



Computational environment for the numerical modelling of hybrid superconductor / magnetic nanostructures

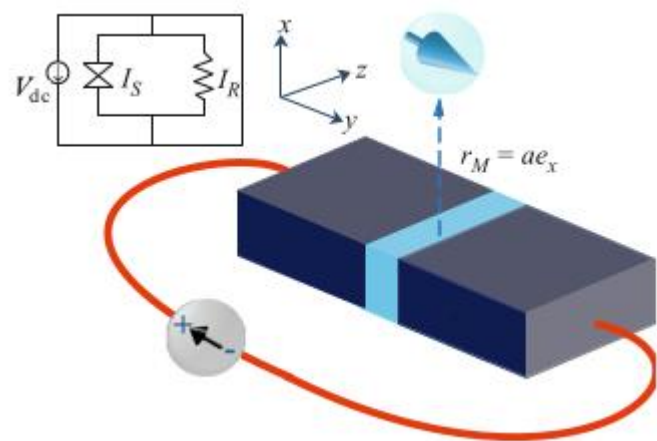
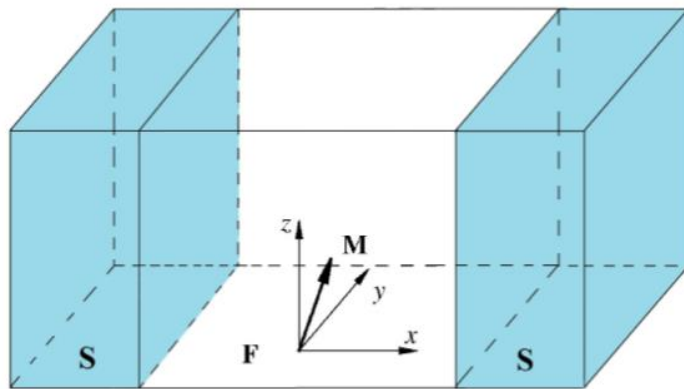
Andrey Nechaevskiy



This work was supported by Russian Science Foundation grant № 22-71-10022

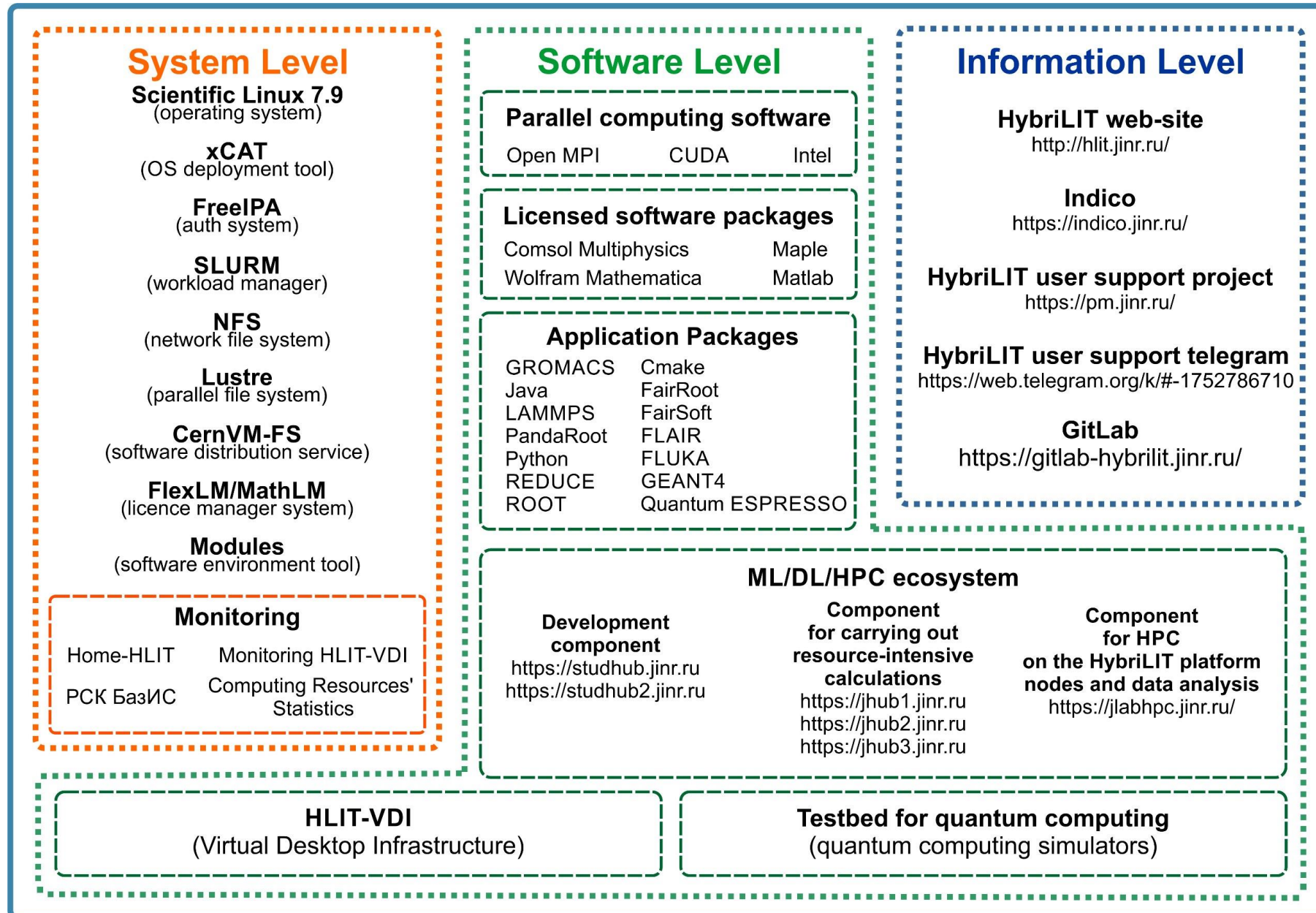


Mathematical modeling of superconducting nanostructures with a magnetic to study the possibilities of magnetization and magnetic excitations control using high-performance computing systems



The primary focus of modern nanotechnology research is the development, analysis and exploitation of novel materials and structures. The investigation of the physical properties of these objects requires the numerical solution of complex systems of non-linear differential equations, which requires a significant investment of time and computational resources. The transition to advanced digital technologies, such as high-performance hybrid computing (including parallel computing technologies on a cluster, on a graphics card, etc.), will facilitate the solution of this class of problems in a time-efficient manner, allowing the achievement of physically significant, world-class results. These results can then be used in the development of quantum computers and in solving problems in superconducting electronics and spintronics.

