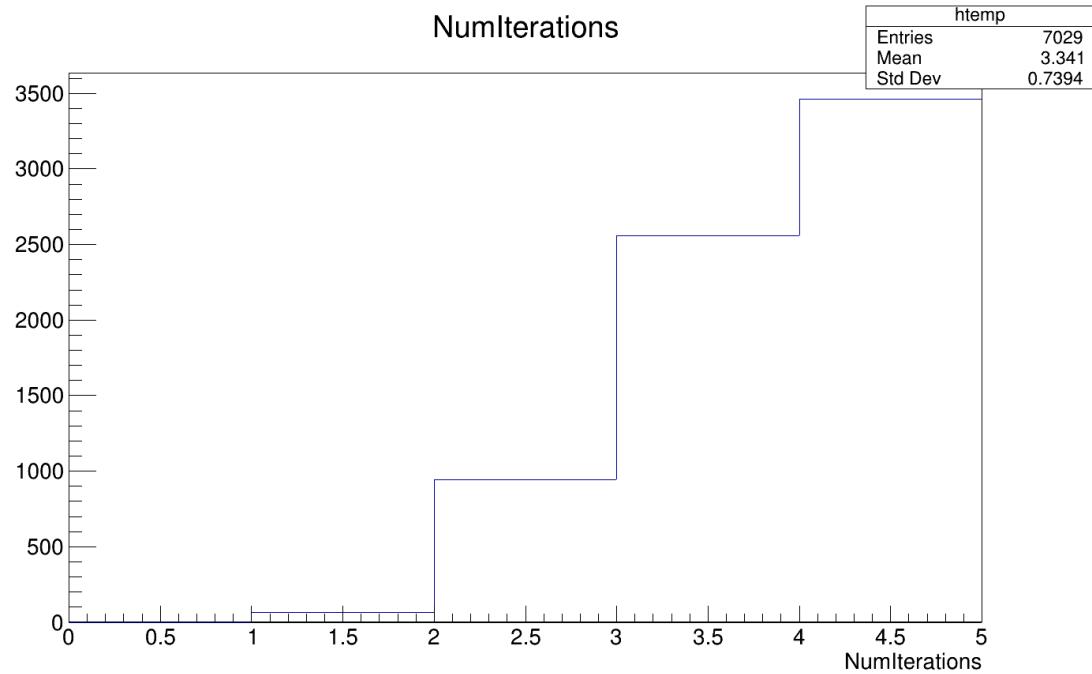


The fitter has a minimum and maximum number of iterations, which are 2 and 4 by default. As soon as the minimum number of iterations have been done, it is checked if the p-value has changed less than  $1 \times 10^{-3}$  with respect to the previous iteration. However, tracks with a p-value close to zero are often considered as “converged” with this criterion, while the  $\chi^2$ , albeit big, is still changing significantly, indicating that the fit is still improving. This occurs often for tracks which are given bad start values. To cure this issue, a non-convergence criterion has been introduced: If the relative change in  $\chi^2$  from one iteration to the next is bigger than 20 %, the fit will continue.

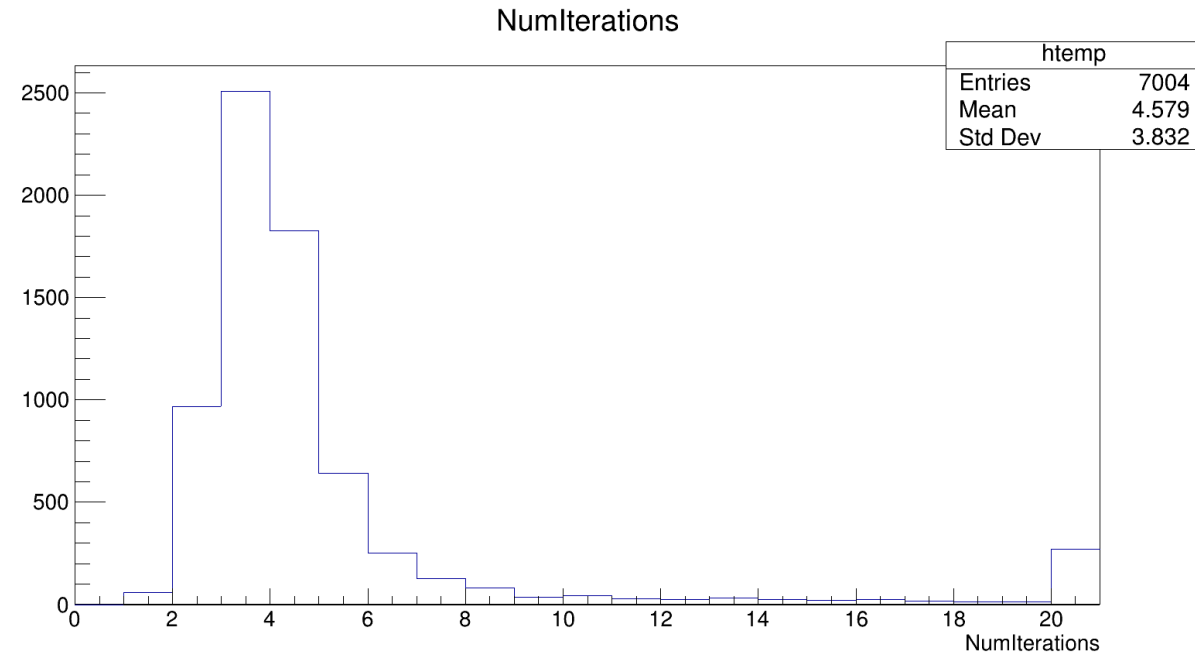
The number of iterations and convergence criteria values can be adjusted by the user.

