

Comparison of Python 3 Single-GPU Parallelization Technologies on Example of Charged Particles Dynamics Simulation Problem

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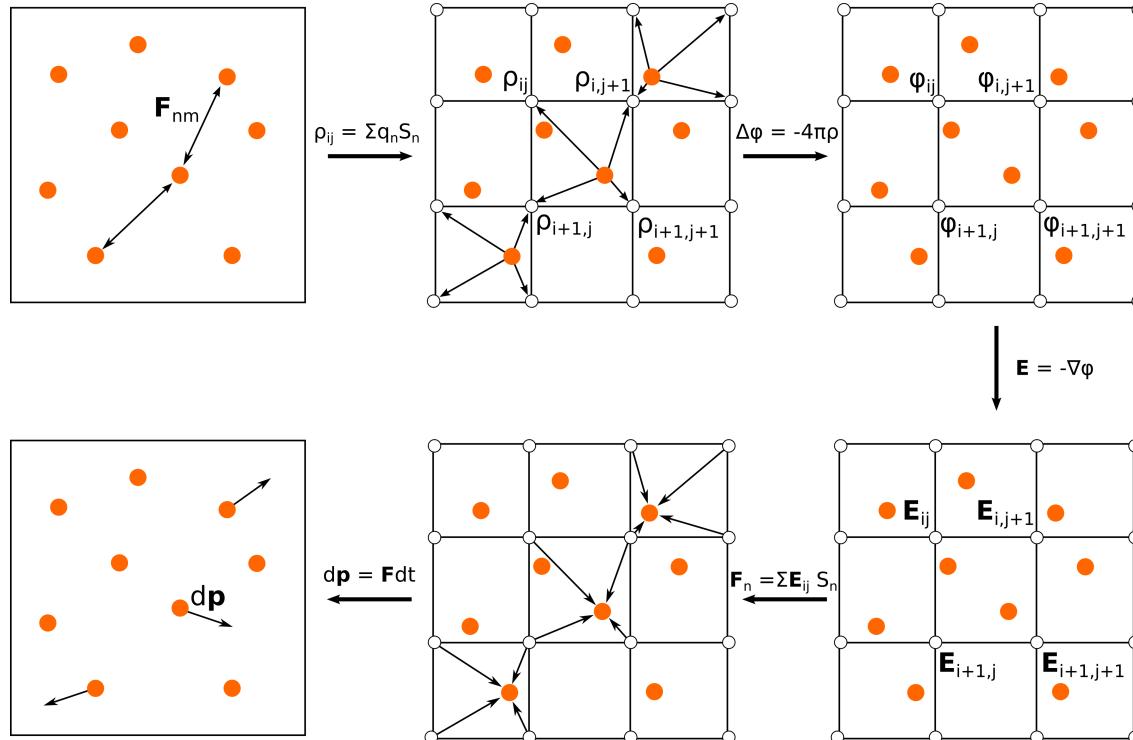
General motivation

Ion source simulation



Concrete motivation

Particle-in-cell simulation



Python

Fast development

Slow computing

GPU

Slow development

Fast computing

Libraries

Python development

GPU computing

Candidate libraries

Numba

CUDA (Nvidia)

Python decorators

@jit

```
def sum2d(arr):
```

...



PyCUDA

CUDA (Nvidia)

Compiled string of CUDA code

```
mod = SourceModule("__global__ void  
region_update_vels_from_bin_interact  
ion(float reg, float reg_5, ...
```

PyOpenCL

OpenCL

on CUDA

Compiled string of OpenCL code

```
program = cl.Program(reg["ctx"],  
"""
```

```
_kernel void update_position(  
_global const unsigned int *id,
```

...



Testing platform

Google Colaboratory

NVidia Tesla K80

Shared IPython notebooks

Easy collaboration

Common environment



The screenshot shows the Google Colaboratory interface. At the top, it says "test_numba.ipynb" and "[OFFLINE]". The menu bar includes File, Edit, View, Insert, Runtime, Tools, and Help. Below the menu is a toolbar with CODE, TEXT, CELL, COPY TO DRIVE, and other options. The code cell contains the following Python code:

```
n_of_particles = 1000
saving t = 15 to sim_15.png
from t = 16 to 17 of 20
n_of_particles = 1000
from t = 17 to 18 of 20
n_of_particles = 1000
from t = 18 to 19 of 20
n_of_particles = 1000
from t = 19 to 20 of 20
n_of_particles = 1000
saving t = 20 to sim_20.png
```

The next cell contains:

```
[ ] from IPython.display import Image
display(Image("./sim_10.png"))
#display(Image("./sim_10_gpu.png"))
```

Below the code cells is a scatter plot titled "t = 10". The plot shows numerous small, colored dots representing particles scattered across a 2D plane with axes labeled X and Y, both ranging from 0.0 to 1.0.

