Vogel's algebra and its application to the knot invariants

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Content

1 Motivation:

Knotsevich integralvsChern-Simons theory(universal Vassiliev invariant)(quantum knot invariants)

- 2 Vassiliev invariants, chord and closed Jacobi diagrams
- 3 Vogel's algebra Λ
- 4 Characters of Λ
- 6 Universality of Lie algebras
- 6 Kernel of Lie algebras weight systems
- Implications for knot invariants

Chern-Simons theory

The Chern-Simons action for the vector field $A_{\mu} = A^{a}_{\mu}T^{a}$ is

$$S(A) = \frac{\kappa}{4\pi} \int_{S^3} d^3 x \epsilon^{\mu\nu\rho} \operatorname{tr} \left(A_{\mu} \partial_{\nu} A_{\rho} + \frac{2}{3} A_{\mu} A_{\nu} A_{\rho} \right)$$
(1)

Gauge algebra is \mathfrak{g} , $\hbar = \frac{2\pi i}{\kappa + N}$ is a coupling constant. Gauge invariant functions of A_{μ} are given by Wilson loops,

$$\langle W_R(\mathcal{K}) \rangle = \frac{1}{Z} \int \mathcal{D}A \, e^{iS(A)} \, \operatorname{tr}_R \left(\operatorname{Pexp} \, i \oint_C A_\mu dx^\mu \right)$$
(2)

which determine topological knot and link invariants \mathcal{K} [A.Schwartz'1987; E.Witten'1989]. Chern-Simons partition function is $Z = \int \mathcal{D}A \ e^{iS(A)}$.

Knot theory

Definition

A knot \mathcal{K} is an embedding of the circle into the three-dimensional Euclidean space $\mathcal{K}: S^1 \hookrightarrow \mathbb{E}^3$.











torus knot [15,-4]

Ambient isotopy is an equivalence relation on knots.



Holomorphic gauge for the CS theory

Following [Labastida, J. M. F., Perez, E., 1998]:

- 1 Wick rotation $A_z^a = A_1^a iA_2^a$, $A_{\overline{z}}^a = A_1^a + iA_2^a$;
- **2** fix gauge $A_{\bar{z}} = 0$;
- **3** quadratic action $S(A)|_{A_{\overline{z}}=0} = i \int dt d\overline{z} dz \, \epsilon^{mn} A^a_m \partial_{\overline{z}} A^a_n$;
- 4 pair correlator

$$\langle A_m^a(t_1, z_1, \bar{z}_1) A_n^b(t_2, z_2, \bar{z}_2) \rangle = \epsilon_{mn} \, \delta^{ab} \, \frac{\hbar}{2\pi i} \frac{\delta(t_1 - t_2)}{z_1 - z_2};$$

6 Wick theorem.

Answer for the vacuum expectation value

$$\langle W_{R}(K) \rangle = \sum_{n=0}^{\infty} \frac{\hbar^{n}}{(2\pi i)^{n}} \times \int_{o(z_{1}) < \ldots < o(z_{n})} \sum_{\substack{p \in P_{2n} \\ p \in P_{2n}}} (-1)^{p_{\downarrow}} \bigwedge_{k=1}^{n} \frac{dz_{i_{k}} - dz_{j_{k}}}{z_{i_{k}} - z_{j_{k}}} \times \operatorname{tr}_{R} \left(T^{a_{\sigma_{p}(1)}} T^{a_{\sigma_{p}(2)}} \dots T^{a_{\sigma_{p}(2n)}} \right)$$
(3)

Vassiliev invariants and group factors

From this expansion we see that the information about the knot and the gauge group $\langle W_R(\mathcal{K}) \rangle$ contributes separately. The information about the embedding of knot into S^3 is encoded in the integrals of the form [Birman,Lin'1993; D.Bar-Natan'1995]:

$$v_{n,m}^{\mathcal{K}} \sim \int\limits_{o(z_1) < ... < o(z_n)} \sum_{p \in P_{2n}} (-1)^{p_{\downarrow}} \bigwedge_{k=1}^n rac{dz_{i_k} - dz_{j_k}}{z_{i_k} - z_{j_k}}$$

and the information about the gauge group and representation enter the answer as the group factors:

$$G_{n,m}^{\mathfrak{g},R} \sim \operatorname{tr}_{R} \Big(T^{\mathfrak{a}_{\sigma_{p}(1)}} T^{\mathfrak{a}_{\sigma_{p}(2)}} ... T^{\mathfrak{a}_{\sigma_{p}(2n)}} \Big).$$

Thus, schematically one can rewrite the perturbative series as follows

$$\langle W_{R}^{\mathfrak{g}}(\mathcal{K}) \rangle = \sum_{n=0}^{\infty} \hbar^{n} \cdot \sum_{m=1}^{\mathcal{N}_{n}} G_{n,m}^{\mathfrak{g},R} \cdot v_{n,m}^{\mathcal{K}}, \qquad (4)$$

where \mathcal{N}_n is the number of independent group elements of degree *n*.