MICC component: HybriLIT platform



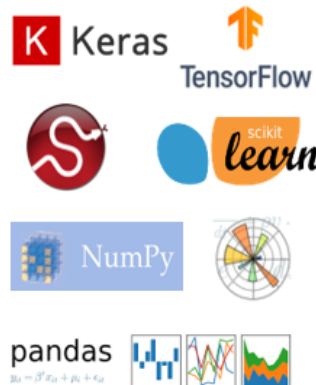
ML/DL/HPC ecosystem

Development component

VM with JupyterHub
<https://jhub.jinr.ru>



VM:
CPU: 24 Cores
RAM: 32 GB



Computation component

Servers with
NVIDIA
Volta & Intel Xeon Gold
<https://jhub2.jinr.ru>

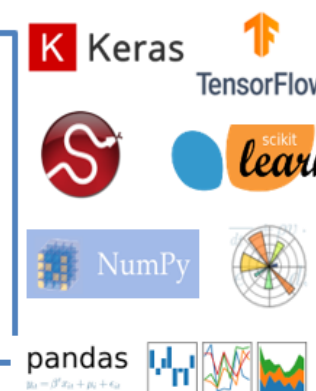
Dell Volta specs:
GPU: 4x Nvidia Volta V100-SXM2 NVLink 32Gb HBM2
CPU: 2x Intel(R) Xeon(R) Gold 6148 CPU @ 2.40GHz 20 Cores/40 Threads
RAM: 512 GB DDR4 2666MHz
SSD: 2*240 GB

HPCLab component

VM with
JupyterHub and SLURM
<https://jlabhpc.jinr.ru/>

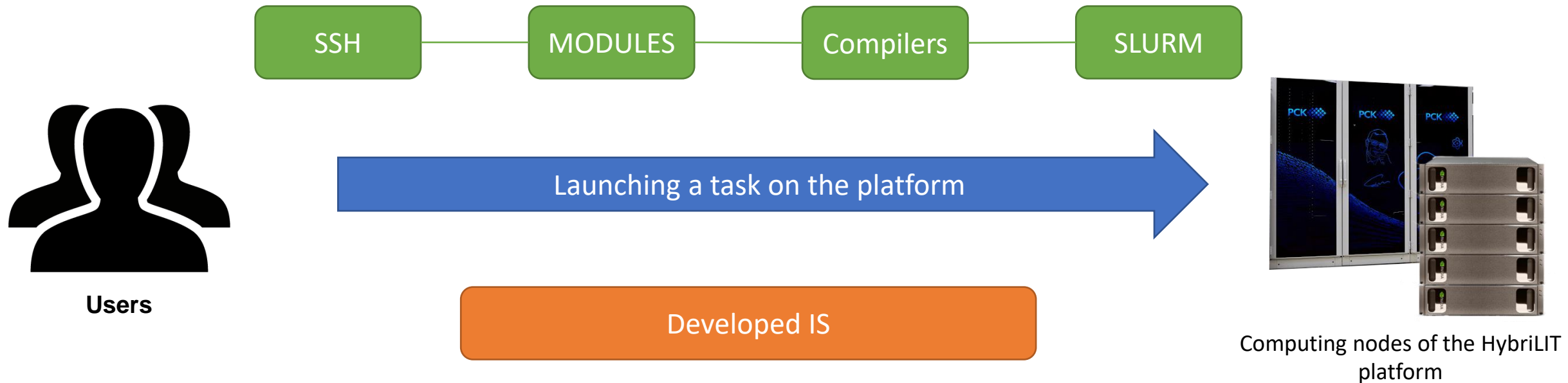


VM:
CPU: 24 Cores
RAM: 64 GB



High Performance Computing

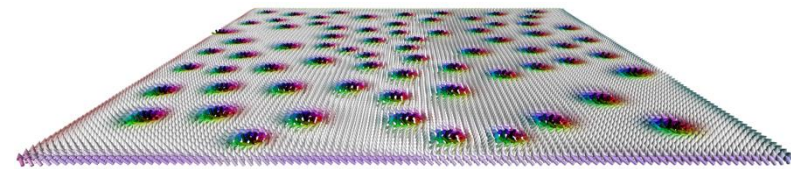
Development of information systems for theoretical and applied tasks on the HybriLIT platform



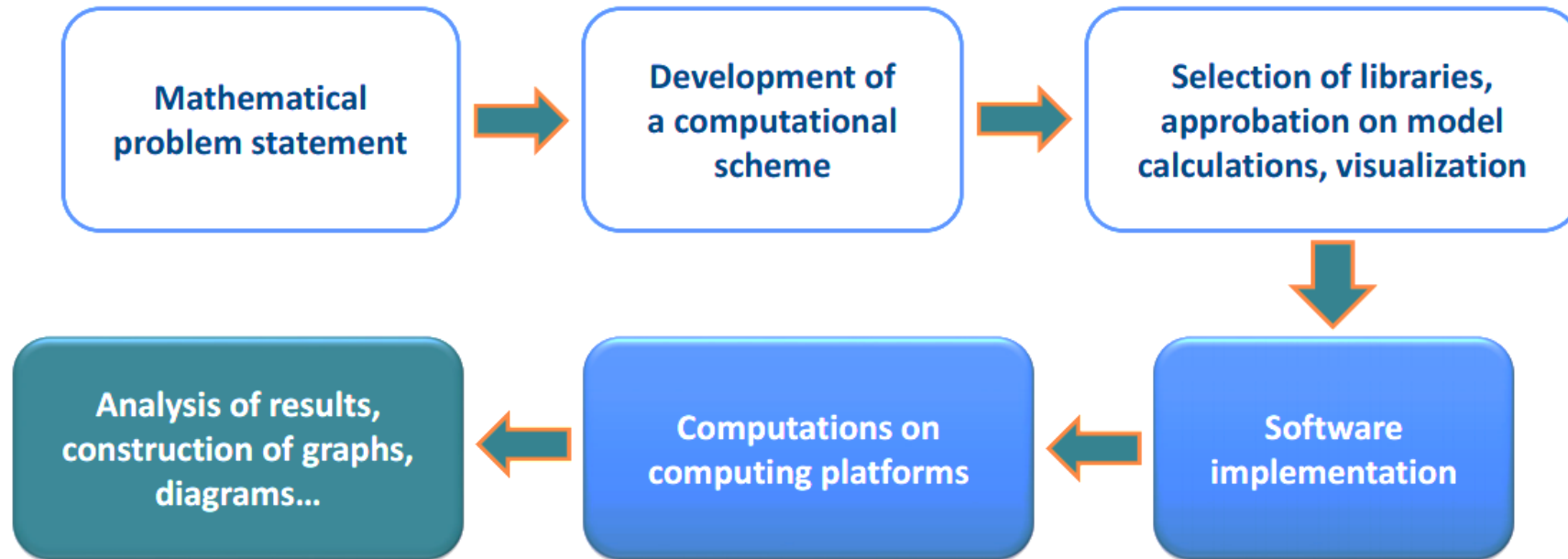
- The **main goal of the project** is to create a computational environment that will allow the efficient processing of the numerical modelling of hybrid S/F nanostructures.
- This environment will provide access to a range of tools and algorithms, as well as visualisation of computational results.

