




JOINT INSTITUTE
FOR NUCLEAR RESEARCH



The issue of functional division of automated systems in experimental facilities

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Dubna, April 2024

AUTOMATION – MAIN IDEA



OPERATION DATA



CONTROL ROOM



CONTROL & ADJUSTMENT





Current design solutions in automation field

- CDR Conceptual design report MPD
- Shaped DAQ и DCS
- TDR technical design report only for DAQ



Current reporting on the status of works in automation field

- Unreported timebound and percentage about automated subsystems
- DAQ report mostly about hardware solutions
- Couldn't find the latest DCS report



Current understanding the scope of tasks in automation field

- What are the key expectations and functional requirements for automated systems?
- What architectural principles and structure components are envisaged for them?
- What manpower are necessary to to deploy and maintain automated systems?



Enterprise expectations



Max efficiency



Reduce exploitation costs



Trouble-free operation



Improve uptime



Management expectations



Streamlined training & staff flexibility



Correct shifter's actions, minimal mistakes



Reduced shifter's workload



Ensure shifter situation awareness



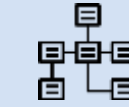
Reduce incident response time



Shifter's expectations



Intuitive recognizable user interface



Hierarchical & structured information



System response & alerts



Safety control, false action protection

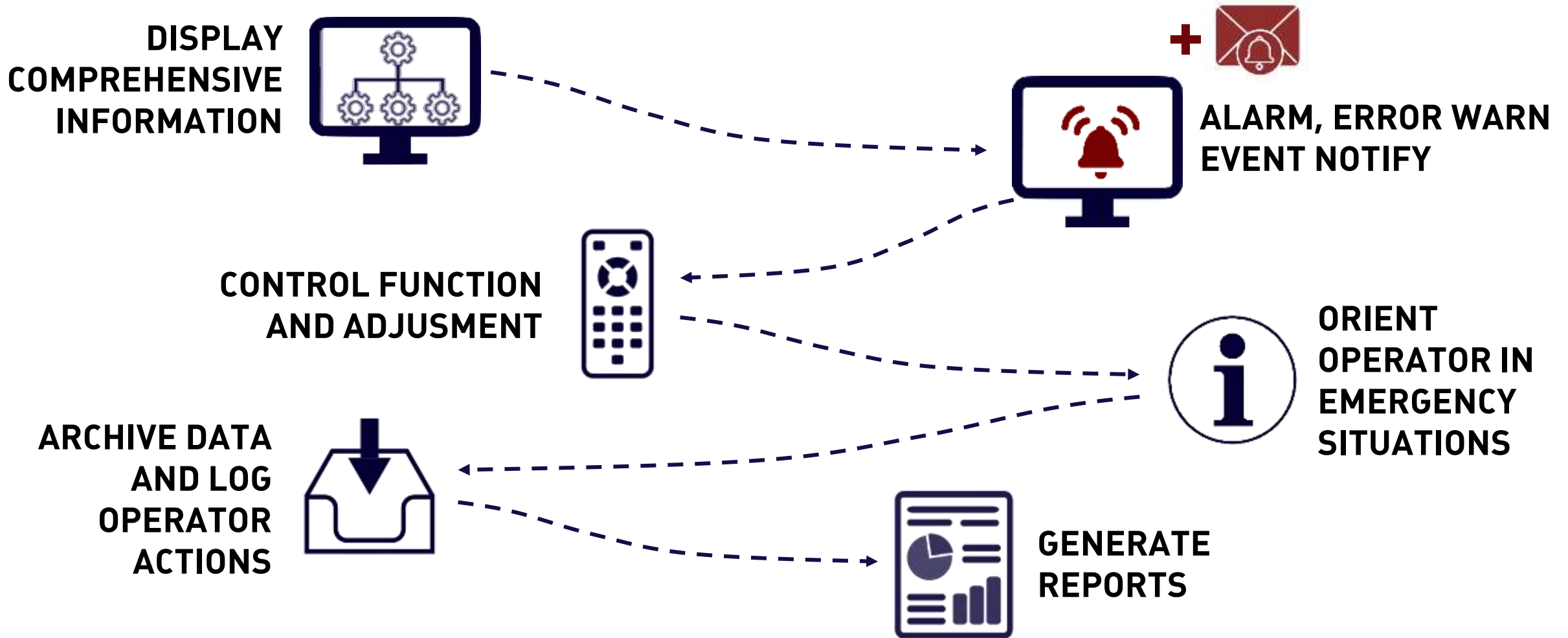


Flexibility & adjustments possibilities



Minimum routine

Functionality of Automated Systems



NEED TO DEFINE ARCHITECTURE SOLUTIONS



**Specified
staff team**



**Specified
shifter
work places**



**Functionality
division**

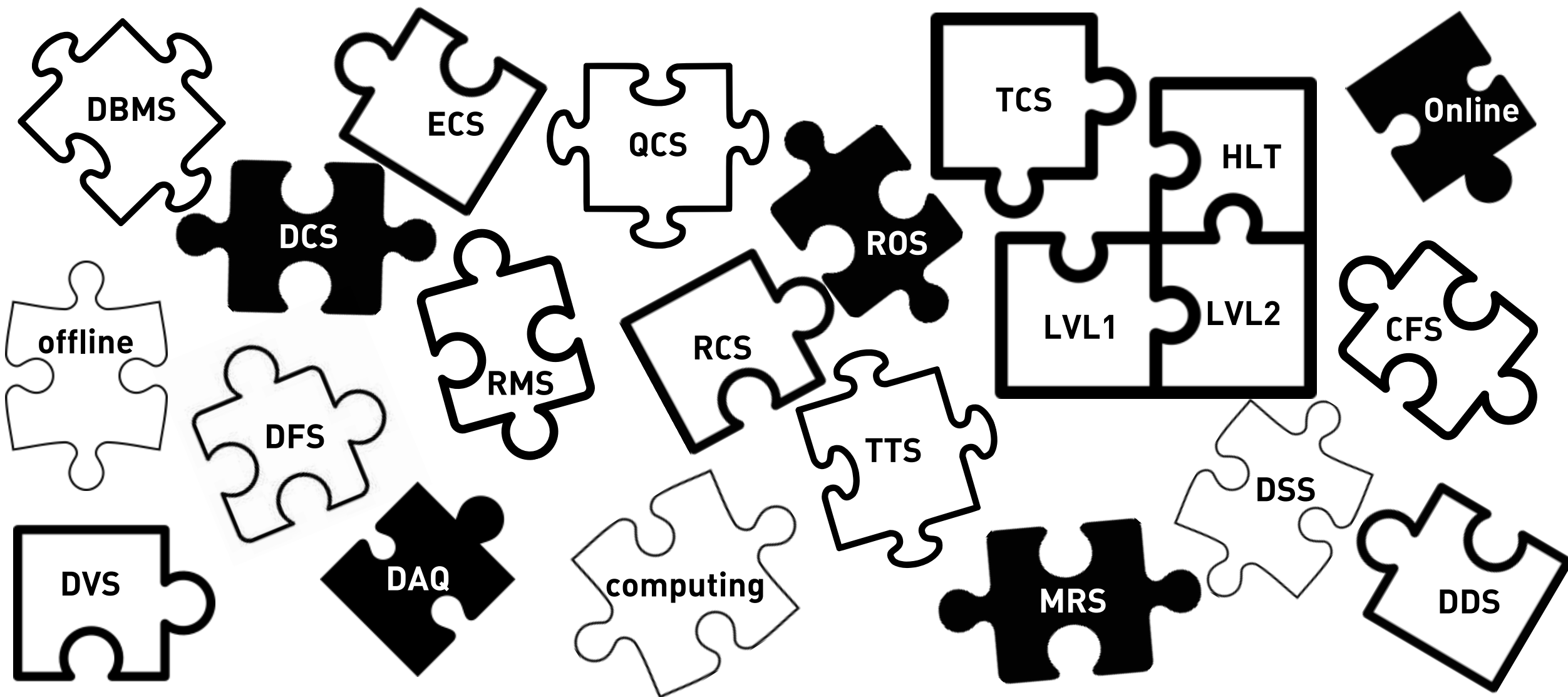


**Personalized
HMI/GUI**

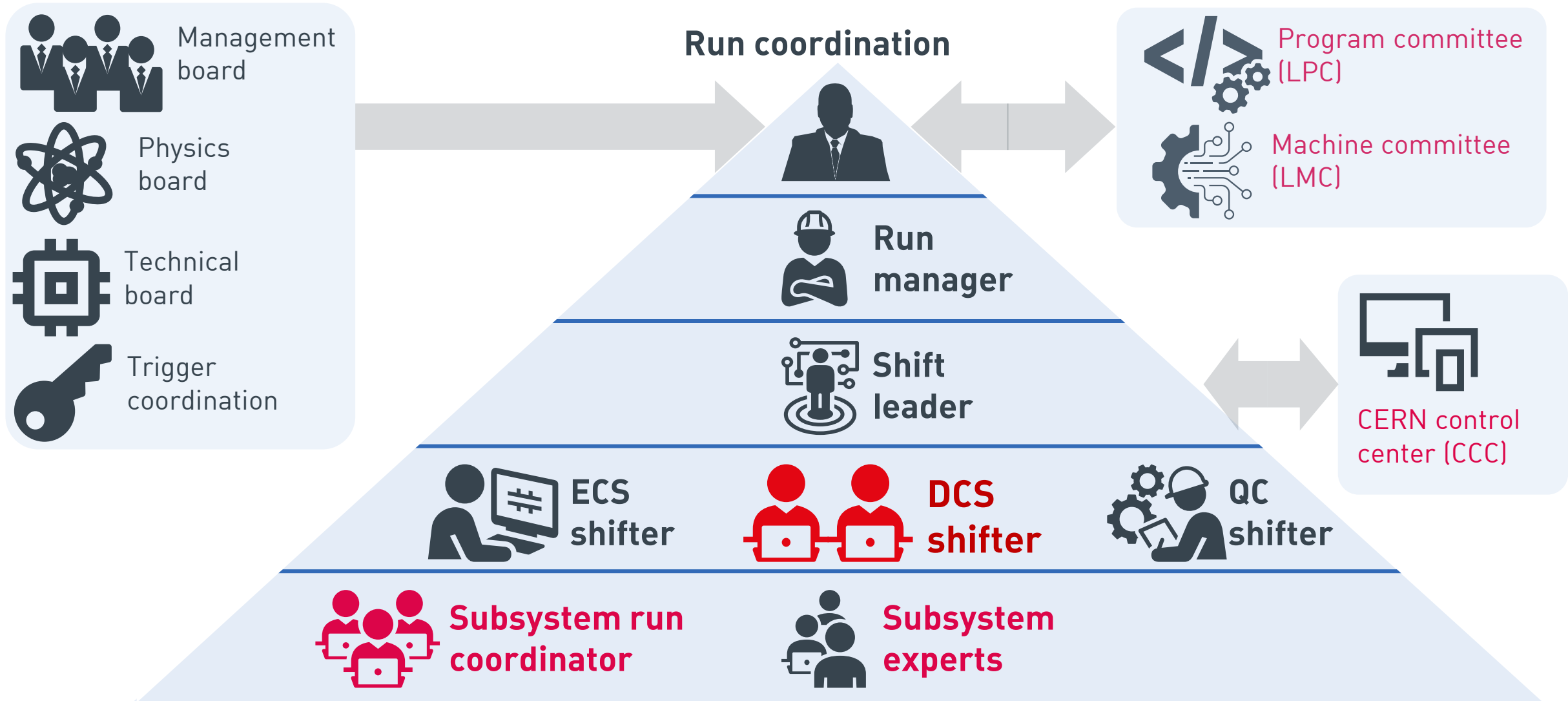


**Define
architecture**

Which division of automated system are needed?

