

Analytical Computation Software Module in Python for Automating the Representation of Equations for Further Numerical Modeling of the Chain of Nanomagnets Associated with the Josephson Junction

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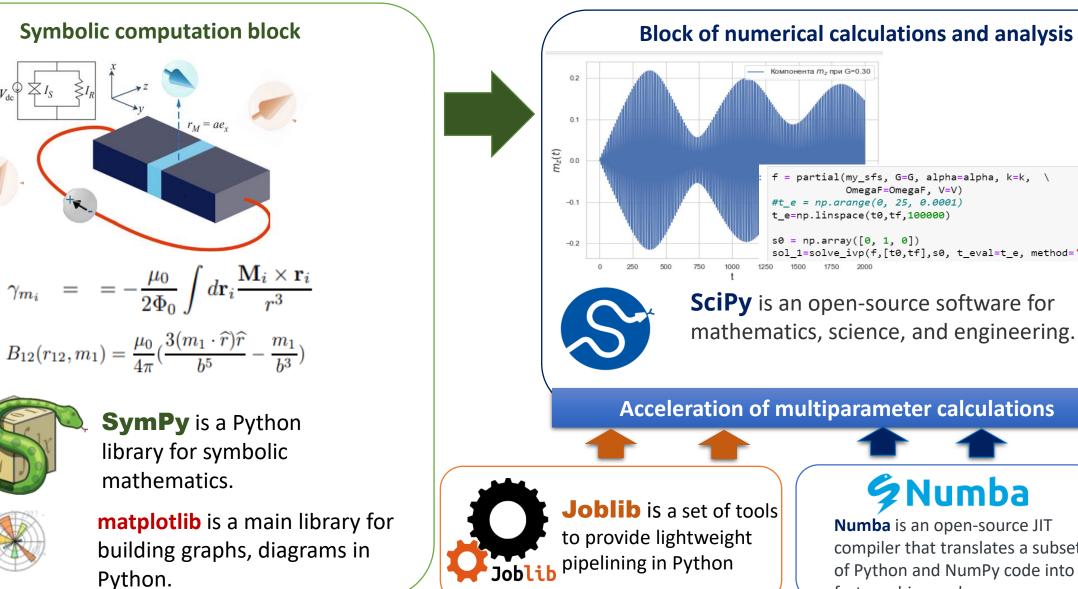


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Research of systems based on Josephson junctions





= partial(my_sfs, G=G, alpha=alpha, k=k, \ OmegaF=OmegaF, V=V) #t_e = np.arange(0, 25, 0.0001) t e=np.linspace(t0,tf,100000) s0 = np.array([0, 1, 0])sol_1=solve_ivp(f,[t0,tf],s0, t_eval=t_e, method='RK45') **SciPy** is an open-source software for

Acceleration of multiparameter calculations

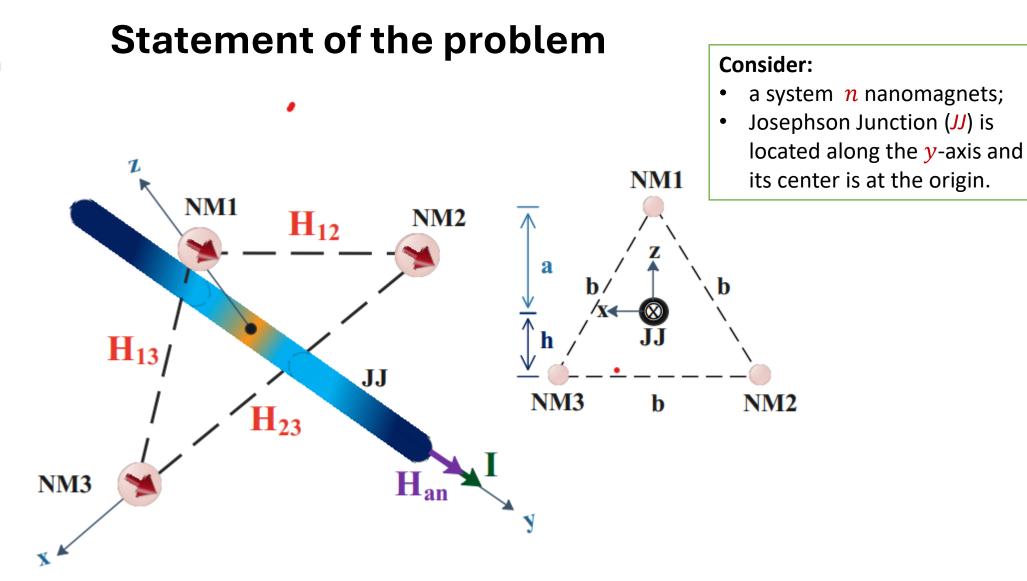
Numba is an open-source JIT compiler that translates a subset of Python and NumPy code into fast machine code.