# Number iterations

MinIterations = 1    default  
MaxIterations = 4



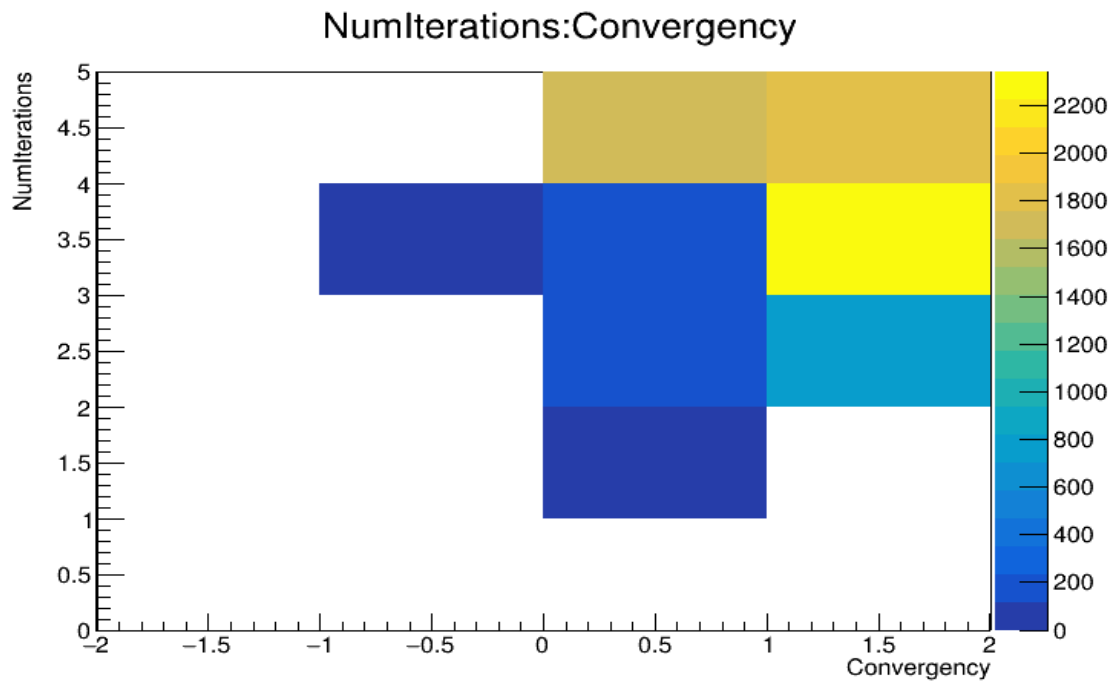
MinIterations = 1  
MaxIterations = 20    extended