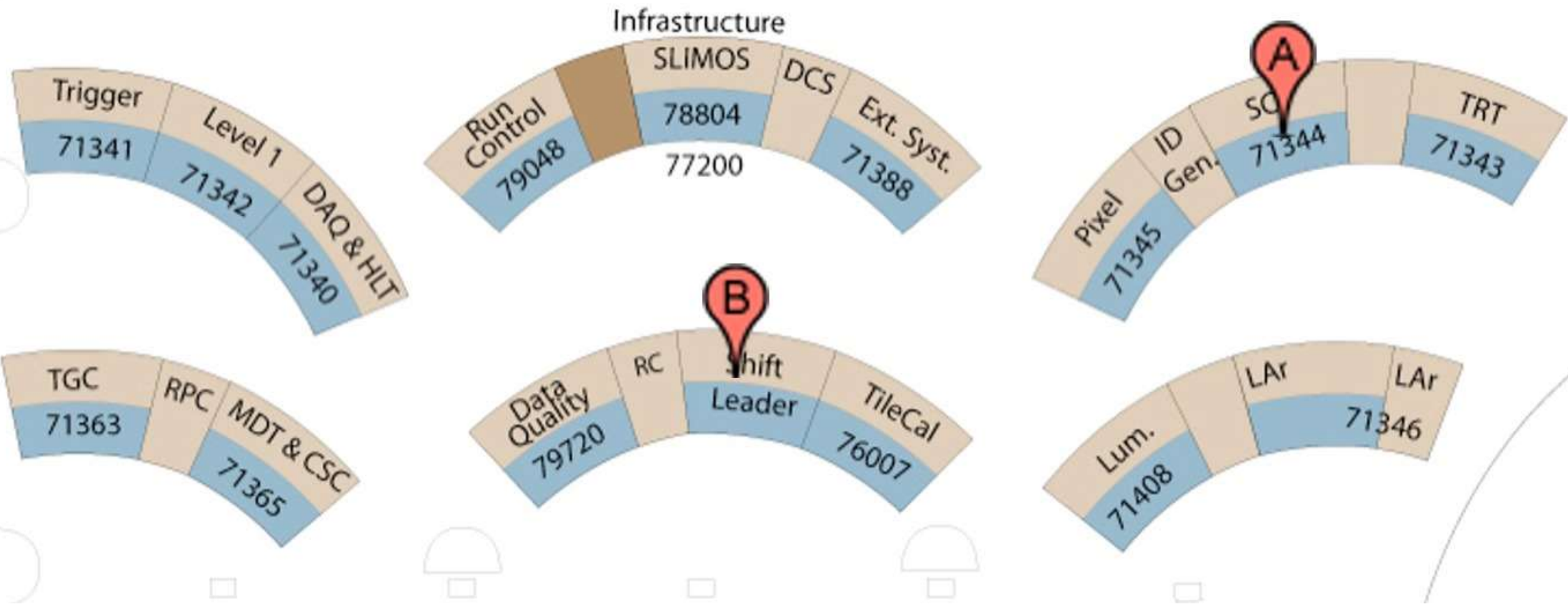


ALICE organization structure

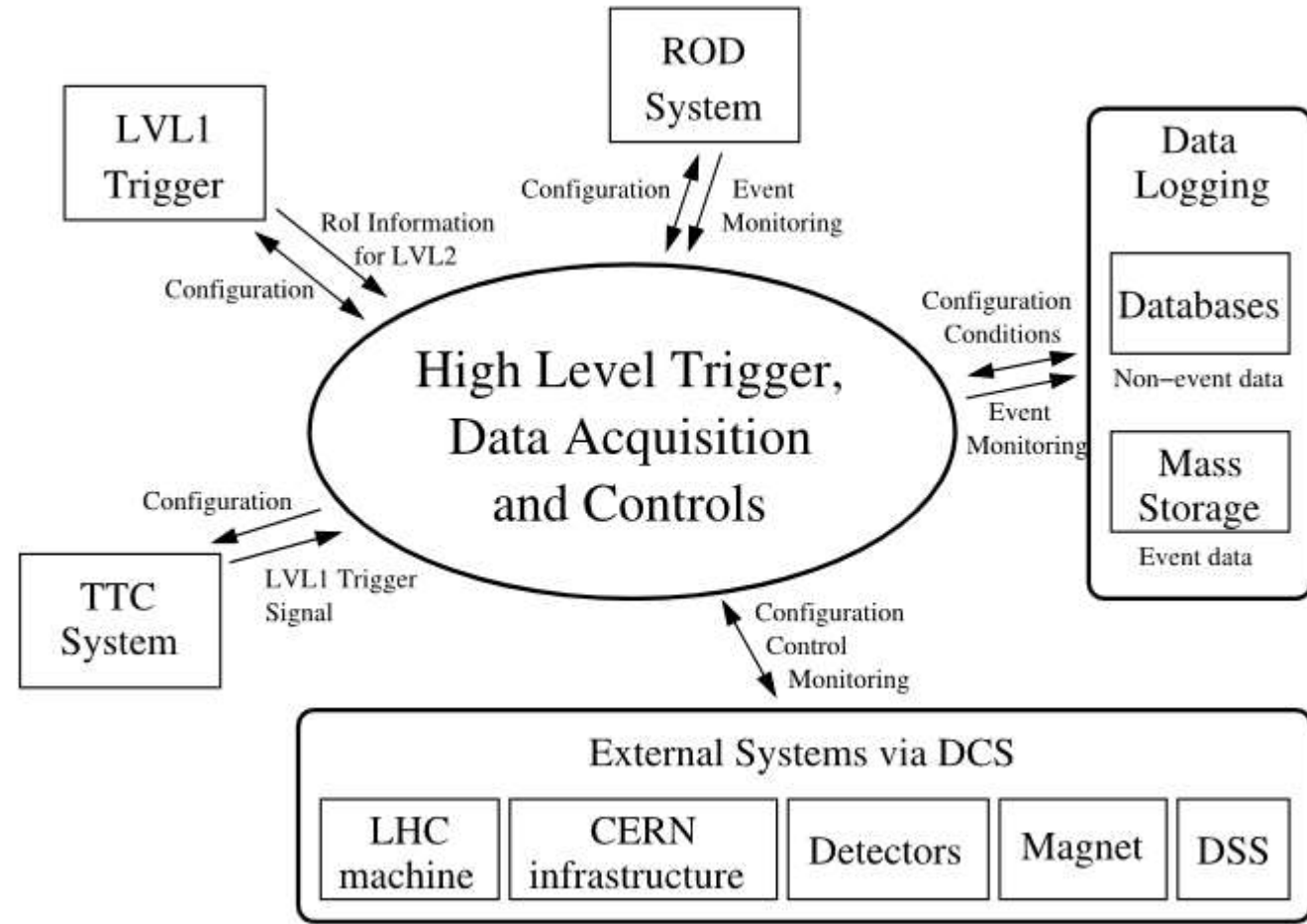
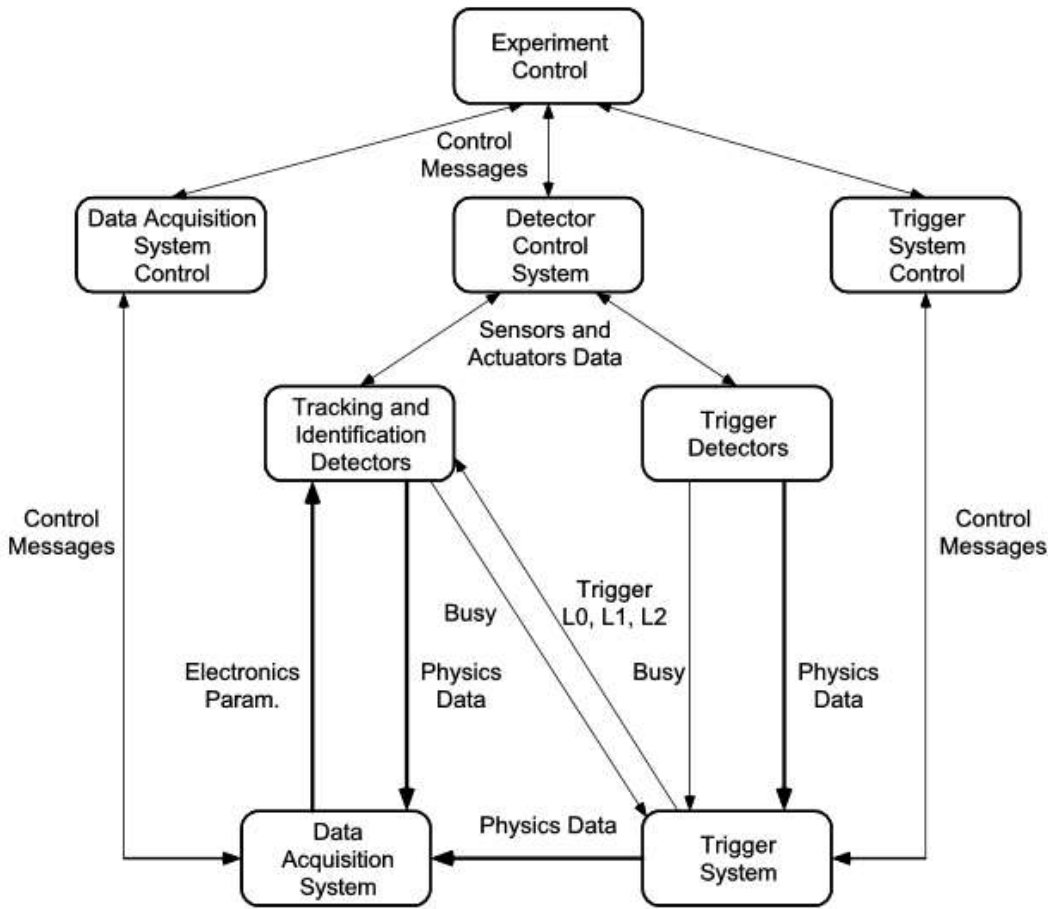


ATLAS CONTROL ROOM work areas

cy



Examples of structured diagrams



1.

Provide stable units operation



Ensure safety equipment

2.