Tools and services for solving spintronics problems

- Existing tools for modelling nanostructures have quite a wide functionality and are useful for modelling magnetic moment dynamics. But they do not involve the new types of interactions that can appear in hybrid nanostructures.
- For modelling hybrid nanostructures, there are currently no off-the-shelf modelling tools that can solve this problem.
- To solve this class of problems, we develop a computational environment for modelling hybrid superconductor/magnetic nanostructures, which provides access to the developed algorithms, computational resources and visualisation of the calculation results.



Numerical Research Process



The creation of a toolkit that allows one to carry out computations, to visualize the results within a single application, and perform the most resource-intensive calculations in parallel is an urgent task. The *Jupyter Notebook* environment provides this capability.

Tools and services for solving spintronics problems

Jupyter Notebook is a powerful code management tool.

It provides many opportunities for developers and researchers.

- An environment with syntax highlighting, error correction and other IDE features.
- The ability to run individual sections of code or the entire program.
- You can run any piece of code in any order, which makes testing and debugging easier.
- Inserting and outputting results right in the middle of the code.
- Code sharing and collaboration.
- Beautiful and clear document design.

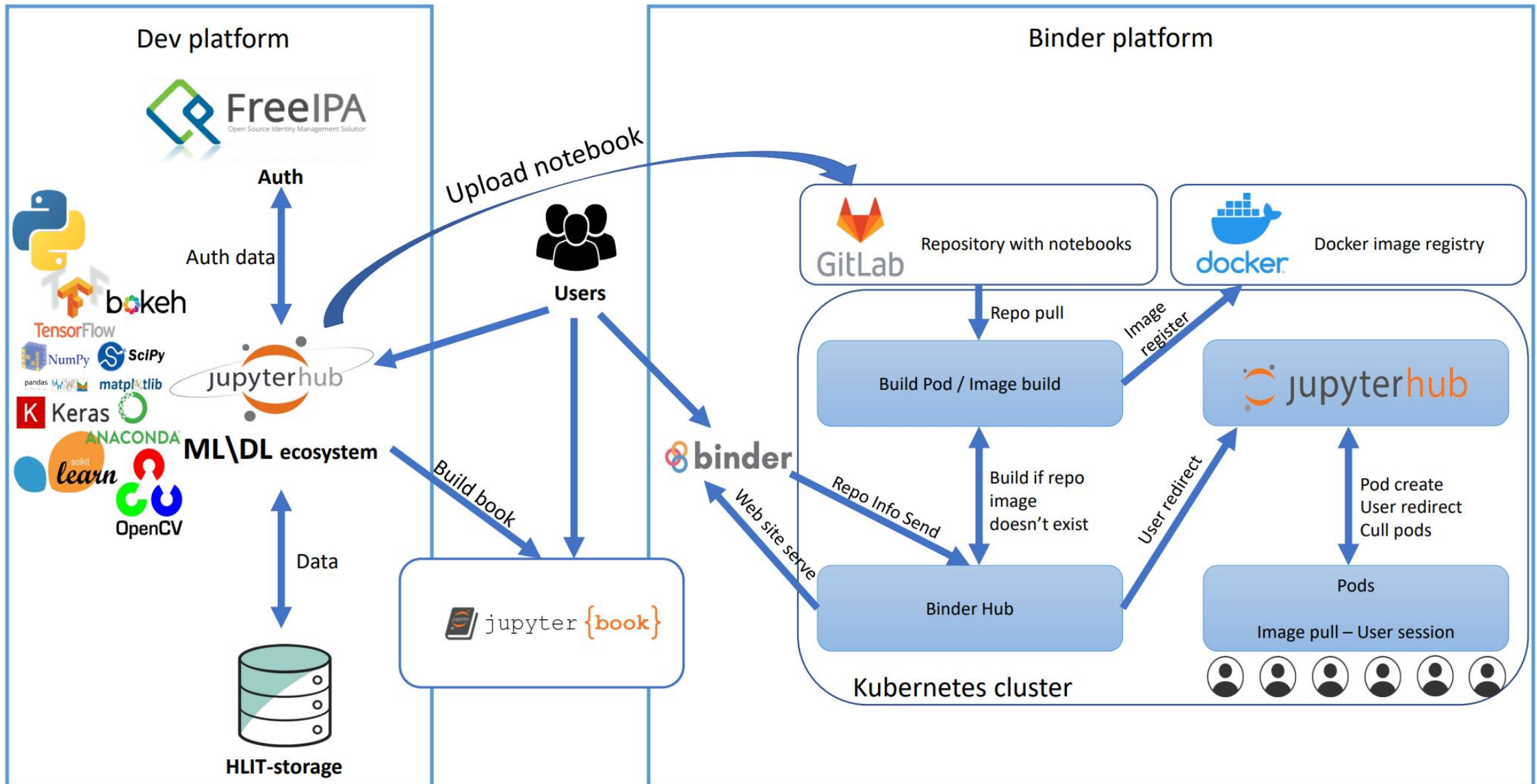


Tools and services for solving spintronics problems

- The first step was the implementation of a model for the study of Josephson junctions in Python in the Jupyter Notebook environment.
- Integration of the Jupyter Binder platform, for users who do not have access to the HybriLIT platform, including for test calculations or training courses.
- Jupyter Book integration, allowing users to create books, in the form of Jupyter Notebooks, that can be viewed or downloaded to work on their computing resources.
- HybriLIT platform used for computation and active development.

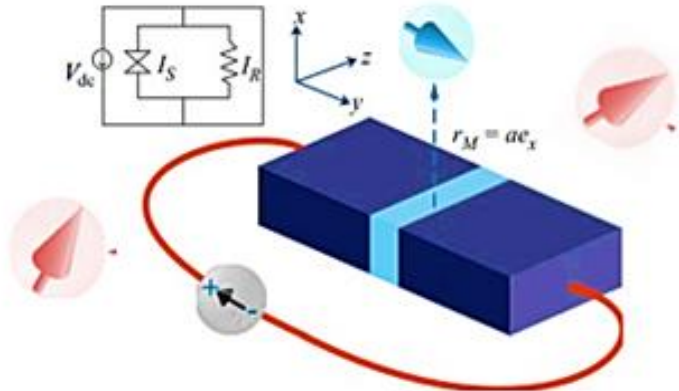


Computational environment for the numerical modelling



Development of information systems

Symbolic computations block



$$\gamma_{m_i} = -\frac{\mu_0}{2\Phi_0} \int d\mathbf{r}_i \frac{\mathbf{M}_i \times \mathbf{r}_i}{r^3}$$

$$B_{12}(r_{12}, m_1) = \frac{\mu_0}{4\pi} \left(\frac{3(m_1 \cdot \hat{r})\hat{r}}{b^5} - \frac{m_1}{b^3} \right)$$



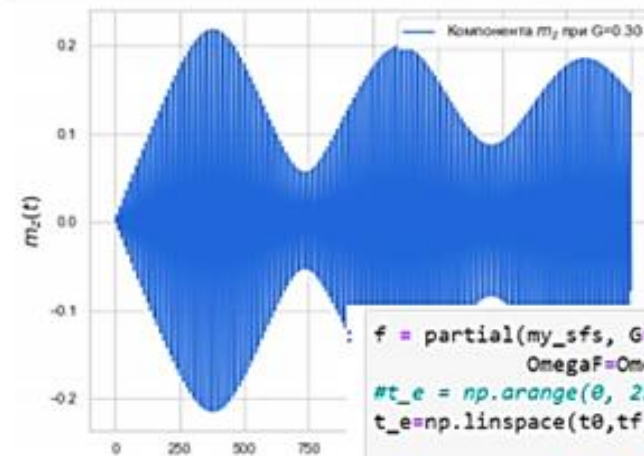
SymPy is a Python library for symbolic mathematics.



matplotlib is a main library for building graphs, diagrams in Python.