Vassiliev invariants

Definition (Singular knots)

A singular knot is an isotopy class of S^1 immersions in \mathbb{R}^3 such that all self-intersection points are simple double points with transversal intersections.



The continuation of knot invariants to the set of singular knots is determined by *Vassiliev skein relation*:

$$\boldsymbol{\mathcal{V}}(\boldsymbol{\mathcal{V}}) = \boldsymbol{\mathcal{V}}(\boldsymbol{\mathcal{V}}) - \boldsymbol{\mathcal{V}}(\boldsymbol{\mathcal{V}})$$

Definition (Vassiliev invariants, [V.Vassiliev'1990])

A knot invariant v is called a Vassiliev invariant of order no more than n if v vanishes at singular knots with $\ge n + 1$ double points.

Relations on Vassiliev invariants

Vassiliev invariants satisfy the following relations



Theorem

The product of two Vassiliev invariants of orders $\leq n$ and $\leq m$ is a Vassiliev invariants of order $\leq n + m$

$$v_n \cdot v_m = v_{n+m}$$

Chord diagrams

Definition

A chord diagram of order n is an oriented circle with n pairs of distinct points. The set of chord diagrams of order n is denoted A_n .

$$\mathbf{A}_1 = \langle \bigcirc \rangle, \quad \mathbf{A}_2 = \langle \bigcirc \rangle, \quad \cdots \rangle$$

Definition

Algebra of chord diagrams is a vector space $A_n = \mathbf{A}_n / \langle 4T, 1T \rangle$ modulo the four-term and the one-term relations



Knotsevich integral

Definition (Weight systems)

The space of weight systems $W_n = A_n^* = \text{Hom } (A_n, \mathbb{R})$ is a space of linear functions on A_n .

Theorem (Vassiliev-Kontsevich theorem)

$$\mathcal{W} = \bigoplus_{n=0}^{\infty} \mathcal{W}_n \cong \bigoplus_{n=0}^{\infty} \mathcal{V}_n / \mathcal{V}_{n-1} = \mathcal{V}$$
(6)

Kontsevich integral is the generating function for Vassiliev invariants

$$I(\mathcal{K}) = \sum_{n=0}^{\infty} \hbar^n \sum_{m=1}^{\dim \tilde{\mathcal{V}}_n} D_{n,m} \cdot v_{n,m}^{\mathcal{K}},$$
(7)

Lie algebra weight systems

Choose a basis $T^1, ..., T^r$ of g and let $T_1, ..., T_r$ be the dual basis with respect to the non-degenerate bilinear form [D.Bar-Natan'1995].

$$\varphi_{\mathfrak{g}}^{R}: \mathcal{A}_{n} \to ZU(\mathfrak{g}), \quad D \mapsto \operatorname{tr}_{R} \left(T^{a}T^{b}...\right)$$

$$D_{2,1} = \underbrace{\left(\begin{array}{c}a & b\\ \hline & \\\end{array}\right)}_{\mathcal{C}}, \quad \varphi_{\mathfrak{g}}^{R}(D_{2,1}) = \operatorname{tr}_{R} \left(\sum_{a,b,c=1} T^{a} T^{b} T^{c} T_{b} T_{a} T_{c}\right)$$

$$\varphi_{\mathfrak{g}}^{R}\left(D_{n,m}\right) = G_{n,m}^{\mathfrak{g},R}$$

$$\varphi_{\mathfrak{g}}^{R}\left(I(\mathcal{K})\right) = \sum_{n=0}^{\infty} \hbar^{n} \sum_{m=1}^{\dim \tilde{\mathcal{V}}_{n}} \varphi_{\mathfrak{g}}^{R}\left(D_{n,m}\right) \cdot \mathbf{v}_{n,m}^{\mathcal{K}} = \langle W_{R}^{\mathfrak{g}}(\mathcal{K}) \rangle$$

$$(9)$$

Are all Vassiliev invariants contained in quantum knot invariants for all possible semisimple Lie (super)algebras g? Vogel's answer (2011) is no, because $\bigcap_{\mathfrak{g},R} \operatorname{Ker} \varphi_{\mathfrak{g}}^{R} \neq \varnothing$.