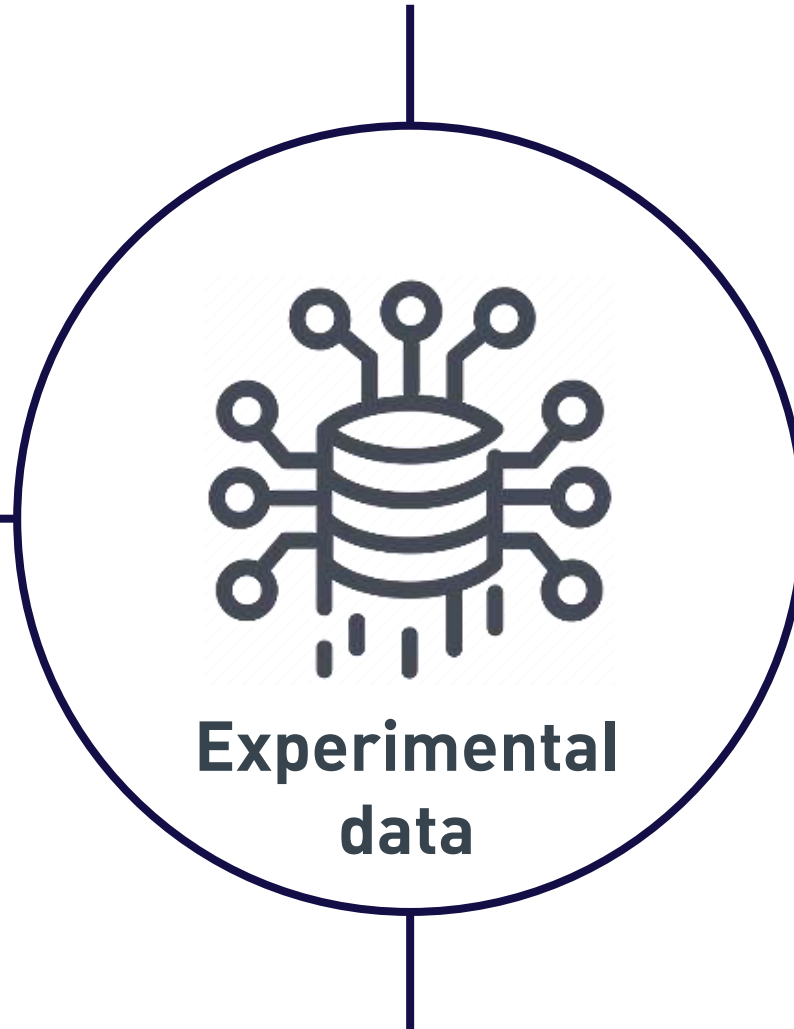
3.

Achieving highest output quality

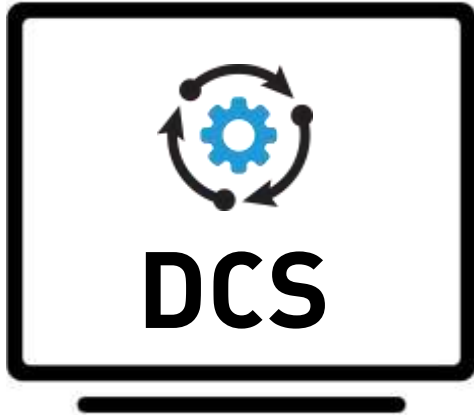


Providing an optimal operational mode

4.



Detector Control System



- Status equipment
- Parameters technology process
- Equipment operation modes

Detector Safety System



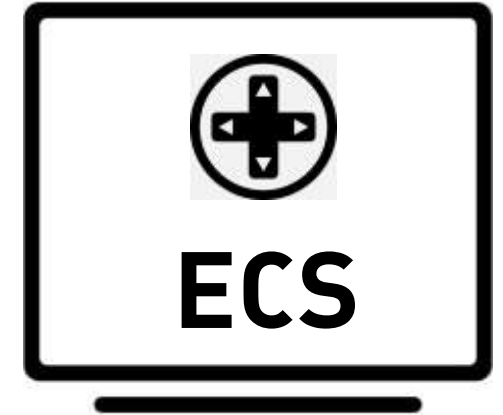
- Interlocks
- Setpoints
- Process protection
- Locks and blocks

Quality Control System



- RAW data
- Quality control
- Correct data

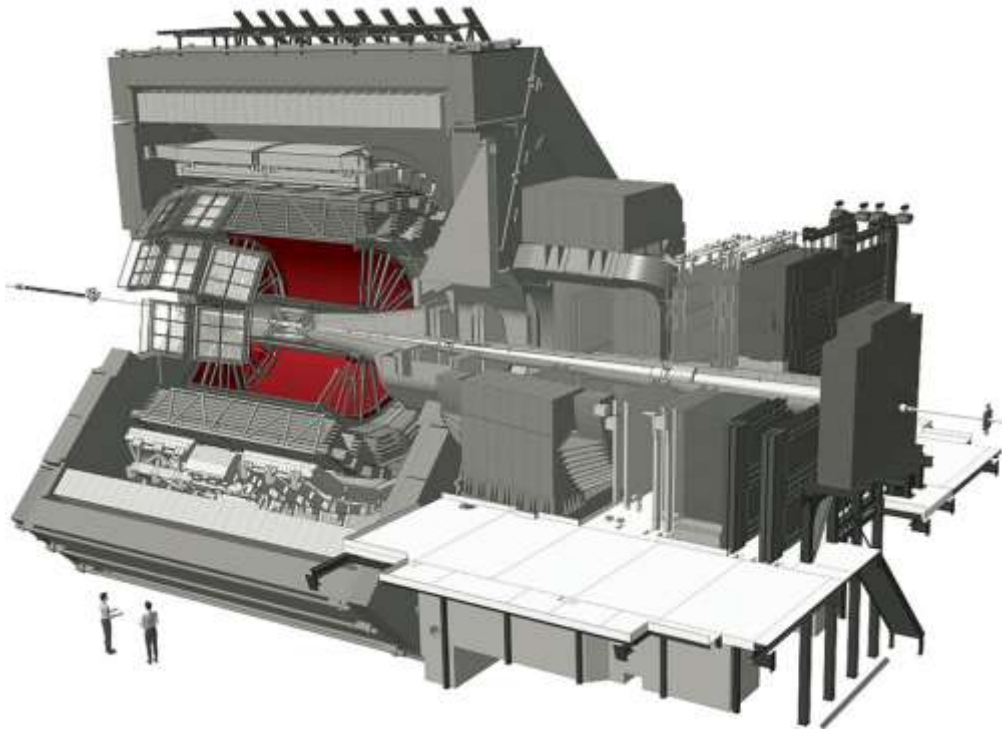
Experiment Control System



- Run start/stop
- Run coordination
- Run processing



at



Quantitative metrics:



1 control room



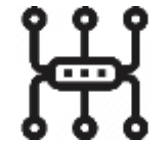
100 servers (WinCC OA)