Block of numerical computations and analysis



```
f = partial(my_sfs, G=G, alpha=alpha, k=k, \
            OmegaF=OmegaF, V=V)
#t_e = np.arange(0, 25, 0.0001)
t_e=np.linspace(t0,tf,100000)

s0 = np.array([0, 1, 0])
sol_1=solve_ivp(f,[t0,tf],s0, t_eval=t_e, method='RK45')
```



SciPy is an open-source software for mathematics, science, and engineering.



Parallelization of multi-parameter computations

Joblib is a set of tools to provide lightweight pipelining in Python

Python implementation

Calculations for different values of parameters

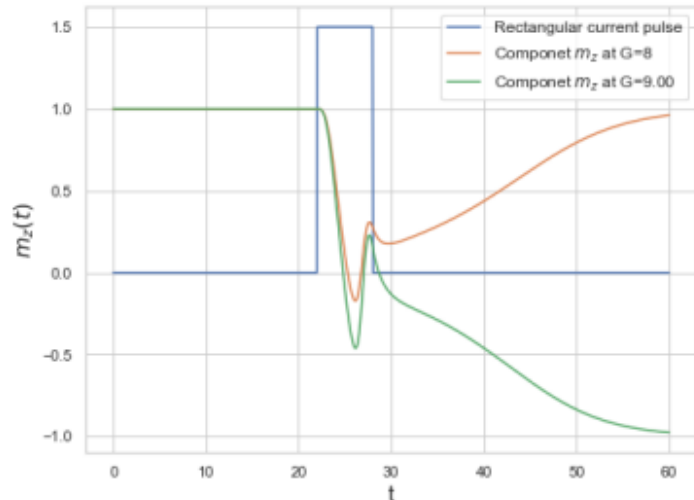
To analyze the possibility of reversing the magnetic moment of the ϕ_0 -Josephson junction at different values of the parameters, we will carry out calculations for $G=8.9$.

```
from scipy.integrate import solve_ivp
from functools import partial
```

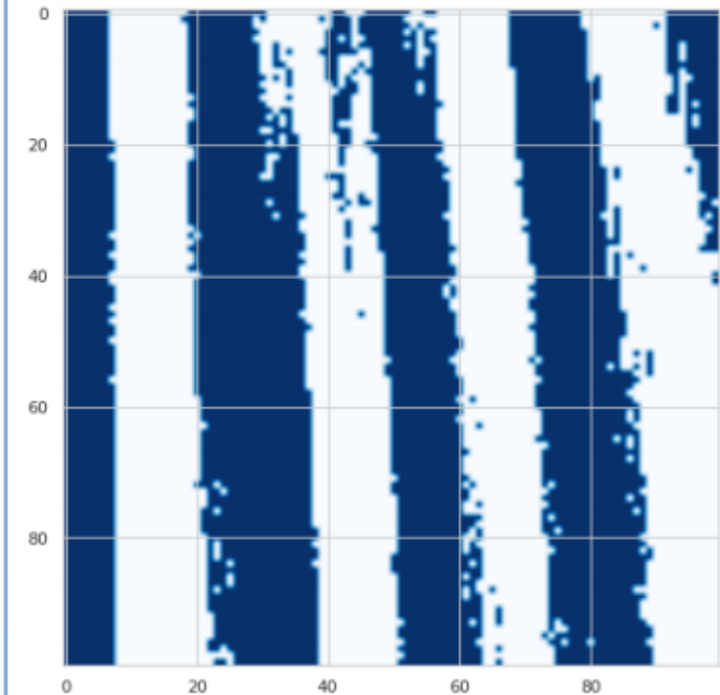
```
G=9
f = partial(my_sfs, G=G, r=r, alpha=alpha, \
            As=As, t_s=t_s, delta_t=delta_t)
#t_e = np.arange(0, 25, 0.0001)
t_e=np.linspace(0,60,1000)

s0 = np.array([0, 0, 1, 0])
sol_2=solve_ivp(f,[0,60],s0, t_eval=t_e) # method = 'Radau'
```

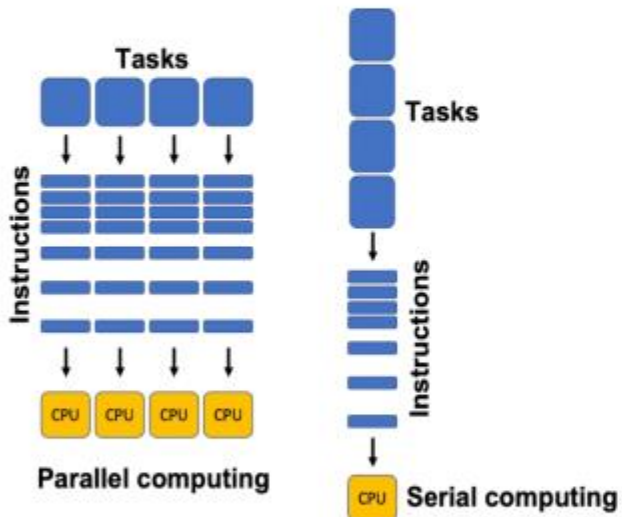
```
plt.figure(figsize = (8, 6))
plt.plot(t_e,y_I, label= 'Rectangular current pulse')
plt.plot(sol_1.t, sol_1.y[2], label= 'Componet  $m_z$  $ at G=8' )
plt.plot(sol_2.t, sol_2.y[2], label= 'Componet  $m_z$  $ at G=%4.2f' %G)
plt.xlabel('t', size=16)
plt.ylabel('$m_z(t)$', size=16)
plt.legend(fontsize=12)
plt.show()
```



```
#plt.figure(figsize = (8, 6))
fig, ax1 = plt.subplots(figsize=(8, 8))
# mask out the negative and positive values, respectively
#Zpos = np.ma.masked_less(alpG[:, :, 0], 0)
Z1 = Zc.reshape(N, N)
plt.imshow(Z1, interpolation='bilinear', cmap='Blues')
#plt.contourf(X, Y, Zc, 100)
#fig.colorbar(Zc, ax=ax1)
plt.show()
```