%Numba



SymPy is a Python library for syml mathematics.

System of nanomagnets and Josephson junction



For definiteness, we will demonstrate the operation of the software module for n=3



The dynamics of a system of nanomagnets with JJ is described by the Landau - Lifshitz - Hilbert equations

$$egin{aligned} &rac{d\mathbf{m}_1}{dt}=-rac{\Omega_{F,1}}{1+lpha^2}\Big(\mathbf{m}_1 imes\mathbf{h}_{eff,1}+lpha\mathbf{m}_1 imes(\mathbf{m}_1 imes\mathbf{h}_{eff,1})\Big)\ &rac{d\mathbf{m}_2}{dt}=-rac{\Omega_{F,2}}{1+lpha^2}\Big(\mathbf{m}_2 imes\mathbf{h}_{eff,2}+lpha\mathbf{m}_2 imes(\mathbf{m}_2 imes\mathbf{h}_{eff,2})\Big)\ &rac{d\mathbf{m}_3}{dt}=-rac{\Omega_{F,3}}{1+lpha^2}\Big(\mathbf{m}_3 imes\mathbf{h}_{eff,3}+lpha\mathbf{m}_3 imes(\mathbf{m}_3 imes\mathbf{h}_{eff,3})\Big) \end{aligned}$$

 $h_{eff,i}$, i = 1, ..., n - effective field $h_{eff,i} = h_{ij} + h_{an,i} + h_{J,i} + h_{ext}$



 $n = 1, 2, \dots 100, \dots$

Calculation of integrals

$$\gamma_{m_i}=\,-\,rac{\mu_i V_{F,i}}{2\Phi_0}\int d{f r}_i rac{{f M}_i imes {f r}_i}{r^3}$$



SymPy is a Python library for symbolic mathematics.

import sympy as sp import numpy as np from sympy import *

System of nanomagnets and Josephson junction

1. Geometry

Data structure for radius vectors of nanomagnets:

$$\underbrace{Geom_NM}_{3xn} = \begin{pmatrix} r_{0,x} & r_1,x & \dots & r_{n-1,x} \ r_{0,y} & r_1,y & \dots & r_{n-1,y} \ r_{0,z} & r_1,z & \dots & r_{n-1,z} \end{pmatrix}$$

a, b, C = sp.symbols('a b C', positive = True, real = True)

from sympy.vector import CoordSys3D, ParametricRegion, ImplicitRegion, vector_integrate
from sympy.abc import r, x, y, z, theta, phi, t, V, t
#https://docs.sympy.org/latest/modules/vector/vector_integration.html
L, K, S = sp.symbols('L K S', positive = True, real = True)

Geom_NM

$$egin{bmatrix} 0 & -rac{\sqrt{3}a}{2} & rac{\sqrt{3}a}{2} \ 0 & 0 & 0 \ a & -rac{a}{2} & -rac{a}{2} \end{bmatrix}$$



SymPy is a Python library for syml mathematics.