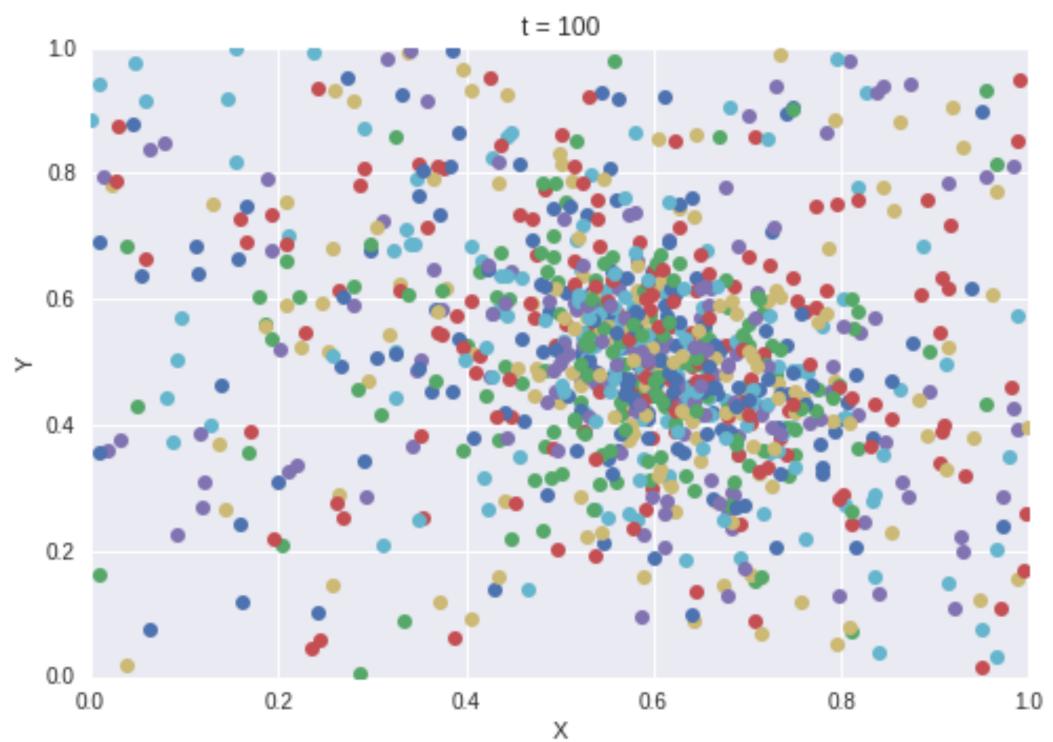
Sample task

2d simulation

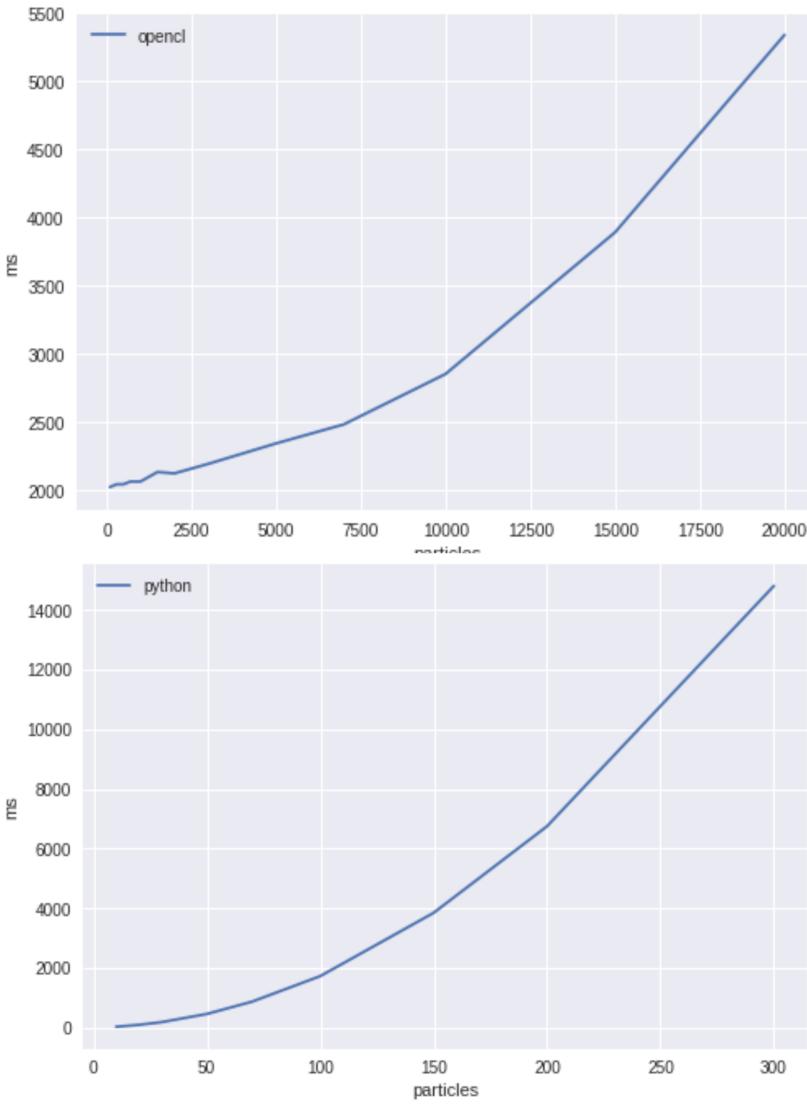
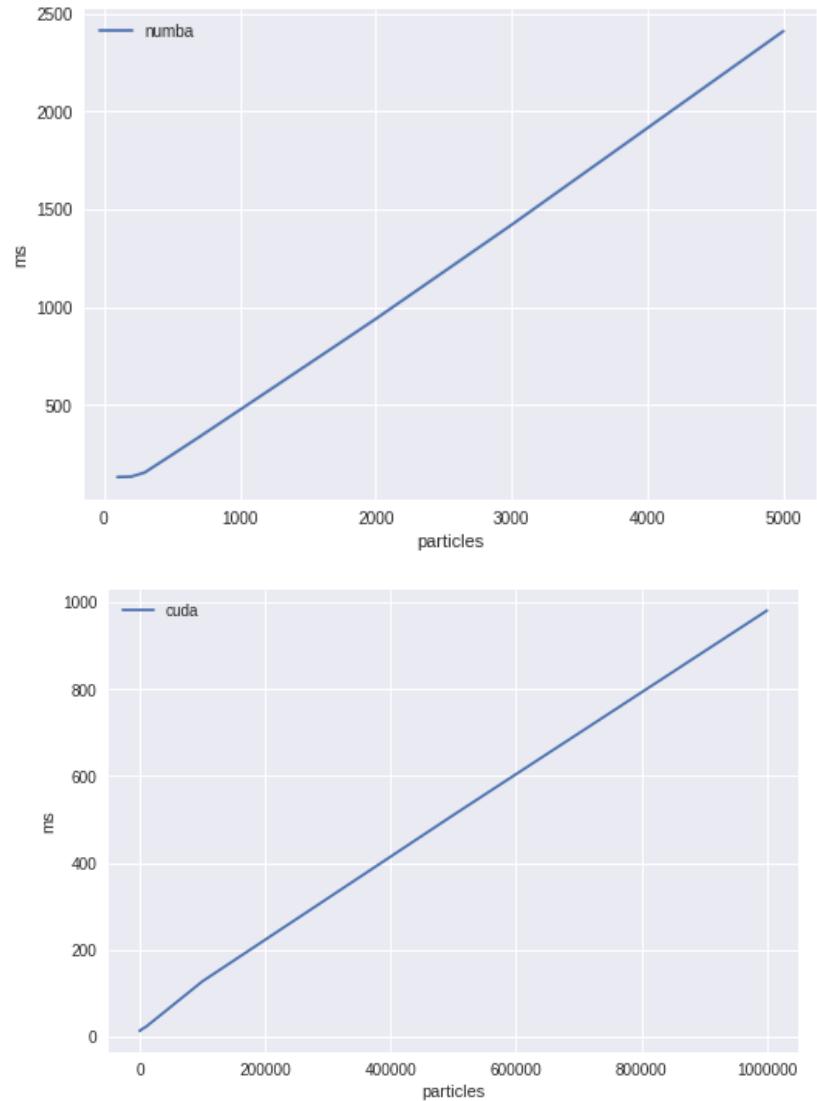
Pair interaction (no PIC!)

100 time steps

10 to 1 000 000 particles



Results



Conclusions

Performance is very dependant on library

Todo: review implementation details

Todo: implement and compare PIC

Google Colaboratory is convenient

Can we test on local hardware

Can we test on HybriLIT

GPUs are orders of magnitude faster

Our problem can parallelize

Implement it into the simulation project as soon as possible

Acknowledgements

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