*12 TPC servers



270 crates

*more 60 cabinets



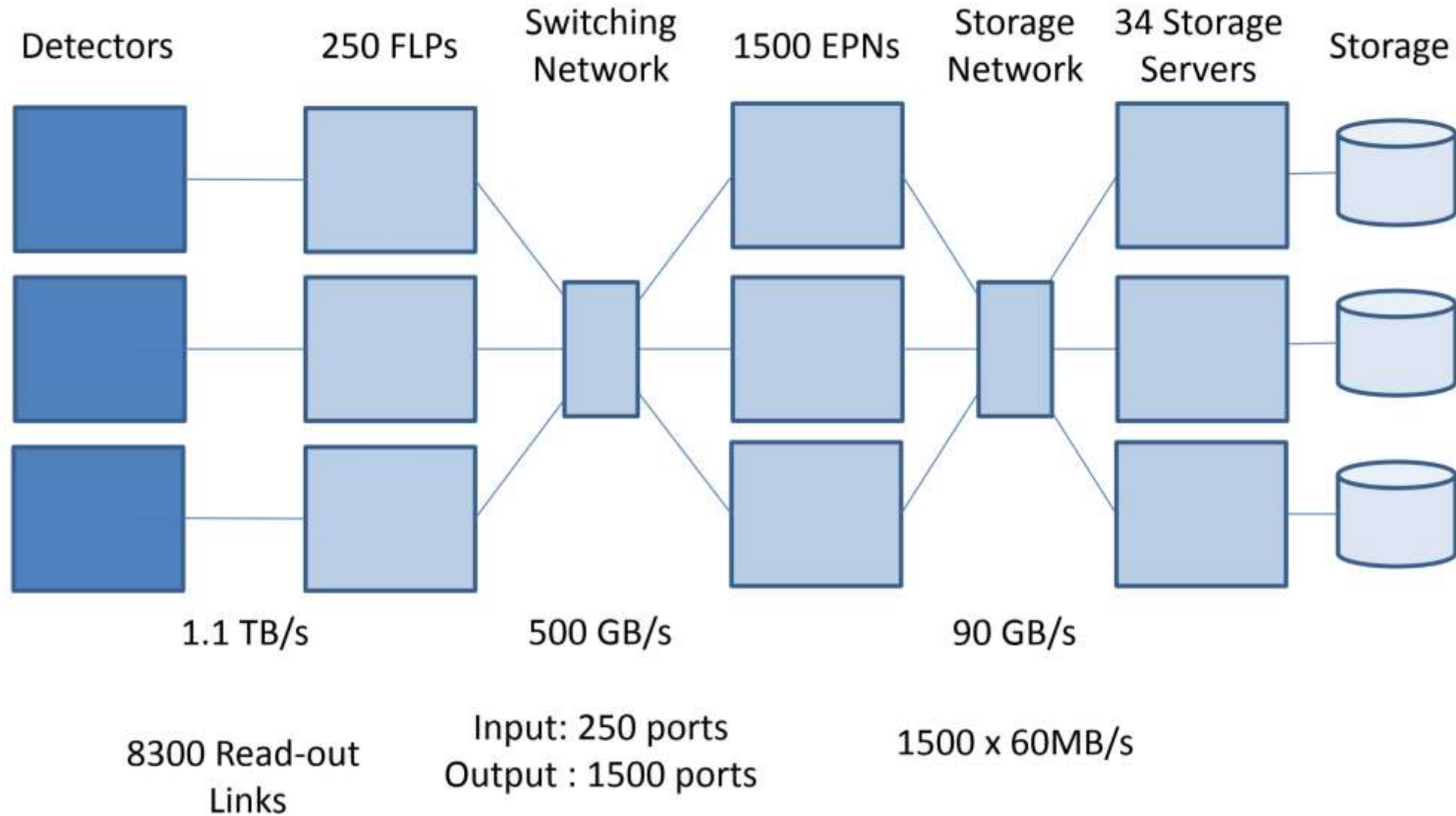
1.200 network-attached devices



3.000.000 parameters

*ATLAS 12.000.000

Some scale of readout system of ALICE



MPD TPC Subsystem list

MPD subsystems table - Google Sheets

docs.google.com/spreadsheets/d/1fjEBkOj7qYCt3u1sz7-asltUAho2ZE0xzWbuxqqO16Q/edit#gid=0

MPD subsystems table

File Edit View Insert Format Data Tools Extensions Help

75% 123 Default... 10 B I A

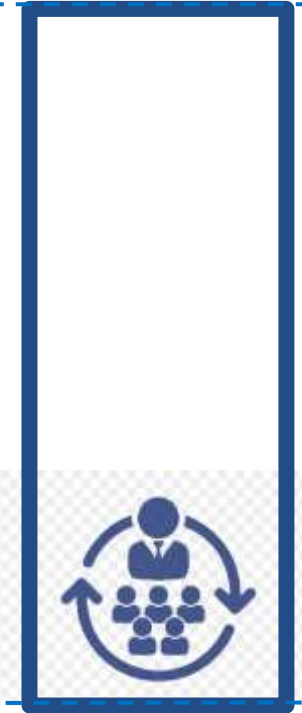
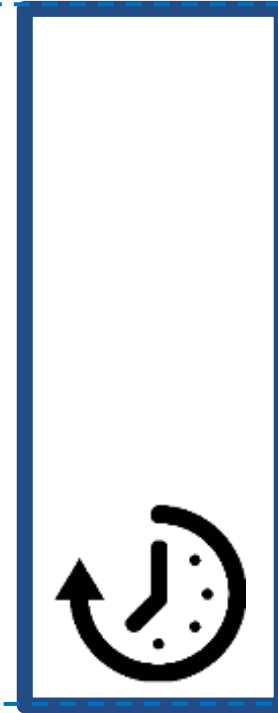
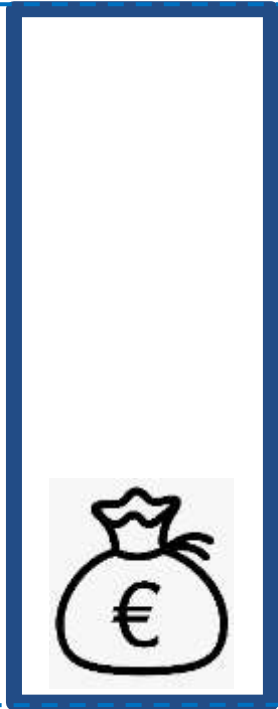
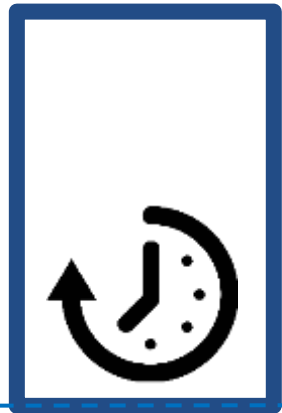
	A	B	C	D	E	F	G	H	I	J	K	L	M
1	№	system	KKS	subsystem group	subsystem name	full name	amount parameters	кол-во PLC	кол-во серверов		responsible	русское название	комментарий
2	1	TPC	00TPC01HVP001	power supply	ROC HV PS	Readout Chamber High Voltage power supply subsystem	10000	2	1		Фатеев О.В.		
3	2	TPC	00TPC01LVP001	power supply	ROC LV PS	Readout Chamber Low Voltage power supply subsystem	10000	2	1		Фатеев О.В.		
4	3	TPC	00TPC01HVP002	power supply	VHV	Central TPC electrode & field cage	?	?	?		Сердюк В.З.		
5	4	TPC	00TPC01LVP002	readout	FED	front-end electronic monitoring	30000	6	2		Верещанин С.В.		
6	5	TPC	00TPC01HVP003	readout	Pulsar	Calibration Pulsar	?	?	?		Верещанин С.В.	подача тестового сигнала на катодную плоскость	
7	6	TPC	00TPC01LVP003	power supply	GCG	Gating Grid Generator Power Supply	?	?	?		Мовчан С.А.		
8	7	TPC	00TPC01HVP004	laser	Laser	Laser and Beam monitoring/control	?	?	?		Лукин Ю.Ю., Аверьянов А.		
9	8	TPC	00TPC01LVP004	laser	Laser synchronization	Laser synchronization	?	?	?		Лукин Ю.Ю.		
10	9	TPC	00TPC01HVP005	readout	DVM	Drift Velocity Monitor (Goofer)	?	?	?		Бычков А.	функция лазерной системы	рознический, подфункция DA
11	10	TPC	00TPC01LVP005	termo	Temperatures	Temperature Monitoring System	500	1	1		Балашов И.А.		
12	11	TPC	00TPC01HVP006	termo	Cooling	Thermostabilisation System monitoring/control	1000	1	1		Балашов И.А.		
13	12	TPC	00TPC01LVP006	gas	GAS	Gas mixing subsystem	1000	1	1		Сердюк В.З.		
14	13	TPC	00TPC01HVP007	gas	GGM	gas gain monitor	500	1	1		Фатеев О.В.	контроль газового усиления в ROC камерах, контроль амплитудных спектров	
15	14	TPC	00TPC01LVP007	readout	TF	Trigger/synchronization fanout					Верещанин С.В.	размножитель триггерного сигнала и подсистема синхронизации всего оборудо	
16	15	TPC	00TPC01HVP008	readout	JTAG	JTAG commutator					Поталов Денис	подсистема перепрошивки FPGA	
17	16	TPC	00TPC01LVP008	power supply	LV FEE	Low Voltage of front-end electronics					Пятер А.		
18	17	SOC	00SOC01PSS001	power supply	PSS	power supply of superconductor solenoid					Мухин		
19	18	SOC	00SOC01VMS001	power supply	VMS	Voltage monitoring system							
20	19	SOC	00SOC01QPS001	power supply	QPS	quench protection system evacuation current					Мухин	подсистема эвакуации токов	
21	20	SOC	00SOC01SMS001		SMS	suspension monitor system					Мухин		
22	21	SOC	00SOC01TMS001	termo	TMS	termo monitor system					Мухин		
23	22	SOC	00SOC01MMS001		MMS	magnetic requirements					Мухин		
24	23	SOC	00SOC01VCS001		VCS	vacuum control system							
25	24	CES	00CES01RFS001		RFS	refrigerator							
26	25	CES	00CES01CDS001		CDS	control duarew							
27	26	CES	00CES01MFS001		MFS	nitrogen hitler (MFS) magnet flushing system							
28	27	CES	00CES01OHS001		OHS	outlet hitlers							
29	28	CES	00CES01NTS001		NTS	nitrogen tanks							