Parallel implementation with Python



Define a function called by each process

```
from joblib import Parallel, delayed
import numpy as np
```

```
def funk_parall(k):
    i=k%N
    j=k//N
    mz_sol=0
    G=G0+delta_G*i
    alpha=alpha0+delta_alpha*j
    f = partial(my_sfs, G=G, r=r, alpha=alpha, \
                As=As, t_s=t_s, delta_t=delta_t)
    t_e=np.linspace(0,60,1000)
    s0 = np.array([0, 0, 1, 0])
    sol_i=solve_ivp(f,[0,60],s0, t_eval=t_e) # method = 'Radau'
    if sol_i.y[2][999] < 0:
        mz_sol= -1
        # alpGxy[i+j*N,2] -= 1
    return mz_sol
```

Serial mode calculation

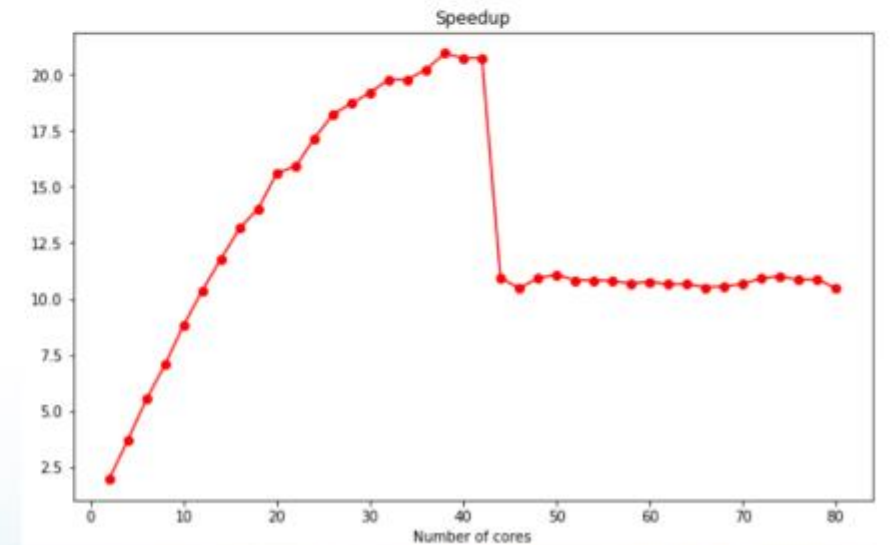
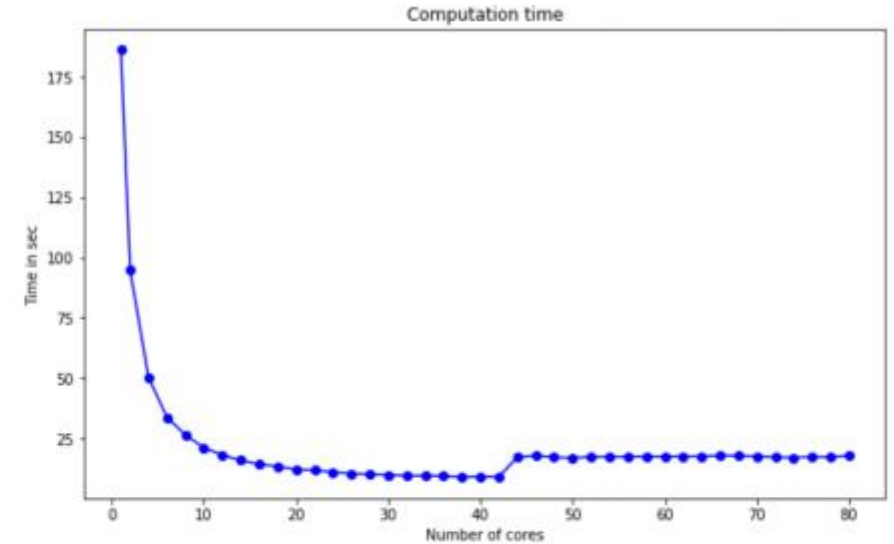
```
t0 = time.time()
rez= Parallel(n_jobs=1)\
    (delayed(funk_parall)(k) for k in range(N*N) )
t1 = time.time()
print(f'Execution time {t1 - t0} s')
```

Execution time 159.9254457950592 s

Computing in Parallel Mode

```
t0 = time.time()
rez= Parallel(n_jobs=6)\
    (delayed(funk_parall)(k) for k in range(N*N) )
t1 = time.time()
print(f'Execution time {t1 - t0} s')
```

Execution time 34.51503801345825 s



Computational environment for the numerical modelling

- Visualisation of simulation results
- Graphical interface for specifying input calculation parameters of models (geometric and physical parameters of models, numerical counting parameters)
- Implementation of the module for resource-intensive calculations on the GOVORUN supercomputer
- Debugging and testing of developed algorithms and modules



Computational environment for the numerical modelling

Magnetization Size Colors About

Load OVF1_TEXT files

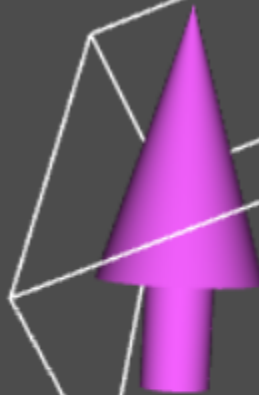
Выбрать файлы Число файлов: 508

m00015958.ovf FPS: 31

Play

Min Max

x-range y-range z-range



```
In [224]: import struct
          from IPython.display import FileLink, FileLinks

          def binary(num):
              return struct.pack('f', num)

          ovf_start_template = '''# OOVVF OVF 2.0
          # Segment count: 1
          # Begin: Segment
          # Begin: Header
          # Title: m
          # meshtype: rectangular
          # meshunit: m
          # xmin: 0
          # ymin: 0
          # zmin: 0
          # xmax: 9e-09
          # ymax: 3e-09
          # zmax: 1e-08
          # valuedim: 3
          # valueunits: m_x m_y m_z
          # desc: Total simulation time: 3.5091592894439995e-10 s
          # base: 1.5e-09
          # use: 1.5e-09
          # use: 5e-09
          # xnodes: 3
          # ynodes: 1
          # znodes: 1
          # xstepsize: 3e-09
          # ystepsize: 3e-09
          # zstepsize: 1e-08
          # End: Header
          # Begin: Data Binary 4
          ...

          ovf_end_template = '''# End: Data Binary 4
          # End: segment'''

          # array must be 2 dimensional with 3 items at line like
          # [
          # [-0.3, 0.1, 0.6],
          # [-0.1, 0.12, 0.96],
          # [-0.9, -0.1, 0.6],
          # ]
          def generate_ovf(input_array, skip_per_step = 0, items_per_frame = 1):
              with zipfile.ZipFile("file.zip", "w") as zip_file:
                  file_number = 1
                  for i in range(0, len(input_array), 1 + skip_per_step):
                      binary_section = generate_binary_start() + generate_line(input_array[i])
                      file_data = generate_file_data(binary_section)
                      zip_file.writestr(("m" + Format(file_number, '08') + ".ovf"), file_data)
                      file_number = file_number + 1
                  return FileLink("file.zip")

          def generate_binary_start():
              return binary(1234567.0)

          def generate_line(line):
              return binary(line[0])+binary(line[1])+binary(line[2])

          def generate_file_data(binary_section):
              return ovf_template1.encode('ascii') + binary_section + ovf_template2.encode('ascii')

          def generate_ovf_with_components(input_array_x, input_array_y, input_array_z, skip_count = 0, items_per_frame = 1):
              mas = []
              for i in range(0, len(input_array_x)):
                  mas.extend([[input_array_x[i], input_array_y[i], input_array_z[i]]])
              return generate_ovf(mas, skip_count, items_per_frame)

          #Использование
          generate_ovf_with_components(sol_1_RK.y[0], sol_1_RK.y[1], sol_1_RK.y[2], 9)

Out[224]: file.zip
```