System of nanomagnets and Josephson junction

1. Geometry Consider: a system *n* nanomagnets; ٠ Josephson Junction (JJ) is ٠ located along the *y*-axis and its center is at the origin. NM1 NM1 NM2 **H**₁₂ a b b h **H**₁₃/ JJ **NM3** NM2 b H_{23} **NM3** Han

For definiteness, we will demonstrate the operation of the software module for n = 3



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System of nanomagnets and Josephson junction

1. Geometry

Matrix of distances between nanomagnets *Rij_NM*

$$\underbrace{Rij_NM}_{3xn^2}|_{n=3} = \begin{pmatrix} 0 & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ r_{00,x} = 0 & r_{01,x} & r_{02,x} & r_{10,x} & r_{11,x} = 0 & r_{12,x} & r_{20,x} & r_{21,x} & r_{22,x} = 0 \\ r_{00,y} = 0 & r_{01,y} & r_{02,y} & r_{10,y} & r_{11,y} = 0 & r_{12,y} & r_{20,y} & r_{21,y} & r_{22,y} = 0 \\ r_{00,z} = 0 & r_{01,z} & r_{02,z} & r_{10,z} & r_{11,z} = 0 & r_{12,z} & r_{20,z} & r_{21,z} & r_{22,z} = 0 \end{pmatrix}$$

$$\begin{bmatrix} 0 & -\frac{\sqrt{3}a}{2} & \frac{\sqrt{3}a}{2} & \frac{\sqrt{3}a}{2} & 0 & \sqrt{3}a & -\frac{\sqrt{3}a}{2} & -\sqrt{3}a & 0\\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0\\ 0 & -\frac{3a}{2} & -\frac{3a}{2} & \frac{3a}{2} & 0 & 0 & \frac{3a}{2} & 0 & 0 \end{bmatrix}$$



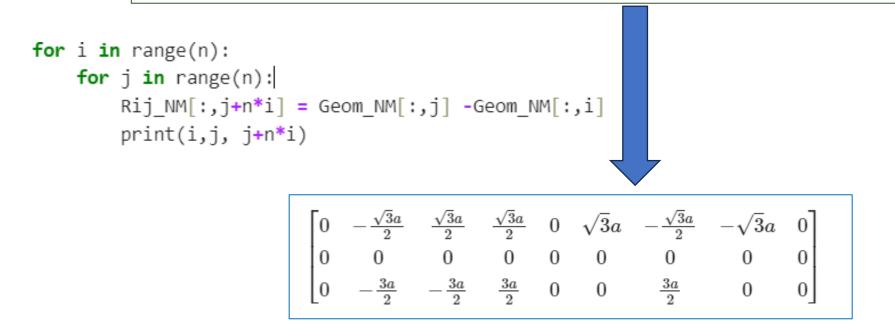
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System of nanomagnets and Josephson junction

1. Geometry

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2. Model parameters

Constants:

- α is the Gilbert damping constant
- $\omega_c = rac{2\pi}{\Phi_0} I_c R$ timescale t is unitless and is reduced
- *ϵ*_J

```
Let's introduce a row matrix, dimensions (1 \times n):
```

- $\gamma = [\gamma_0, \gamma_1, \dots, \gamma_{n-1}]$ is the gyromagnetic ratio for all NM,
- $M_0 = [M_{0,0}, M_{0,1}, \dots, M_{0,n-1}]$ is the saturation magnetization of a simulated ferromagnet
- $\mu = [\mu_0, \mu_1, \dots, \mu_{n-1}]$ is permeability (H/m)
- $V_F = [V_{F,0}, V_{F,1}, \dots, V_{F,n-1}]$ is volumes of NM
- $K_{an} = [K_{an,0}, K_{an,1}, \ldots, K_{an,n-1}]$ is anisotropy

Designation row matrix:

• $\Omega_F = [\Omega_{F,0}, \Omega_{F,1}, \dots, \Omega_{F,n-1}]$

•
$$C = [C_0, C_1, \dots, C_{n-1}]$$

• $\epsilon = [\epsilon_0, \epsilon_1, \dots, \epsilon_{n-1}]$

$$\left[\frac{\epsilon_J}{M_{00}^2 V_{F0} \mu_0} - \frac{\epsilon_J}{M_{01}^2 V_{F1} \mu_1} - \frac{\epsilon_J}{M_{02}^2 V_{F2} \mu_2}\right]$$

$$\left[\int_{02}^{2} V_{F2} \mu_{2} \right]$$

$$egin{aligned} \Omega_{F,i} &= rac{\mu_i M_{0,i} \gamma_i}{\omega_c}, i = 0, 1, \dots, n-1. \ &C_i &= rac{V_{F,i}}{4\pi}, i = 0, 1, \dots, n-1. \ &\epsilon_i &= rac{\epsilon_J}{\mu_i V_{F,i} M_{0,i}^2}, i = 0, 1, \dots, n-1. \end{aligned}$$



SymPy is a Python library for symbolic mathematics.

