# **Centrality determination methods in heavy-ion collisions at the BM@N experiment**

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### **Centrality**

- Evolution of matter produced in heavy-ion collisions depend on its initial geometry
- Centrality procedure maps initial geometry parameters with measurable quantities (multiplicity or energy of the spectators)
- **This allows comparison of the future BM@N results with the data from other experiments (STAR BES, NA49/NA61 scans) and theoretical models**

$$
c(b) = \frac{\int_0^b \frac{d\sigma}{db'}db'}{\int_0^\infty \frac{d\sigma}{db'}db'} = \frac{1}{\sigma_{A-A}} \int_0^b \frac{d\sigma}{db'}db
$$







- A number of produced protons is stronger correlated with the number of produced particles (track & RPC+TOF hits) than with the total charge of spectator fragments (FW)
- to suppress self-correlation biases, it is necessary to use spectators fragments for centrality estimation

#### **Centrality determination in the FIX-target experiments**



Reference multiplicity distributions (black markers) in the kinematic acceptance within  $-0.5 < y < 0$  and  $0.4 < pT < 2.0$  GeV/c, GM (red histogram), and single and pile-up contributions from unfolding. do/dN [mb] **HADES** Data min. bias Au+Au 1.23 AGeV Data central (PT3) GlauberMC  $\times$  NBD( $\mu$ ,  $k$ )  $\times$   $\varepsilon(\alpha)$  $\mu$ =0.24,  $k$ =20.34,  $\alpha$ =-1.10e-07  $10^2$ 20-30% 10-20% 40-50% 30-40%  $-60\%$  $0 - 10%$  $10$  $10^{-1}$  $10<sup>7</sup>$ 20 60 80 40 100  $\Omega$  $N_{\rm tracks}$ 

The cross section as a function of Ntracks for minimum bias (blue symbols) and central (PT3 trigger, green symbols) data in comparison with a fit using the Glauber MC model (red histogram).

<https://arxiv.org/abs/2112.00240>

### **Centrality determination in BM@N**



Relation between impact parameter and track multiplicity

### **The Bayesian inversion method (Γ-fit): DCM-QSM-SMM based**

. The fluctuation kernel for multiplicity at fixed impact

parameter can be describe by Gamma distr.:

**The Bayesian inversion method (F-fit):**  
\nuctuation kernel for multiplicity at fixed impact  
\neter can be describe by Gamma distr.:  
\n
$$
P(M \mid c_b) = \frac{1}{\Gamma(k(c_b))\theta^2} M^{k(c_b)-1} e^{-M/\theta}
$$
\n
$$
c_b = \int_0^b P(b')db' - \text{centrality based on} \text{impact parameter}
$$
\n
$$
\theta = \frac{D(M)}{\langle M \rangle}, \quad k = \frac{\langle M \rangle}{\theta} \qquad \langle M' (c \text{div})
$$
\n
$$
D(M)
$$
\n
$$
D(M) - \text{average and variance of Multiplicity} \qquad \text{car}
$$
\n
$$
\text{exf}
$$

$$
\theta = \frac{D(M)}{\langle M \rangle}, \quad k = \frac{\langle M \rangle}{\theta} \qquad \langle M'(\mathcal{C}_b) \rangle \qquad -
$$

 $\langle M \rangle$ ,  $D(M)$  – average and variance of Multiplicty

$$
P(M) = \int_{0}^{1} P(M \mid c_{b})dc_{b}
$$

$$
CM-QSM-SMM based
$$
\n
$$
P(M) = \int_{0}^{1} P(M \mid c_{b})dc_{b}
$$
\n
$$
\langle M \rangle = m_{1} \cdot \langle M' \rangle
$$
\n
$$
D(M) = m_{1}^{2} \cdot D(M') + m_{1} \cdot m_{2} \langle M' \rangle
$$