systems Subsystems Units Devices Signals/parameters/TAGs Operating modes Interlock Re Explore

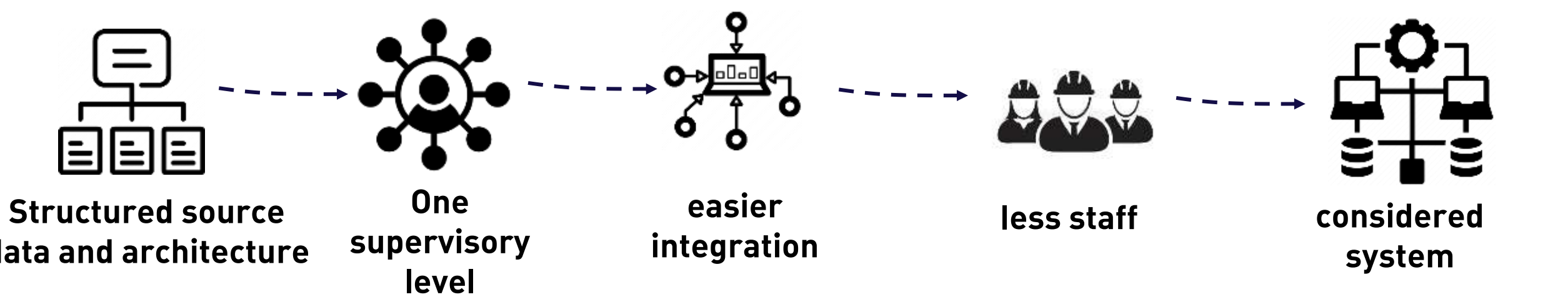
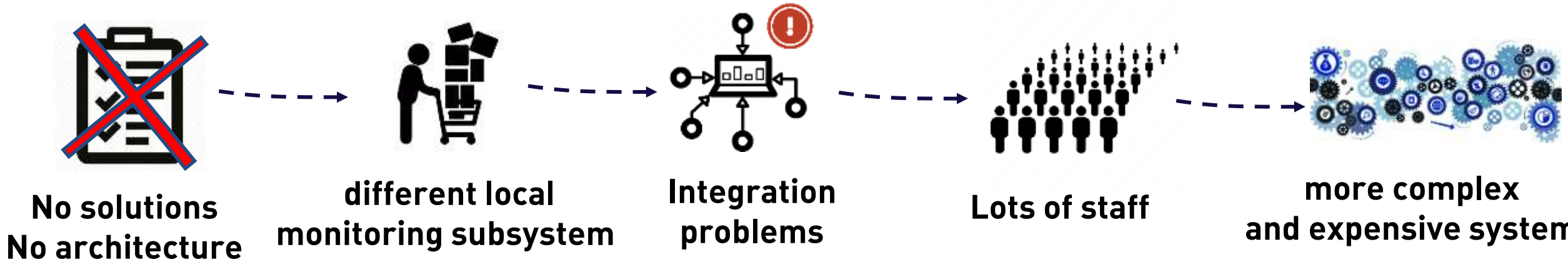
Any Commercial SCADA

Open source SCADA TANGO

much



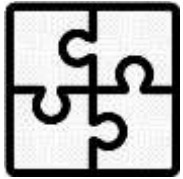
few





Functional expectations

- Supervisory – fully controllable, not only “monitoring”:
- Control, adjustments, alarms, historical data, etc.
- Balance between automation and human involvement



Potential architecture

- Vertical Integration: control, management, enterprise, business
- Horizontal Organization: technological units, processes
- Typical main division: DCS, DSS, QCS, ECS



Scale of already existed automated systems (ALICE)

- DCS – more that 100 servers, 1000-ти MIMICS panels
- DAQ – over 8000 fast links, around 2000 servers
- TCS – complex, multilevel: L0, L1, L2, a lot of config DB, algorithms