3. Required vectors

Magnetization vector (normalized) NM: M_NM

```
M_NM=zeros(3, n)
for i in range(n):
    M_NM[0,i] = Function(symbols("m"+ str(0)+str(i)))(t)
    M_NM[1,i] = Function(symbols("m"+ str(1)+str(i)))(t)
    M_NM[2,i] = Function(symbols("m"+ str(2)+str(i)))(t)
M_NM
```

 $\begin{bmatrix} m_{00}(t) & m_{01}(t) & m_{02}(t) \\ m_{10}(t) & m_{11}(t) & m_{12}(t) \\ m_{20}(t) & m_{21}(t) & m_{22}(t) \end{bmatrix}$





SymPy is a Python library for symbolic mathematics.

4. Effective field

The effective field is consist of 4 terms:

 $h_{eff,i} = h_{ij} + h_{an,i} + h_{J,i} + h_{ext}$

where

- h_{ij} is an effective field duo to the dipole interaction,
- $h_{an,i}$ is an effective field duo to the magnetic anisotropy,
- $h_{J,i}$ is an effective field duo to the current through JJ and
- h_{ext} is an external magnetic field, which is in our case zero ($h_{ext} = 0$).



 h_{ii} is an effective field duo to the dipole interaction

4. Effective field

Finding magnetizations

The magnetic field of a magnetic dipole in vector notation is:

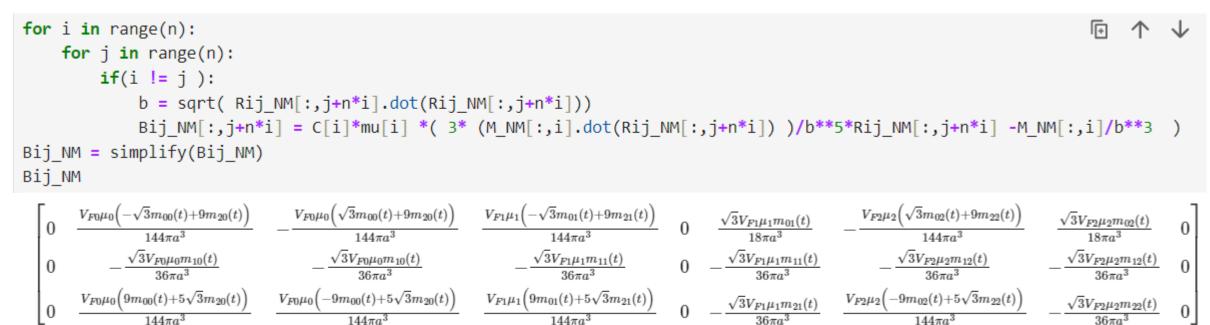
$$B_{ij}(r_{ij},m_i) = rac{V_{F,i} \mu_i}{4\pi} (rac{3(m_i \cdot {f r}) {f r}}{b^5} - rac{m_i}{b^3})$$

where H is the field, r is the vector from the position of the dipole to the position where the field is being measured, b is the distance between nanomagnets, m_i is the magnetization vector, μ_i is the permeability.