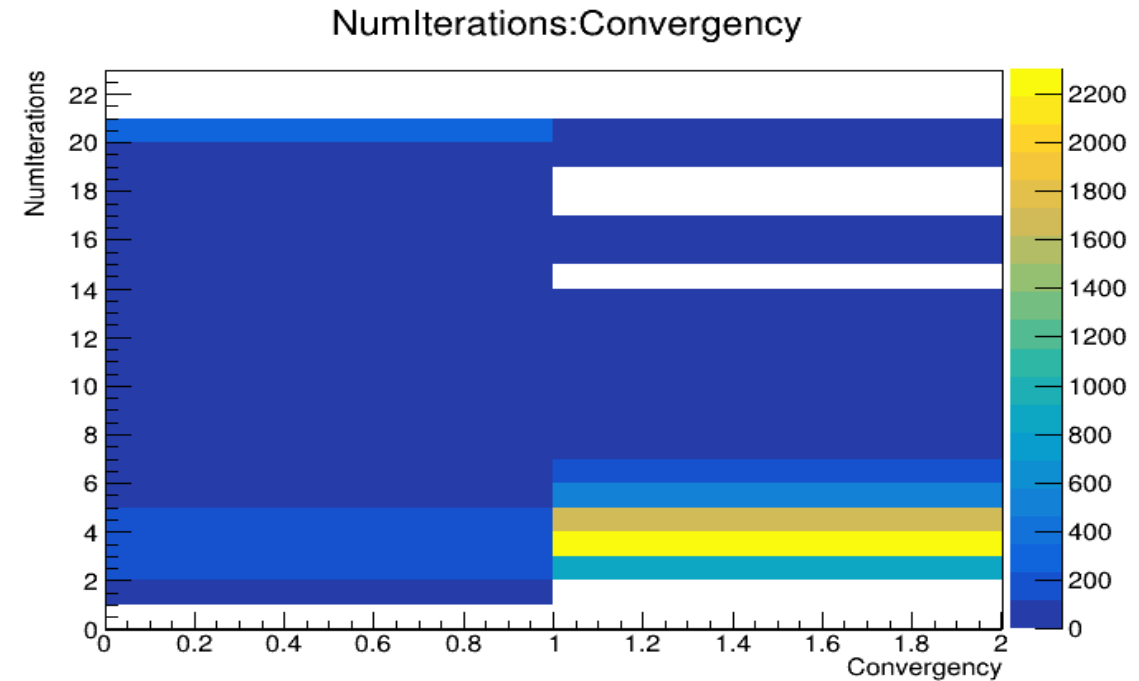
# Number iterations vs convergence

MinIterations = 1    default  
MaxIterations = 4

MinIterations = 1    extended  
MaxIterations = 20



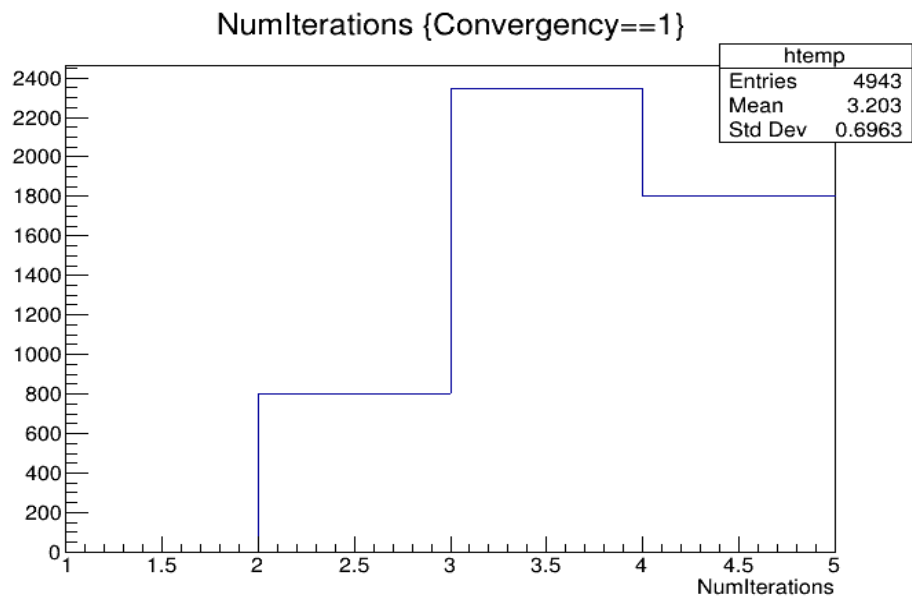
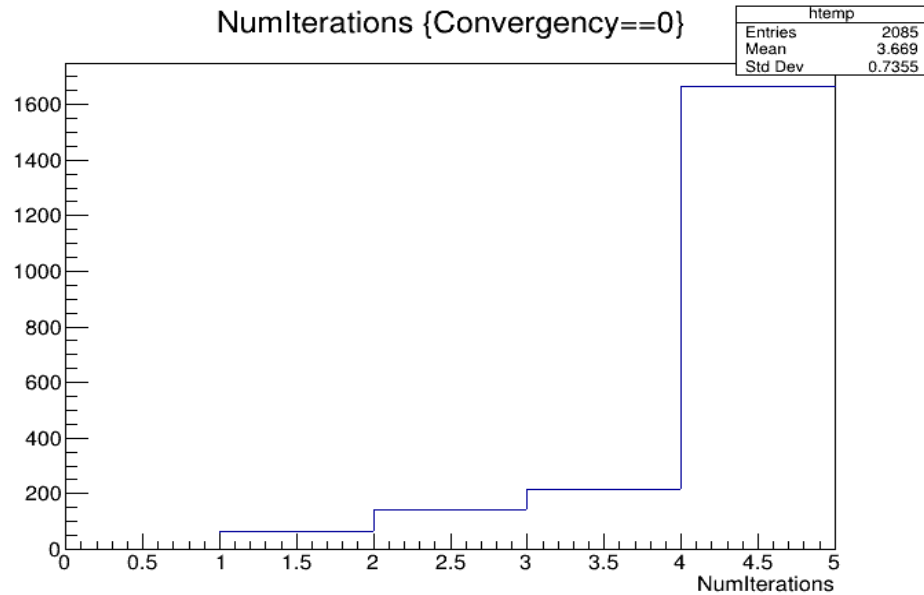
Convergency = 1: **70%**  
Convergency = 0: **29%**  
Convergency = -1: **1%**