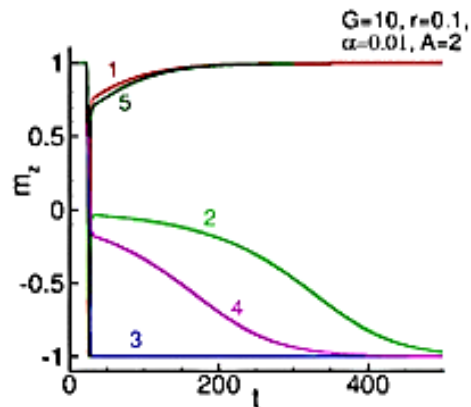
Computational environment for the numerical modelling

Numerical simulation of the magnetization reversal within the RF-SQUID model with φ_0 junction depending on the external magnetic field pulse

M.V. Bashashin, A.R. Rahmonova E.V. Zemlyanaya, Yu. M. Shukrinov, I.R. Rahmonov

Magnetic reversal

Magnetic reversal is an effect when m_z -component of the magnetic field changes the sign and takes the value **-1** for a given initial value of **+1**.



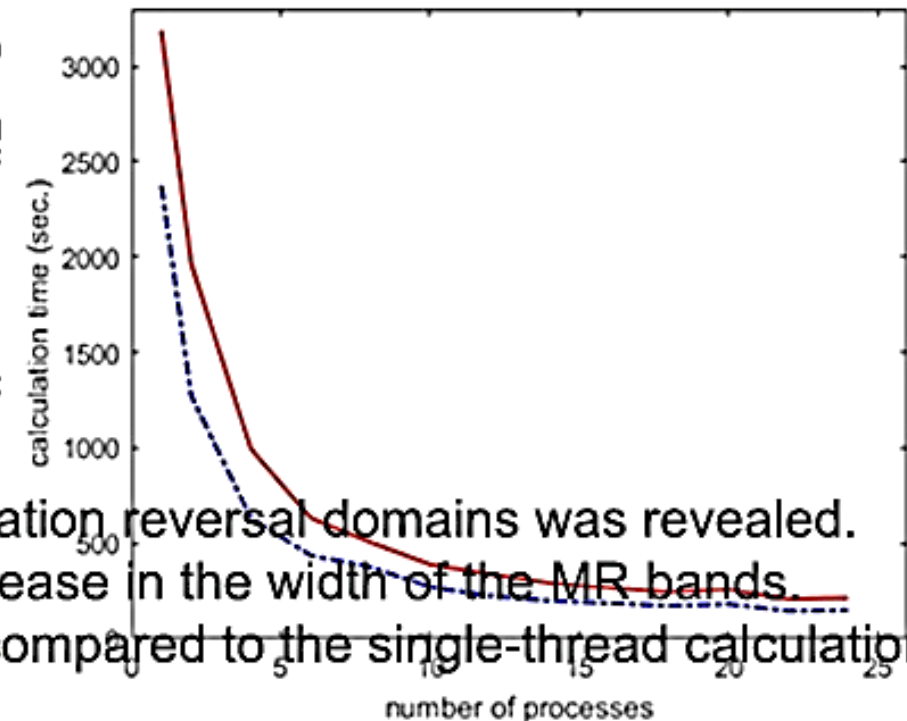
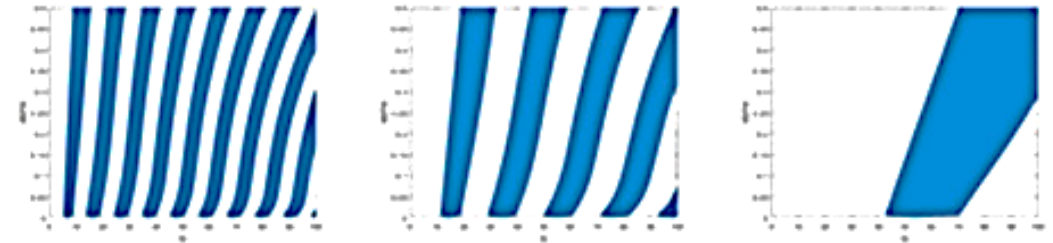
We analyze effect of the SQUID inductance L on MR. In

figure the time d = 1, 2, 3, 4, 5 for the numbers in 1 L .

- In case of $L = 1$ realized and c
- At $L = 3$ the fa acting of puls
- In case of the takes long tim
- At $L = 5$ again

Parallel implementation

- For the numerical solution of the system of n equations the Runge-Kutta method was used.
- The execution time of a serial C++ program of modeling magnetization reversal in the (G, α) -plane is 53 minutes (using Intel compiler).
- The parallelization process is based on the distribution of the (G, α) -plane between parallel threads. The values of G, α where the condition $|m_z(T_{max}) + 1| < \epsilon$ is satisfied, are saved in output structure and file.
- Maximal speedup of MPI implementation is about 15.5 times.
- The same parallelization scheme was used in case of simulation of magnetization reversal in multiple planes.
- Also, using a parallel implementation, the influence of the AVX instructions built into the latest versions of Intel server processors are available on the [Govorun](#) supercomputer.



The performed analysis allows us to conclude that MR has a period of π with respect to SQUID inductance.

The influence of the inductance parameter on the width of magnetization reversal domains was revealed. Shown that an increase in the inductance parameter leads to an increase in the width of the MR bands.