Call to action

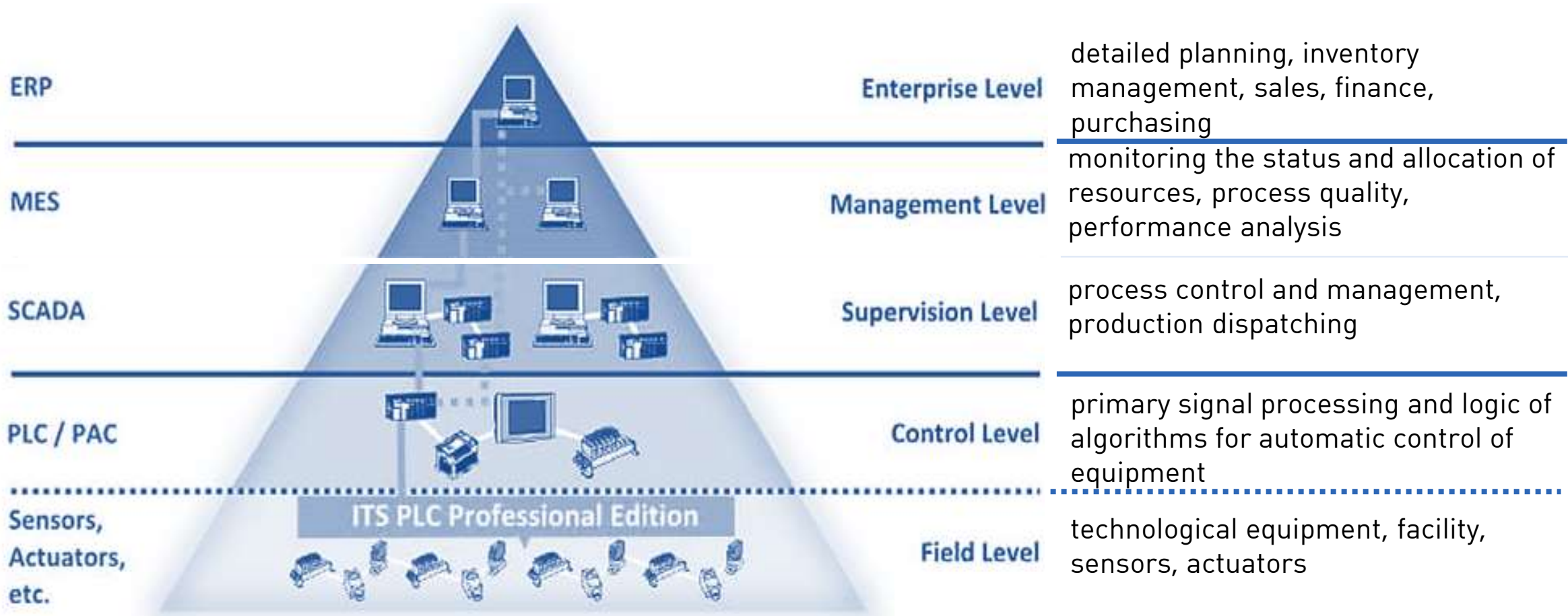
- Establish Clear Functional Devison for MPD's Automated Systems
- Specify Requirements for the Automated Systems of MPD
- Develop design solutions – TDR for each one



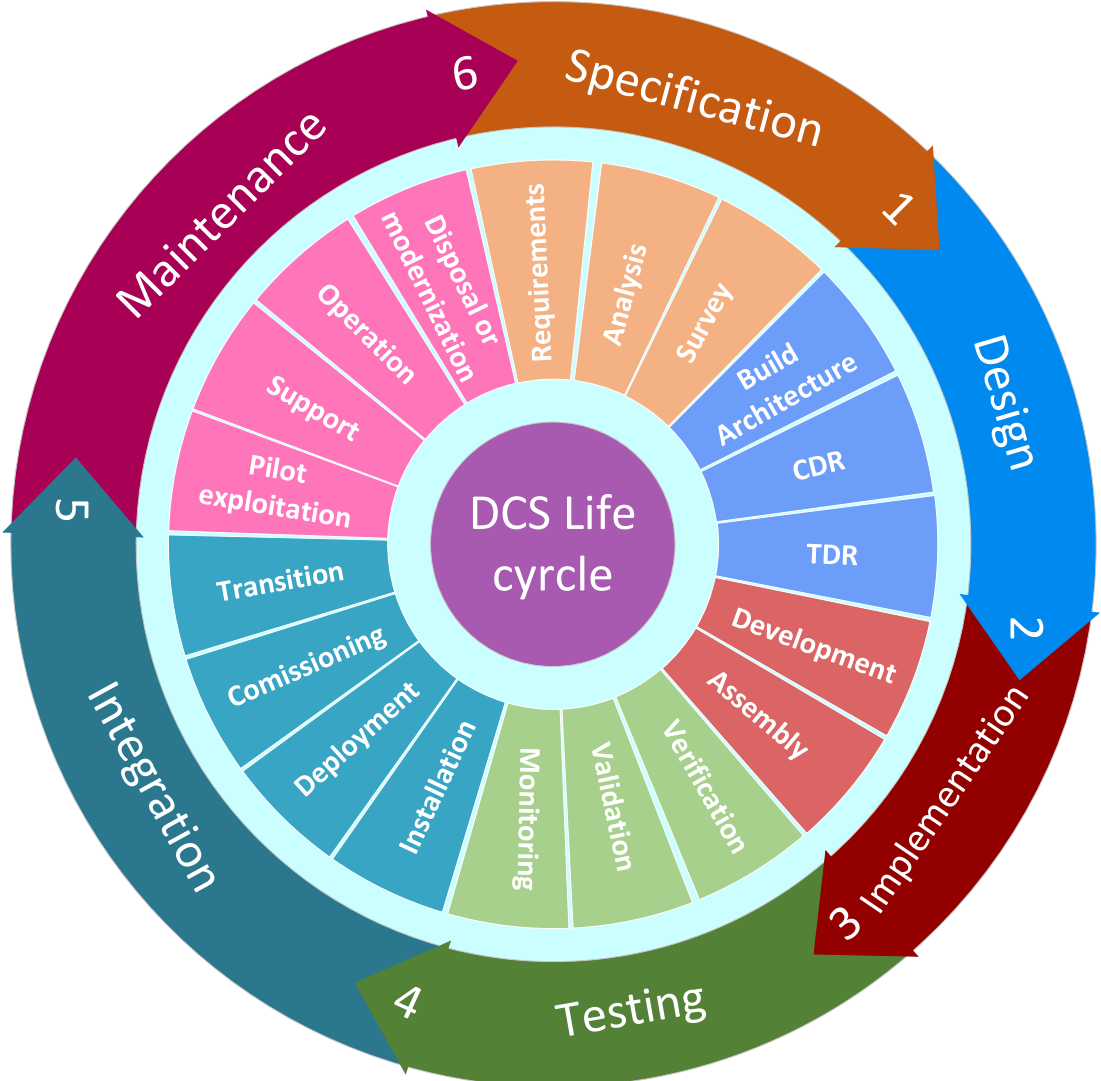
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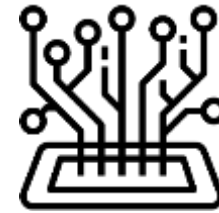
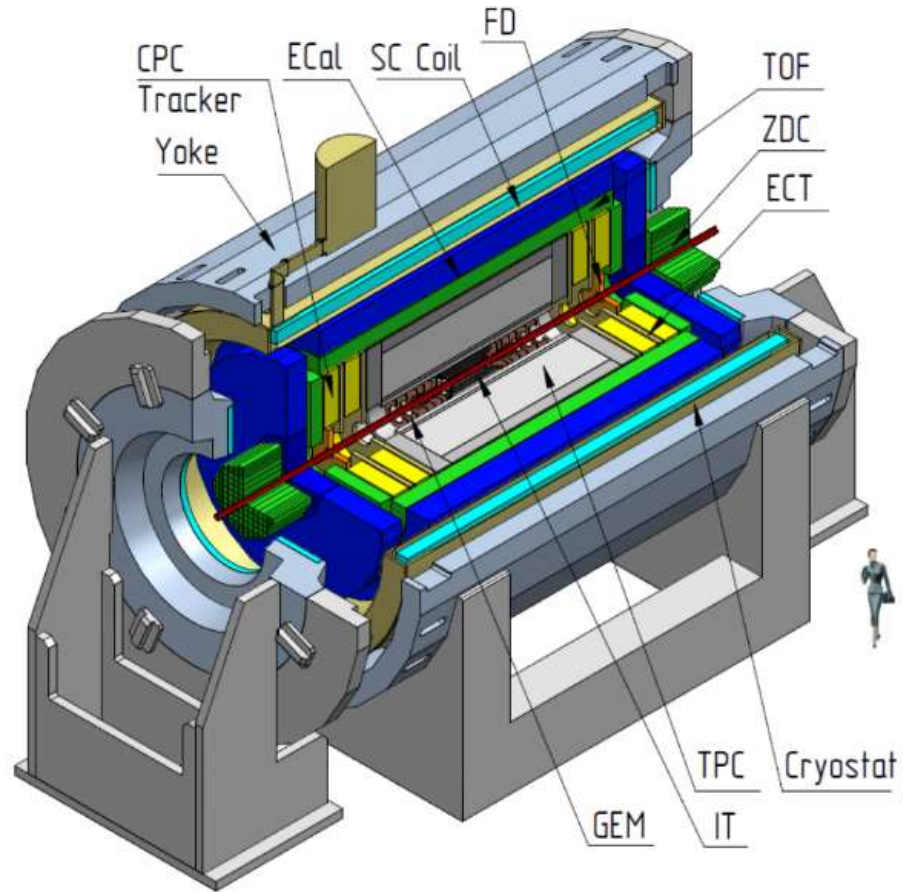
Hierarchy of automated systems