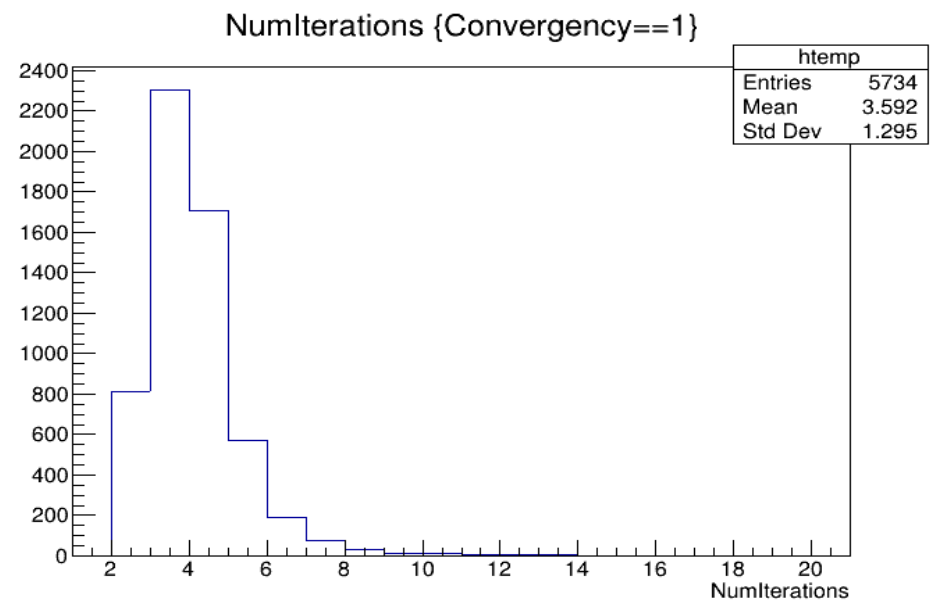
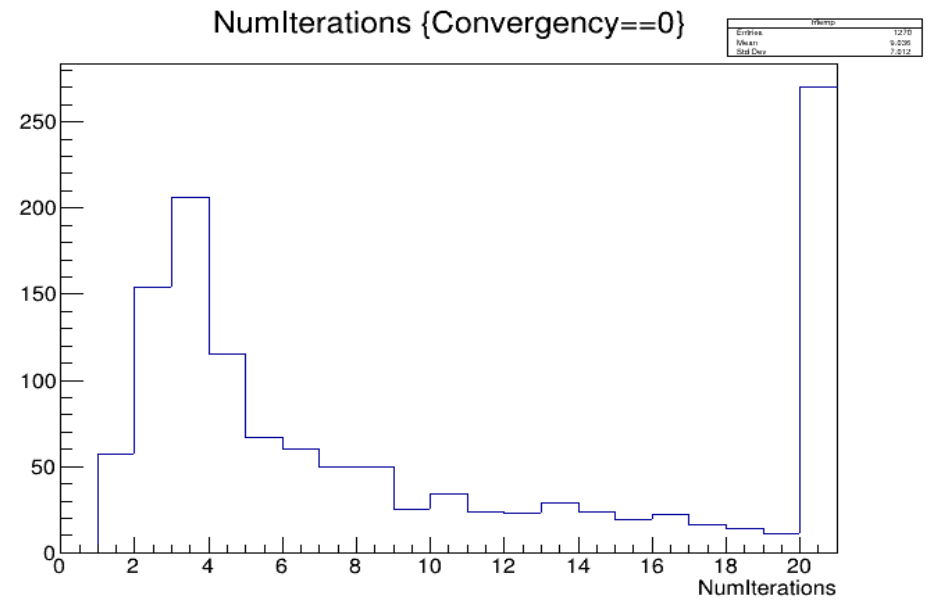
Convergency = 1: **81%**  
Convergency = 0: **19%**