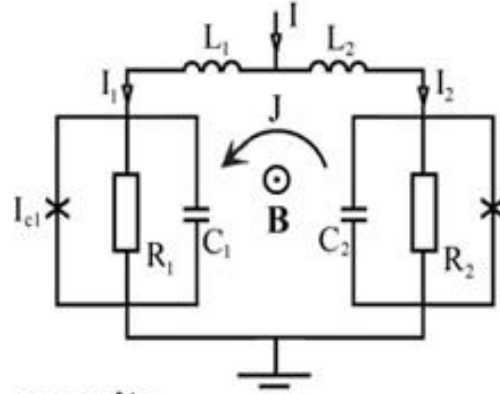
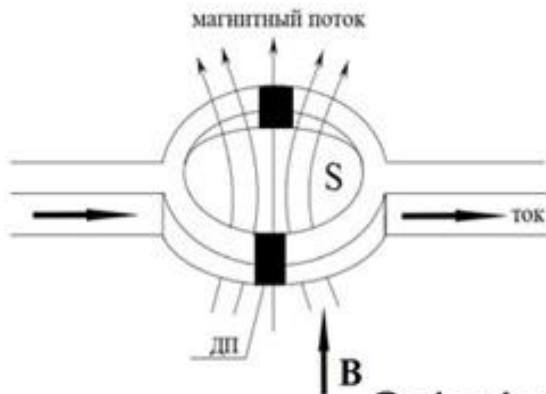
Max speedup of MPI + AVX-512 implementation is about 22 times compared to the single-thread calculation.

Computational environment for the numerical modelling

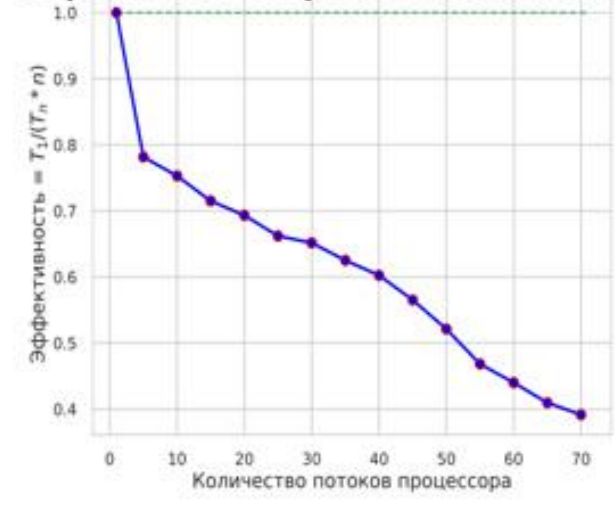
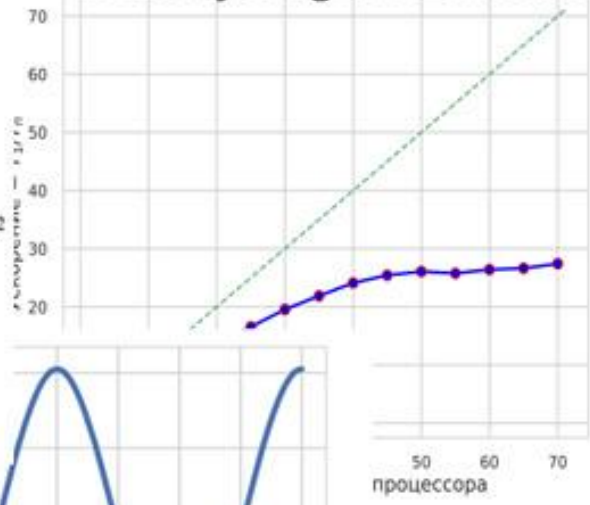
Simulation of the dynamics of a superconducting quantum interferometer with two Josephson junctions based on Python in the Jupyter Book environment

A.R. Rahmonova, O.I. Streltsova, M. Zuev, I.R. Rahmonov, A.V. Nechaevskiy

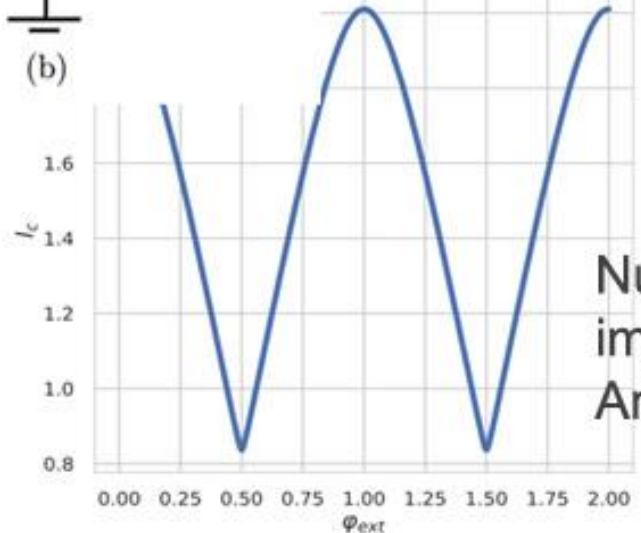
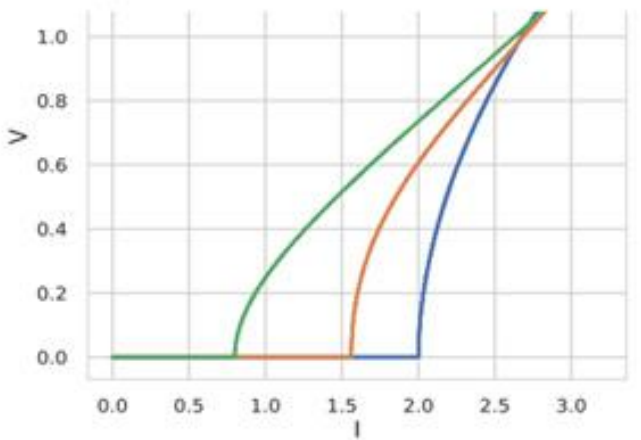
Mathematical model



Analysing the efficiency of parallel implementation



Calculation results



Numba lib was used in the software implementation of the developed algorithms. An acceleration of 27 times was achieved.

JBook is available: <http://studhub.jinr.ru:8080/squid>

JINR Autumn School on Information Technologies 2024

jupyter {book}

Practical lesson within the framework of the Autumn School on Information Technologies of JINR, October 7-11, 2024

Practical lesson within the framework of the JINR Autumn IT School-2024

Practical lesson within the framework of the JINR Autumn IT School-2024

Mathematical modeling of a Josephson superconductor/ferromagnetic junction on the surface of a topological insulator

Zuev M.I., Nechaevsky A.V., Rakhmonov I.R., Rakhmonova A.