LIFE CYCLES OF AUTOMATED SYSTEMS



Multi-Purpose Detector



First stage Subdetectors:

- TPC, TOF, Ecal, FFD, FHCAL

Second stage Subdetectors:

- ITS, GEM, CPC



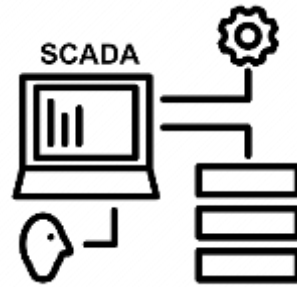
Infrastructure subsystems:

- Magnets, B-field, radiation, access control, ventilation, etc.

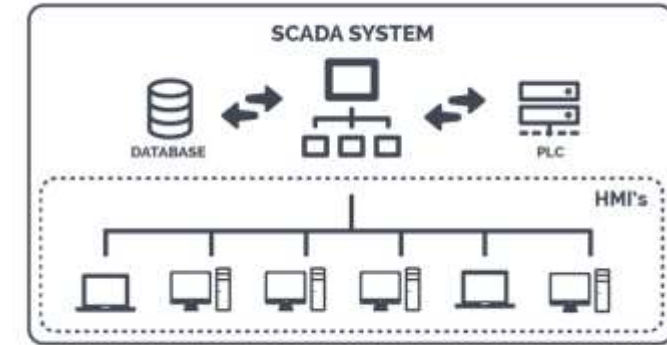


External services:

- Electricity, cryogenic, cooling, gas etc.

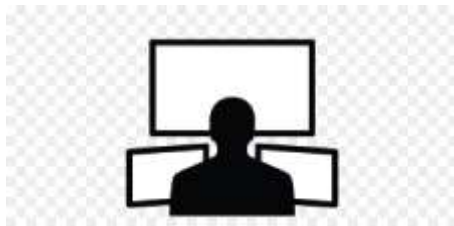


SCADA



Supervisory, control and data acquisition

Supervisory



Control



Data Acquisition





ALICE

“Data Acquisition, Control and Trigger”



“High-Level Trigger, Data Acquisition and Controls”

Trigger



+

Data Acquisition



+

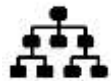
Controls



top-down design



overall concept



defined structure and architecture

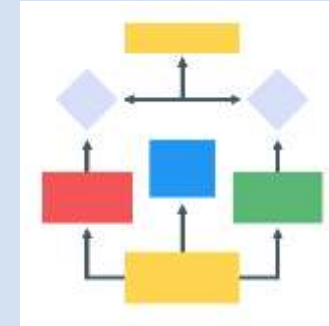


Improved planning and understanding requirements

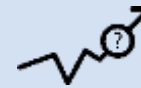


Easy maintenance

bottom-up design



detailed design of low-level components



gradual increase



risk of component integration problems and architecture revision



Difficulties in managing complexity, harder maintenance & rising costs

"convenient" user interface example

Stave	PLC Monitor?	PU1 Monitored?	PU1 Safe?	PU2 Monitored?	PU2 Safe?	PU1 Int. T	PU1 Halfstave T	PU1 Powered?	PU2 Int. T	PU2 Halfstave T	PU2 Powered?	RU FPGA T
L6 00	YES	NO	TRUE	NO	TRUE	22.35	21.52	ERR	21.24	21.07	ERR	30.51
L6 01	YES	NO	TRUE	NO	TRUE	22.19	22.34	ERR	21.15	21.26	ERR	86.80
L6 02	YES	NO	TRUE	NO	TRUE	18.99	18.92	NO	18.74	18.54	NO	172.23
L6 03	YES	NO	TRUE	NO	TRUE	36.81	-268.56	ERR	36.81	-268.56	ERR	99.03
L6 04	YES	NO	TRUE	NO	TRUE	36.81	-268.56	ERR	36.81	-268.56	ERR	-273.82
L6 05	YES	NO	TRUE	NO	TRUE	36.81	-268.56	ERR	36.81	-268.56	ERR	-273.82
L6 06	YES	NO	TRUE	NO	TRUE	36.81	-268.56	ERR	-33.10	501.70	NO	99.04
L6 07	YES	NO	TRUE	NO	TRUE	36.81	-268.56	ERR	36.81	-268.56	ERR	-273.82
L6 08	YES	NO	TRUE	NO	TRUE	-259.51	175.01	ERR	-259.73	1.16	ERR	-273.82
L6 09	YES	NO	TRUE	NO	TRUE	-259.73	-268.34	ERR	-259.73	1.16	ERR	-273.82
L6 10	YES	NO	TRUE	NO	TRUE	36.81	-268.56	ERR	36.81	-268.56	ERR	-273.82
L6 11	YES	NO	TRUE	NO	TRUE	36.81	-268.56	ERR	36.81	-268.56	ERR	31.41
L6 12	YES	NO	TRUE	NO	TRUE	779.17	-268.56	ERR	18.83	18.22	NO	-273.71
L6 13	YES	NO	TRUE	NO	TRUE	299.11	-247.79	ERR	18.80	18.13	NO	32958422.83
L6 14	YES	NO	TRUE	NO	TRUE	19.28	18.38	NO	18.77	18.47	NO	32958422.83
L6 15	YES	NO	TRUE	NO	TRUE	19.25	18.70	NO	18.74	18.54	NO	32958422.83
L6 16	YES	NO	TRUE	NO	TRUE	19.28	18.60	NO	18.83	18.35	NO	32958422.83
L6 17	YES	NO	TRUE	NO	TRUE	19.28	18.70	NO	18.64	18.19	NO	32958422.83
L6 18	YES	NO	TRUE	NO	TRUE	19.02	19.01	NO	18.52	18.66	NO	32958422.83
L6 19	YES	NO	TRUE	NO	TRUE	19.09	18.38	NO	18.67	18.22	NO	32958422.83
L6 20	YES	NO	TRUE	NO	TRUE	19.06	18.89	NO	18.52	18.28	NO	32958422.83
L6 21	YES	NO	TRUE	NO	TRUE	278.69	106.77	ERR	18.52	18.22	NO	32958422.83
L6 22	YES	NO	TRUE	NO	TRUE	19.12	18.51	NO	18.52	18.89	NO	32958422.83
L6 23	YES	NO	TRUE	NO	TRUE	18.93	18.32	NO	18.45	18.47	NO	32958422.83

Qualitative indicators:



Monitoring all subsystems
All in one application



Alarm table & tips
All in one application



Automations algorithms



Control function



Archive & logging