# Convergence

MinIterations = 1    default  
MaxIterations = 4



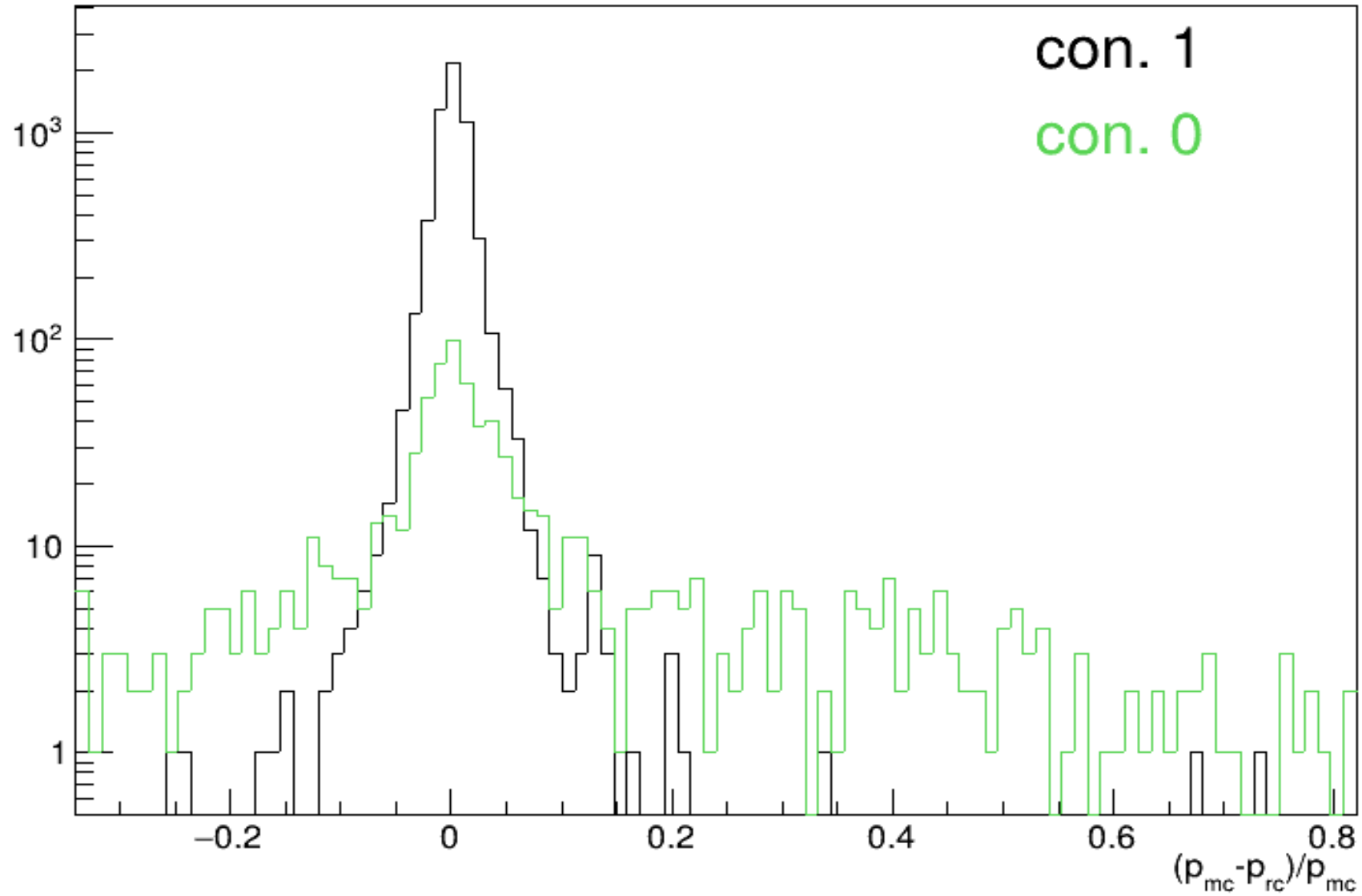
MinIterations = 1    extended  
MaxIterations = 20



# Resolution

MinIterations = 1  
MaxIterations = 20

extended



# Conclusion

- The relationship between the number of iterations and the parameter convergency was studied
- Using the default settings, minimum (1) and maximum (4) number of iterations we lost 30% tracks
- If maximum number of iterations will increase to 20, we lost 19% tracks