 $\langle M'(\overline{c}_b^-)\rangle$  average value and var. of energy/mult.  $(M\,{}^{\prime}(c_{_b}))\quad$  from the rec. model data  $D(M$  ' $(c_{_b}))$  from the re

• can be approximated by polynomials and exponential polynomial

#### **Probabilistic model of pileup**

 $M_{pu}(b_1, b_2)$  =  $M_1(b_1)$  +  $M_2(b_2)$  - pileup as two independent events, with impact parameters  $b_1$ , $b_2$ 

 $M_{pu}(b_1, b_2)$  =  $\langle M_1(b_1) \rangle + \langle M_2(b_2) \rangle$ ,  $D(M_{pu}(b_1, b_2)) = D(M_1(b_1)) + D(M_2(b_2))$ 

$$
P_{pu}(M_{pu} | b_1, b_2) = \frac{1}{\Gamma(k_p) \theta_p^2} M_{pu}^{k_p - 1} e^{-M_{pu}/\theta_p}
$$

 $\mathcal{L}_{p-1}$ <sub>p</sub> $\mathcal{L}_{p}$ <sup>- $M_{pu}/\theta_p$ </sup> . The fluctuation of multiplicity can be describe by Gamma distribution

$$
\theta_p = \frac{D(M(b_1, b_2))}{\langle M(b_1, b_2) \rangle}, \quad k_p = \frac{\langle M(b_1, b_2) \rangle}{\theta_p}
$$
 . The parameter

 $=\frac{\sqrt{M}\left(\frac{U_{1},U_{2}}{U_{1}},\frac{U_{2}}{U_{2}}\right)}{M}$  . The parameters of Gamma distribution

 $P_{_{\mu\nu}}(M_{_{\mu\nu}})$  – the probability distribution of pileup can be calculated as

$$
P_{pu}(M_{pu}) = \int_{0}^{b_{\text{max}}} \int_{0}^{b_{\text{max}}} P(M_{pu} | b_1, b_2) P(b_1) P(b_2) db_1 db_2 = \int_{0}^{c_{b1}c_{b2}} \int_{0}^{c_{b2}} P_{pu}(M_{pu} | c_{b1}, c_{b2}) dc_{b1} dc_{b2}
$$

#### **Corrections for efficiency and pileup**

• **Correction for efficiency of normalized multiplicity distribution P(M)**

**Corrections for efficiency and pileup**  
\nction for efficiency of normalized multiplicity distribution P(M)  
\n
$$
P(M) = \frac{dN}{dM} / N_{ideal}^{ev} \left( \frac{N_{raw}^{ev}}{N_{ideal}^{ev}} \right) \frac{1}{N_{raw}^{ev}} \frac{dN_r}{dM} = \frac{1}{K} \cdot Norm. History
$$
\n
$$
Eff = \frac{N_{raw}^{ev}}{N_{ideal}^{ev}} = \frac{1}{K}
$$
\nintercept integration in the original efficiency  
\n
$$
\text{Fit function for multiplicity distribution P(M)}
$$
\n
$$
M = K \cdot P_{total}(M), \quad P_{total}(M) = N_p \cdot P_{pu}(M) + (1 - N_p) \cdot P(M)
$$
\n
$$
E(M) = E(M) \cdot \text{Fit function, corrected for efficiency and nilsum}
$$

• **Fit function for multiplicity distribution P(M)**

$$
F(M) = K \cdot P_{total}(M), P_{total}(M) = N_p \cdot P_{pu}(M) + (1 - N_p) \cdot P(M)
$$

- fit parameters, *F*  $P_{total}(M) = N_p \cdot P_{pu}(M) + (1 - N_p) \cdot P(M)$ <br>*F*  $(M)$  – fit function, corrected for efficiency and pileup  $m_{\text{\tiny 1}}^{} , m_{\text{\tiny 2}}^{} , K , N_{\text{\tiny p}}^{}$ - fit parameters,