4. Effective field





4. Effective field



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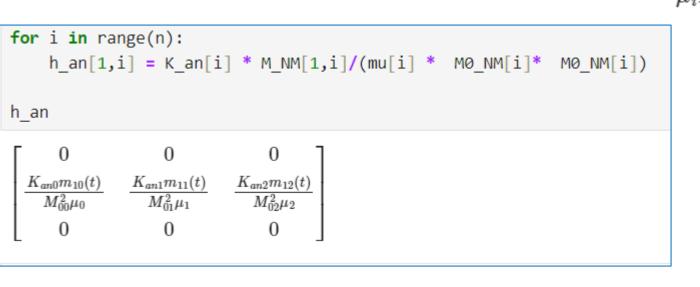
4. Effective field

The magnetic anisotropy field is given by:

 $h_{an,i}$ - is an effective field duo to the magnetic anisotropy

$$h_{an,i} = ilde{K}_{an,i} m_{y,i}$$

where



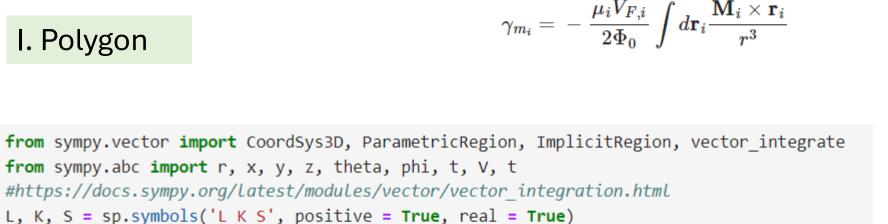
$$ilde{K}_{an,i} = rac{K_{an,i}}{\mu_i M_{0,i}^2}, i = 0, 1, \dots, n-1.$$



4. Effective field

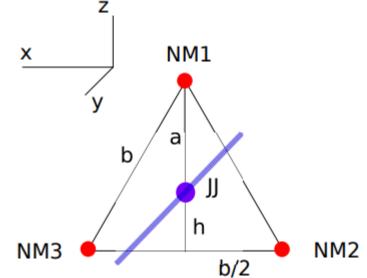
 $h_{J,i}$ - is an effective field duo to the current through JJ

The superconductive phase shift γ_{m_1,m_2} caused by the nanomagnets is given by



```
tp = sp.symbols('tp', positive = True, real = True)
```

```
from sympy.geometry import Point, Polygon
curve = ParametricRegion( (0, tp, 0), (tp, -L/2, L/2))
C = CoordSys3D('C')
```





 $\mathbf{M}_{2} \times \mathbf{r}_{2}$

HiVE: C

4. Effective field

 $h_{J,i}$ - is an effective field duo to the current through JJ

The superconductive phase shift γ_{m_1,m_2} caused by the nanomagnets is given by

$$\gamma_{m_{i}} = -\frac{\mu(1-Y_{i})}{2\Phi_{0}} \int d\mathbf{r}_{i} \frac{\sin(1-Y_{i})}{r^{3}}$$
II. Vector
integrate
$$\begin{bmatrix} Am_{v} \text{vecl} = -K^{*}\text{nm.cross}(r1m)/\text{sqrt}(r1m.dot(r1m))^{**3} \\ Am_{v} \text{vecl} \end{bmatrix}$$

$$\begin{pmatrix} -\frac{K(-\mathbf{y}_{C}m_{20}(t) - am_{10}(t))}{(\mathbf{y}_{C}^{2} + a^{2})^{\frac{3}{2}}} \end{pmatrix} \hat{\mathbf{i}}_{C} + \left(-\frac{Kam_{00}(t)}{(\mathbf{y}_{C}^{2} + a^{2})^{\frac{3}{2}}} \right) \hat{\mathbf{j}}_{C} + \left(-\frac{\mathbf{y}_{C}Km_{00}(t)}{(\mathbf{y}_{C}^{2} + a^{2})^{\frac{3}{2}}} \right) \hat{\mathbf{k}}_{C}$$
Data structure:

$$\gamma = [\gamma_{0}, \gamma_{1}, \gamma_{2},]$$
for i in range(n):

$$r1m = (\Theta - \text{Geom}_{1}\text{MM}[\Theta, i])^{*}\text{C.i} + (C.y - \text{Geom}_{1}\text{NM}[1, i])^{*}\text{C.j} + (\Theta - \text{Geom}_{1}\text{NM}[2, i])^{*}\text{C.k}$$

$$m = M_{1}\text{MM}[\Theta, i]^{*}\text{C.i} + M_{2}\text{M}[1, i]^{*}\text{C.j} + M_{2}\text{M}[2, i]^{*}\text{C.k}$$