Closed Jacobi diagrams

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Definition (Jacobi diagrams $\mathcal{C} = \bigoplus_n \mathcal{C}_n$)

The space of Jacobi diagrams C_n is a linear space generated by connected graphs having 2n trivalent vertices, as well as having a distinguished cycle (vertices on this cycle are called external), the remaining (internal) vertices are equipped with a cyclic order of half-edges, modulo the STU relation:



Figure: Product of Jacobi diagrams

Isomorphism of diagrams: $A_n \cong C_n / \langle 1T \rangle$ \bigcirc \bigcirc \bigcirc \bigcirc

Figure: Examples of Jacobi diagrams

Chord diagrams are a special type of Jacobi diagrams.

Theorem (D.Bar-Natan'1995)

 $\mathbf{A}_n/\langle 4T \rangle \cong \mathcal{C}_n$, and $\mathcal{A}_n \cong \mathcal{C}_n/\langle 1T \rangle$.

The space of *primitive* Jacobi diagrams \mathcal{P} is a subspace of \mathcal{C} linearly generated by Jacobi diagrams with a connected internal graph. The STU relation imposes additional constraints on an internal graph of Jacobi diagrams:



Don't get lost

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Vogel's algebra Λ

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Definition (Algebra Λ)

A is an algebra over \mathbb{Q} , generated by 3-legged 3-valent diagrams (legs are numerated) modulo AS and IHX relations, antisymmetric with respect to permutations of legs. Multiplication in A is given by insertion of one factor into any vertex of the other factor.



Jacobi diagrams as A-module

A-algebra naturally acts on closed Jacobi diagrams (with connected internal graph):



Theorem

Let $\hat{\lambda} \in \Lambda$ and $u \in C$ is the "Mercedes-Benz". Then the element $\hat{\lambda} \cdot u$ is also non-zero primitive in C.

$\Lambda: \text{generators}$

- The structure of the algebra Λ is unknown.
- The dimension of Λ is known up to order 10, because Λ-algebra is isomorphic to the algebra of 3-graphs, defined in [Chmutov-Duzhin-Kaishev'1998].
- Λ-algebra is a commutative.
- There exists a unique graded algebra homomorphism

 $\psi: \mathbb{Q}[t] \oplus \omega \mathbb{Q}[t, \sigma, \omega] \to \Lambda,$

where formal variables deg(t) = 1, deg(σ) = 2 and deg(ω) = 3. ψ is bijective for the degree \leq 10 and injective for the degree \leq 15. In degree 16 Ker ψ is nonzero.

Λ : examples

$$\psi: \mathbb{Q}[t] \oplus \omega \mathbb{Q}[t, \sigma, \omega] \to \Lambda.$$

Example

$$\psi(t) = \hat{t} = \frac{1}{2}\hat{x}_{1}, \qquad \psi(t^{2}) = \hat{t}^{2} = \hat{x}_{2},$$

$$\psi(4t^{3} - \frac{3}{2}\omega) = \hat{x}_{3}, \qquad \psi(12t^{5} - \frac{17}{2}t^{2}\omega + \frac{3}{2}\sigma\omega) = \hat{x}_{5}.$$

$$\hat{1} = \underbrace{\qquad} \qquad \hat{t} = \underbrace{\qquad} \qquad \hat{x}_{n} = \underbrace{\qquad} \qquad \hat{x}_{$$

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Λ : generalized weight system

Simple Lie algebra \mathfrak{g} (over field K) with non-degenerate bilinear form gives a weight system on Λ by the map

$$\Phi_{\mathfrak{g}}:\Lambda
ightarrow \mathfrak{g}^{\otimes 3}, \ \checkmark \qquad \mapsto \ f_{abc}$$

Then AS means anticommutativity, IHX means Jacobi identity. Any simple Lie algebra g has only 1 primitive 3-tensor:

$$\Phi_{\mathfrak{g}}(\hat{x}) = \chi_{\mathfrak{g}}(\hat{x}) f_{abc},$$

where $\chi_{\mathfrak{g}}(\hat{x}) : \Lambda \to K$ is a well-defined character. It is a polynomial in t, σ, ω .