### **Fit results**



Vertex Cuts: CCT2,  $N_{vtxTr} > 1, |V_{x,y} - (0.3,0.14)| < 1$  cm,  $|V_{z} - 0.07| < 0.2$  cm Good agreement with fit Track selection: Nhit>4, η<3, Pt>0.05 GeV/c

### **The Bayesian inversion method (Γ-fit): 2D fit**

. The fluctuation kernel for energy and multiplicity at fixed

impact parameter can be describe by 2D Gamma distr.:

$$
P(E, M \mid c_{b}) = G_{2D}(E, M, \langle E \rangle, \langle M \rangle, D(E), D(M), R)
$$

– centrality based on  $\int_0^{\infty}$  impact parameter  $(b^{\cdot})db^{\cdot}$  – centi *b*  $b^c{}_b = \int P(b')db'$  - centrality based on **The Bayesian i**<br>
The fluctuation kernel for energy and multiplic<br>
mpact parameter can be describe by 2D Gamm<br>  $E, M \mid c_b$  =  $G_{2D}(E, M, \langle E \rangle, \langle M \rangle, D(E), L$ <br>  $c_b = \int_0^b P(b')db'$  -- centrality based or<br>  $E$ ,  $D(E)$  -- average value **Example 3**<br>
ergy and multiplic<br>
cribe by 2D Gamn<br>  $\langle \rangle, \langle M \rangle, D(E), I$ <br>
centrality based of<br>
npact parameter<br>
and variance of example and variance of r<br>
tion coefficient<br>  $\frac{E'D(M')}{(E)D(M)}$ **The Bayesian inversic**<br> **CETTE:** The fluctuation kernel for energy and multiplicity at fixed<br>
impact parameter can be describe by 2D Gamma distr.:<br>  $P(E,M | c_b) = G_{2D}(E,M,\langle E \rangle, \langle M \rangle, D(E), D(M), R)$ <br>  $c_b = \int_0^b P(b')db'$  — centrality bas *D E D M*

 $\langle E \rangle$ ,  $D(E)$  – average value and variance of energy

 $\langle M \rangle$ ,  $D(M)$  – average value and variance of mult.

– Pirson correlation coefficient

 $E'(c_{\mu})\rangle$  average value and var. of energy/mult.  $(E'(c_{_b}))$  from the rec. model data  $\langle E\prime(c_{_b})\rangle$  $D(E^{\, \prime}(c_{_b}))$  from the r

$$
\langle E \rangle = \varepsilon_1 \langle E'(c_b) \rangle + \varepsilon_0, \quad D(E) = \varepsilon_2 D(E'(c_b))
$$
  

$$
\langle M \rangle = m_1 \langle M'(c_b) \rangle, \quad D(M) = m_1^2 \cdot D(M') + m_1 \cdot m_2 \langle M' \rangle
$$

 $\langle E^{\prime}(c_{_{b}}) \rangle$ ,  $\langle D(E^{\prime}(c_{_{b}})) \rangle$  - can be approximated by polynomials

**Example 1** The Bayesian inversion method (F-fit): 2D fit  
\nThe fluctuation Kernel for energy and multiplicity at fixed  
\nimpact parameter can be describe by 2D Gamma distr.:  
\n
$$
P(E,M | c_b) = G_{2D}(E,M,\langle E \rangle, \langle M \rangle, D(E), D(M), R)
$$
  