The work was supported by the Russian Science Foundation

Project "Mathematical modeling of superconducting nanos controlling magnetization and magnetic excitations using J"

1. Introduction: Study of the for different values of param integration and approximat different values of paramete

Features of calculating the integral:

$$j_s = \int_{-\pi/2}^{\pi/2} \cos \varphi \exp\left(-\frac{\epsilon}{\cos \varphi}\right) d\varphi$$

Let's define the integrand function

```
def funct_js(phi, mx, r, d):  
    """ Defines the integrand in the definition of current js,  
        mx, r, d - parameters """  
    return (np.cos(phi) * np.exp(-d / np.cos(phi)) * np.cos(r*mx*np.tan(phi)))
```

```
d = 0.8  
r = 1.1  
mx = 0.5
```

```
funct_js(-np.pi/2, mx, r, d)
```

```
0.0
```

```
phi = np.linspace(-np.pi/2, np.pi/2, 1000)
```

```
y = funct_js(phi, mx, r, d)  
print(y.max(), y.argmax())
```

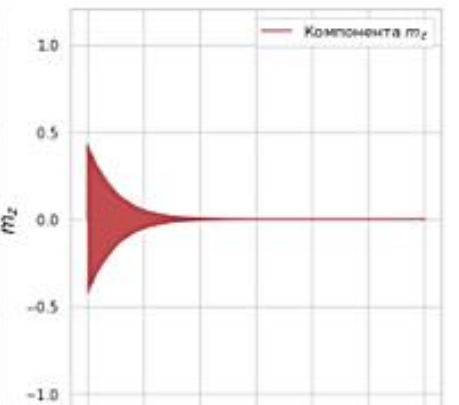
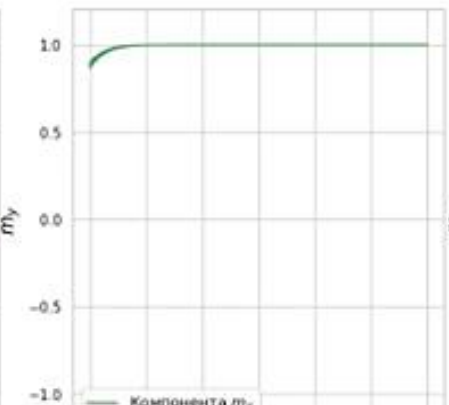
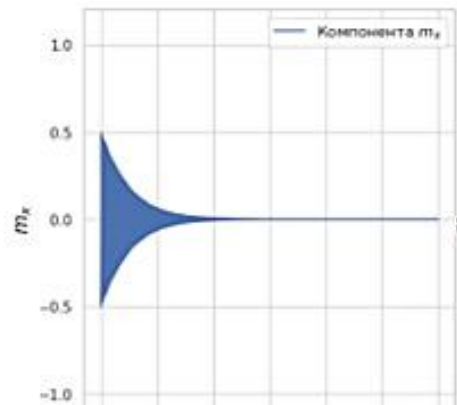
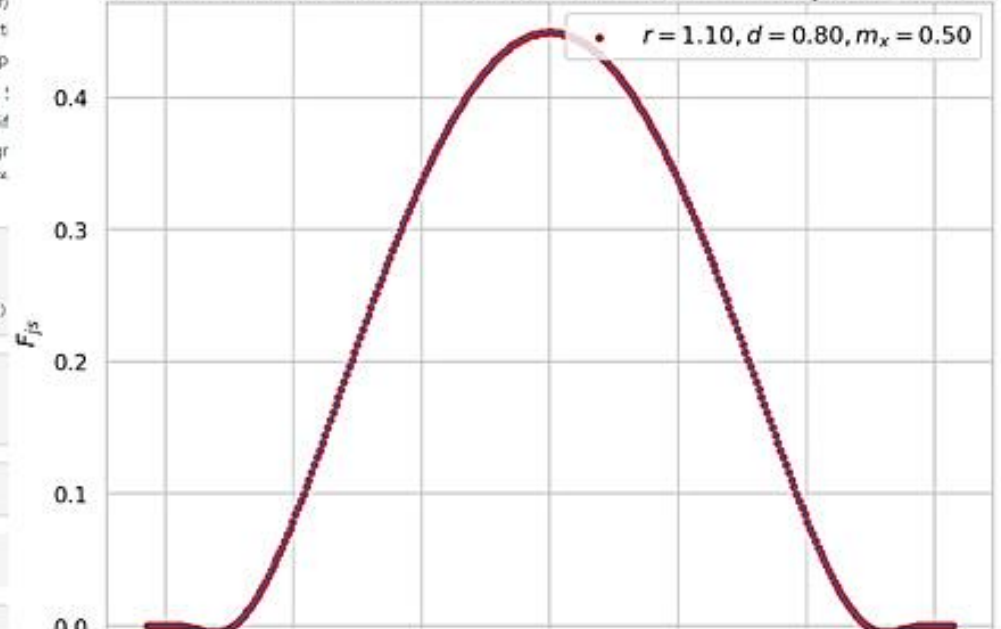
```
0.4493159274797835 149
```

```
plt.figure(figsize=(8, 6), dpi=100)  
plt.scatter(phi, y, edgecolor='r', s=36, zorder=2)  
plt.plot(phi, y)  
plt.xlabel(r"$\varphi$")  
plt.ylabel(r"$f_{js}$")
```

```
plt.title(r"Зависимость подынтегральной функции от угла $\varphi$")  
plt.legend(loc="upper right")  
plt.show()
```

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- superconductor,
- Josephson junct
- dimensional top
- 1. Introduction: !
- integrand for dif
- numerical integr
- integrals for diffe

Зависимость подынтегральной функции F_{js} от угла φ



Welcome to HLIT Jupyter Book

Основы работы с Python:
инструментарий на Python для
решения научных и прикладных
задач

Численное решение задачи Коши:
библиотека SciPy

Задача 1: Линеаризованное
уравнение на магнитный момент

Задача 2. Периодичность появления
интервалов переворота
намагниченности в $\langle \phi_0 \rangle$
джозефсоновском переходе под
воздействием импульса тока



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- [Численное решение задачи Коши: библиотека SciPy](#)
- [Задача 1: Линеаризованное уравнение на магнитный момент](#)
- [Задача 2. Периодичность появления интервалов переворота намагниченности в \$\langle \phi_0 \rangle\$ джозефсоновском переходе под воздействием импульса тока](#)

Next

[Основы работы с Python: инструментарий на Python для решения научных и прикладных задач](#) >

By A.R. Rahmonova, A.S. Vorontsov, A.V. Nechaevskiy, I.R. Rahmonov, M.V. Bashashin, M.I. Zuev, O.I. Streltsova, Y.A. Butenko.
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Conclusion

- Jupyter Notebook is an environment that enables users to create and execute Jupyter Notebooks.
- Notebooks are documents comprising live code, equations, visualisations and descriptive text.
- Notebooks can be executed in a multitude of programming languages, including Python, R, and Julia.
- Feasible to incorporate libraries and packages, including NumPy, Pandas, Matplotlib, and numerous others.
- Jupyter Binder enables users to run Jupyter notebooks in a web browser without requiring authorisation or the installation of software on the local machine.
- The developed platform allows users to perform sophisticated data analysis, numerical calculations and visualisation tasks with minimal effort on the HybriLIT platform.
- Project is create new opportunities for the study of hybrid nanostructures.

Project Team



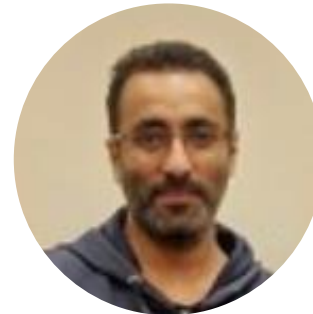
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