Characters

Characters $\chi_{\mathfrak{g}}(\hat{x})$ are polynomials in t, σ, ω .

$$P_{sl} = -2t^{3} + 2\sigma t - \omega$$

$$P_{osp} = -24\sigma t^{4} + 40\omega t^{3} + 29\sigma^{2}t^{2} - 72\omega\sigma t + 4\sigma^{3} + 27\omega^{2}$$

$$P_{exc} = 40t^{3} - 45\sigma t + 27\omega$$

Lie algebra	t	σ	ω
$A_n = \mathfrak{sl}_{n+1}$	n+1	$2n^2 + 4n - 2$	$2(n^2-1)(n+3)$
$B_n = \mathfrak{so}_{2n+1}$	2 <i>n</i> – 1	4(n+1)(2n-3)	4(n-1)(2n+3)(2n-3)
$C_n = \mathfrak{sp}_{2n}$	n+1	(n+2)(2n-1)	(n-1)(2n+3)(n+2)
$D_n = \mathfrak{so}_{2n}$	2 <i>n</i> – 2	4(2n+1)(n-2)	8(n-2)(2n-3)(n+1)
G ₂	4	260/9	880/9
F ₄	9	170	1470
E ₆	12	308	3600
E ₇	18	704	12480
E ₈	30	1976	58800
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Kernel of sl_n weight system

Up to degree 10 calculate from Vogel's algebra [D.Khudoteplov, E.Lanina, A.S., 2024]:

n=8:
$$\widehat{\omega P_{sl}} \cdot \bigcirc \Rightarrow \dim \operatorname{Ker} \varphi_{sl_n}(\mathcal{P}_n) = \mathbf{1}$$

If $\hat{\lambda} \neq 0 \in \Lambda$ and D is the "Mercedes-Benz" diagram in C, then $\hat{\lambda} \cdot D \neq 0$ is also nonzero primitive diagram.

$$\mathbf{n=9:} \quad \hat{t} \cdot \widehat{\omega P_{sl}} \cdot \bigodot, \quad \psi(P_{sl}) \cdot \bigodot \Rightarrow \dim \operatorname{Ker} \varphi_{sl_n}(\mathcal{P}_n) = \mathbf{2}$$
$$\mathbf{n=10:} \quad \hat{t}^2 \cdot \widehat{\omega P_{sl}} \cdot \bigodot, \quad \widehat{\omega \sigma P_{sl}} \cdot \bigodot, \quad \hat{t} \cdot \psi(P_{sl}) \cdot \bigodot,$$
$$\widehat{\omega P_{sl}} \cdot \bigodot, \quad \psi(P_{sl}) \cdot \bigodot + \hat{t} \cdot \bigodot \Rightarrow \dim \operatorname{Ker} \varphi_{sl_n}(\mathcal{P}_n) = \mathbf{5}$$

Kernel of all Lie algebras weight system

$$\psi(\omega P_{sl}P_{osp}P_{exc}) = \hat{\lambda}$$

Let \hat{U} be the following 6-legged diagram



then we define $\hat{\lambda} \neq 0 \in \Lambda$ by removing a trivalent vertex from V:

$$V = \sum_{\sigma \in S_6} \operatorname{sign}(\sigma) \cdot \underbrace{\hat{U}}_{\sigma} \quad \sigma \quad \hat{U}_{\sigma} = \widehat{\lambda} \quad \text{remove}$$
$$D_{17} := \widehat{\lambda} \cdot \underbrace{\bigcirc}_{\sigma} \neq 0$$
$$\Phi_{\mathfrak{g}}(D_{17}) = \Phi_{\mathfrak{g}}(\widehat{\lambda} \cdot \widehat{t}) \cdot \Phi_{\mathfrak{g}}(\bigcirc) = 0 \quad (10)$$
Zero divisor: $\widehat{t} \cdot \widehat{\lambda} = 0, \quad \widehat{t} = \bigwedge, \quad (2 \cdot 3 = 0 \mod 6, \text{ where } 2, 3 \neq 0)$

Conclusion

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Vogel's Λ-algebra implies:

- Universal formulas for various contractions of Lie algebra structure constants (*universal Lie algebra*?)
- Alternative approach (zero divisor) to the classification of Lie algebras from knot invariants
- ${f 3}$ Explicit description for kernels of Lie algebra ${f g}$ weight system
- Infinitely many Vassiliev invariants are absent in the Chern-Simons invariants

Today it cannot be claimed that we can distinguish more knots using Vassiliev invariants than using the Chern-Simons invariants (Jones, HOMFLY-PT, Kauffman, etc. polynomials).

Thank you for your attention!

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