\n $C_b = \int_0^b P(b')db'$  - centrality based on  
\n $E(\langle E, \rangle)$  (where  $E(\langle E, \rangle) + E_b$ ,  $D(E) = \varepsilon_1 D(E(c_b))$   
\n $C_b = \int_0^b P(b')db'$  - centrality based on  
\n $\langle E \rangle$ ,  $D(E)$  - average value and variance of energy  
\n $\langle E' \rangle$ ,  $D(E'(\langle E, \rangle))$ ,  $D(E'(\langle E, \rangle))$  - can be approximated by polynomials  
\n $\langle M \rangle$ ,  $D(M)$  - average value and variance of the  
\n $\langle E' \rangle$ ,  $D(E'(\langle E, \rangle))$  -  $\sum_{j=1}^{12} a_j c_b^j$ ,  $D(E' \langle E, \rangle) = \sum_{j=1}^{19} b_j c_b^j$   
\n $R(E,M)$  - Pirson correlation coefficient  
\n $\langle E' \langle E, \rangle \rangle = \sum_{j=1}^{12} a_j c_b^j$ ,  $D(M' \langle E, \rangle) = \sum_{j=1}^{19} b_j c_b^j$   
\n $R(E,M) = \varepsilon_1 \cdot m_1 \cdot R(E'M) \sqrt{\frac{D(E')D(M)}{D(E)D(M)}}$  - fit parameters

#### **2D Gamma distribution**

It is possible to find such a rotation angle of the system that

Then the two-dimensional distribution in the new coordinate system will be

**2D Gamma distribution**  
to find such a rotation angle of the system that 
$$
cov(x, y) = 0
$$
  
to-dimensional distribution in the new coordinate system will be  

$$
G_{2D}(E_{FH}, M_{ch}, \langle E \rangle, \langle M \rangle, D(E), D(M), R) = G(x, \theta_x, k_x) \cdot G(y, \theta_y, k_y)
$$

$$
G(x, \theta_x, k_x) \cdot G(y, \theta_y, k_y) = \frac{(x)^{k_x(c_b)-1} e^{-x/\theta_x}}{\Gamma(k_x(c_b))\theta_x^2} \cdot \frac{(y)^{k_y(c_b)-1} e^{-y/\theta_y}}{\Gamma(k_y(c_b))\theta_y^2}
$$

$$
\theta_x = \frac{D(x)}{\langle x \rangle}, \quad k_x = \frac{\langle x \rangle^2}{D(x)}, \quad \theta_y = \frac{D(y)}{\langle y \rangle}, \quad k_y = \frac{\langle y \rangle^2}{D(y)}
$$
\n
$$
\alpha = \arctan\left(\frac{2\sqrt{D(E)D(M)}R(E,M)}{D(E) - D(M)}\right)
$$

The distribution of energy and multiplicity at a fixed impact parameter is well described by the gamma distribution



*EFH*

*y*

### **2D fit results**



Good agreement between fit and data.

#### **Energy distribution**



Good agreement between fit and data.

# **Clusterization with k means for centrality classes**



the bivariate fit distribution was divided into 10 centrality classes

# **MC-Glauber based centrality framework**



## **Comparison with MC-Glauber fit**



There is agreement within 5%.  $15$ 

### **Summary and outlook**

- A new approach for efficiency and pileup correction was developed
- The Bayesian inversion method reproduce charged particle multiplicity for fixed-target experiment at BM@N
- A new approach for centrality determination with energy of spectators and multiplicity of charged particles was proposed
- The proposed method was applied to the data from BM@N experiment
	- results are consistent with the conventional MC-Glauber based approach
- It is planned to create a two-dimensional method based on a signal from a hodoscope and energy from the FHCal

# **Thank you for your attention!**

#### **2D Gamma distribution**

It is possible to find such a rotation angle of the system that

Then the two-dimensional distribution in the new coordinate system will be



mean value and variance in the new coordinate system

$$
\langle x \rangle = \cos(\alpha) \langle E \rangle + \sin(\alpha) \langle M \rangle \qquad D(x) = D(E) \cos(\alpha)^2 + R(E, M) \sqrt{D(E)D(M)} \sin(2\alpha) + D(M) \sin(\alpha)^2
$$
  

$$
\langle y \rangle = -\sin(\alpha) \langle E \rangle + \cos(\alpha) \langle M \rangle \qquad D(y) = D(E) \sin(\alpha)^2 - R(E, M) \sqrt{D(E)D(M)} \sin(2\alpha) + D(M) \cos(\alpha)^2
$$

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### **Dependence of the variance of multiplicity and energy on centrality**