$$Am_{v} \text{vecl} = -mu[i]^{*} \text{V}_{F}[i]/(2^{*}\text{Phi}_{0}\Theta) * nm.cross(r1m)/\text{sqrt}(r1m.dot(r1m))^{**3}$$

$$gamma_{m}[i] = \text{vector_integrate}(Am_{v}\text{vecl}, \text{curve})$$

$$gamma_{m}$$

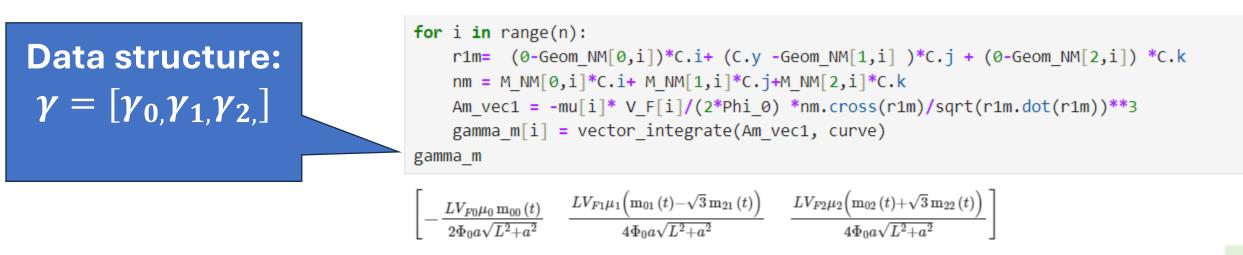


5. The current flowing through the JJ

The current flowing through the JJ is given by

$$I = \sin[Vt + \gamma_{m_1} + \gamma_{m_2} + \gamma_{m_3}] + V + \dot{\gamma}_{m_1} + \dot{\gamma}_{m_2} + \dot{\gamma}_{m_3}.$$

 $h_{J,i}$ - is an effective field duo to the current through JJ

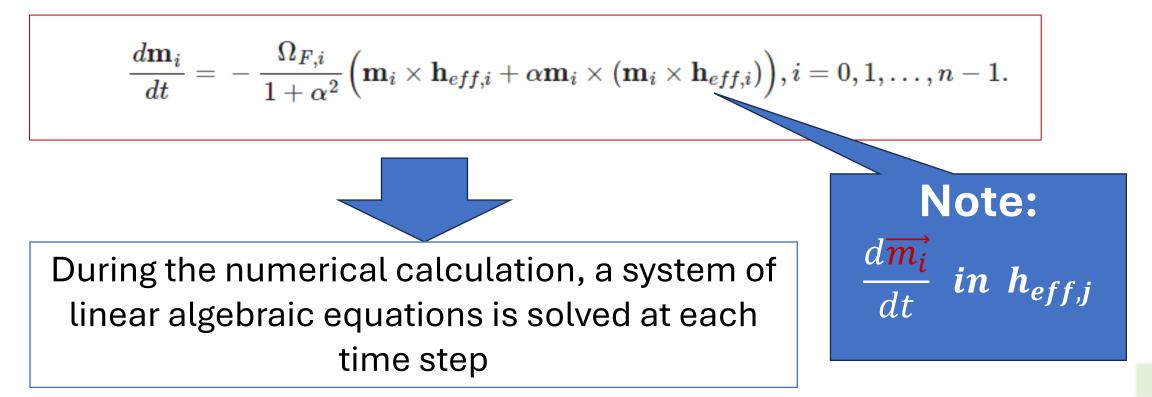




6. LLH system of equations

To further solve the Cauchy problem (**IVP**) numerically, it is necessary to reduce the system of ordinary differential equations to the form:

$$\frac{d\vec{y}}{dt} = F(t, \vec{y})$$



Conclusion

To study the chain of nanomagnets associated with the Josephson junction, a **software module** has been developed to output equations in symbolic form for further numerical modeling. In this case, the equations are reduced to the form of a system of ordinary differential equations resolved with respect to the derivative at each integration step.

The implementation is carried out using the **SymPy** library for symbolic operations.