Good fit quality and the set of the

### **Dependence of the average value of multiplicity and energy on centrality**



#### **Energy distr. fit**



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#### **Mult distr. fit**



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### **Impact parameter distribution for centrality classes**



### **The fluctuation of energy and multiplicity at fixed impact**



The distribution of energy and multiplicity at a fixed impact parameter is well described by the gamma distribution

 $\cdot$  Find probability of *b* for fixed range of E and M using Bayes' theorem:

$$
P(b | E_1 < E < E_2, M_1 < M < M_2) = P(b) \frac{\int_{E_1 M_1}^{E_2 M_2} P(E, M | c_b) dM dE}{\int_{E_1 M_1}^{S} \int_{0}^{M_2} P(E, M | c_b) dM dE d c_b}
$$

#### **Event cleaning**



#### **Event cleaning**



The most of the background has been suppressed after cuts for Erat >0.29 and vertex position (V<sub>x</sub>-0.3)<sup>2</sup>+(V<sub>y</sub>-0.14)<sup>2</sup><1 cm

### Event cleaning in HADES

#### **Segmented gold target:**

- $197$ Au material
- 15 discs of  $Ø = 2.2$  mm mounted on kapton strips

 $\vec{z}$ 

 $200 -$ 

 $150$ 

 $100$ 

50

- $\triangle$ z = 3.6 mm
- 2.0% interaction prob.



Kindler et al.. NIM A 655 (2011) 95



beam direction

30/11/2021 FANI-2021 | R. Holzmann (GSI) for the HADES collaboration

http://indico.oris.mephi.ru/event/221/session/1/contribution/1/material/slides/0.pdf <sup>27</sup>

 $\overline{3}$ 

# **NA61/SHINE experimental setup**

Data samples:

- Pb-Pb  $\omega$  p<sub>beam</sub> = 13A GeV/c
- data from 2016 physics run
- DCM-QGSM-SMM x Geant4 M.Baznat et al. PPNL 17 (2020) 3, 303

#### Subsystems

- Multiplicity: TPCs
- Spectators energy: PSD



# **Dependence of the average value and variance of energy on centrality**



The average value and dispersion of energy from the DCM-QGSM-SMM model are well described by polynomials

# **Reconstruction of** *b*

- Normalized energy distribution P(E)  $1$  and  $1$  and  $1$  and  $1$  and  $1$  and  $1$  $\overline{0}$  $P(E) = \int P(E | c_b) d c_b$
- Find probability of *b* for fixed range of E using Bayes' theorem:

$$
P(b \mid E_1 < E < E_2) = P(b) \frac{\int_{E_1}^{E_2} P(b \mid E) dE}{\int_{E_1}^{E_2} P(E) dE}
$$

• **The Bayesian inversion method consists of 2 steps:** –Fit normalized energy distribution with P(E) –Construct P(*b*|E) using Bayes' theorem with parameters from the fit



Good agreement between fit and data in wide energy range

## **Fit results for NA61**



The method reproduces the energy distribution well. The difference in the peripheral region is due to the trigger efficiency

# **Comparison with MC-Glauber fit**



Good agreement between fit and data. There is agreement within 5%.

# **Reconstruction of** *b*

• Normalized multiplicity distribution  $P(N_{ch})$ 

$$
P(N_{ch}) = \int_0^1 P(N_{ch}|c_b)dc_b
$$

**•** Find probability of *b* for fixed range of  $N_{ch}$  using Bayes' theorem:

$$
P(b|n_1 < N_{ch} < n_2) = P(b) \frac{\int_{n_1}^{n_2} P(N_{ch}|b) dN_{ch}}{\int_{n_1}^{n_2} P(N_{ch}) dN_{ch}}
$$

- **The Bayesian inversion method consists of 2 steps:**
- –Fit normalized multiplicity distribution with  $P(N_{ch})$
- –Construct  $P(b|N_{ch})$  using Bayes' theorem with parameters from the fit

