Lagrangian manifolds and Petrovsky surfaces corresponding to short-wave asymptotics for hyperbolic systems with abruptly varying coefficients.

> Andrei Shafarevich Joint work with Anna Allilueva

> > PMMP-25

February 13, 2025

・ロト ・聞 ト ・ ヨ ト ・ ヨ ト

Outline



Strictly hyperbolic systems with smooth coefficients

2 Strictly hyperbolic systems with singular coefficients

 Reflection and transmission of Lagrangian manifolds. Ramifying Hamiltonian billiards and Petrovsky surfaces.

- Amplitudes of transmitted and reflected waves. Discontinuous coefficients.
- Smoothed discontinuity. Model equation.

Hyperbolic systems

$$(-i\frac{\partial}{\partial t})^{m}u = A(t, x, -i\frac{\partial}{\partial t}, -i\frac{\partial}{\partial x})u,$$

 $x \in \mathbb{R}^{n}, \quad u \in \mathbb{C}^{I}, \quad A(t, x, p_{0}, p) - I \times I \quad matrix.$

Matrix $A(t, x, p_0, p)$ is polynomial of degree m in (p_0, p) , smooth in (t, x) and does not depend on (x, t) outside a compact. Hyperbolicity in Petrovsky sense: equation

$$\det(p_0^m-A_m)=0$$

has *mI* real roots $p_0 = -H_k(t, x, p)$, distinct if $p \neq 0$.

▲口 > ▲ □ > ▲ □ > ▲ □ > ▲ □ > ▲ □ > ▲ □ > ▲ □ >

Examples

1. One-dimensional systems

$$\frac{\partial u}{\partial t} = A(t,x)\frac{\partial u}{\partial x}, \quad x \in \mathbb{R}, \quad H_k = \lambda_k(t,x)p,$$

 λ_k — eigenvalues of *A*. 2. Wave equation

$$rac{\partial^2 u}{\partial t^2} = c^2(t,x)\Delta u, \quad x \in \mathbb{R}^n, \quad H_{1,2} = \pm c(t,x)|p|.$$

▲□▶ ▲□▶ ▲目▶ ▲目▶ - 目 - のへで

3. Linearized shallow-water equations

$$\begin{split} &\frac{\partial u}{\partial t} + (V(t,x),\nabla)u + (u,\nabla)V(t,x) + \nabla\eta = 0, \\ &\frac{\partial \eta}{\partial t} + (\nabla,\eta V(t,x)) + (\nabla,c^2(t,x)u) = 0, \quad x \in \mathbb{R}^2, \\ &H_1 = (V,p), \quad H_{2,3} = (V(t,x),p) \pm c(t,x)|p| \end{split}$$

4. Massless (2 + 1)- Dirac equations

$$i\frac{\partial u}{\partial t} = \begin{pmatrix} 0 & -i\frac{\partial}{\partial x_1} + \frac{\partial}{\partial x_2} \\ -i\frac{\partial}{\partial x_1} - \frac{\partial}{\partial x_2} & 0 \end{pmatrix} u + V(t,x)u, \quad H_{1,2} = \pm |p|$$

・ロト・日本・日本・日本・日本・日本

Short-wave initial conditions

$$u|_{t=0} = \varphi^0(x)e^{\frac{iS_0(x)}{h}}, \quad (\frac{\partial}{\partial t})^j u|_{t=0} = 0, \quad j = 1, \dots, m-1, \quad h \to 0.$$

 $S_0\in {old C}^\infty({\mathbb R}^n),\, arphi^0\in {old C}_0^\infty({\mathbb R}^n).$ Two cases

- S₀ real-valued (rapidly oscillating wave packet);
- S₀ complex-valued, ℑS₀ ≥ 0, ℑS₀ = 0 ⇔ x ∈ W₀, W₀
 smooth *k*-dimensional surface, d²ℑS₀|_{NW} > 0 (squeezed state).

Strictly hyperbolic systems with smooth coefficients

Strictly hyperbolic systems with singular coefficients



Figure: Wave packet



Strictly hyperbolic systems with smooth coefficients

Strictly hyperbolic systems with singular coefficients

アノ

Figure: Squeezed state



Construction of asymptotics. Small times — without focal points $(\Lambda_k^t : p = \frac{\partial S_k(t,x)}{\partial x})$ — WKB-formulae

$$u \sim \sum_{k=1}^{ml} e^{\frac{iS_k(t,x)}{h}} (\sum_{s=0}^{\infty} h^s \varphi_{k,s}(t,x)),$$

$$\frac{\partial S_k}{\partial t} + H_k(t, x \frac{\partial S_k}{\partial x}) = 0, \quad S_k|_{t=0} = S_0(x).$$

▲□▶▲圖▶▲臣▶▲臣▶ 臣 のへ⊙

Arbitrary finite time. Phase space $\mathbb{R}^{2n}_{(x,p)}$; initial Lagrangian surface $\Lambda_0 : p = \frac{\partial S_0}{\partial x}$. Hamiltonan systems

$$\dot{x} = \frac{\partial H_k}{\partial p}, \quad \dot{p} = -\frac{\partial H_k}{\partial x}.$$

イロト イポト イヨト イヨト

Lagrangian surfaces $\Lambda_k^t = g_k^t \Lambda_0$. Volume forms $\sigma_0 = dx$ on Λ_0 , $\sigma_t = (g_k^t)^* dx$ on Λ_k^t .

Strictly hyperbolic systems with smooth coefficients

Strictly hyperbolic systems with singular coefficients



Figure: Lagrangian surface

▲□▶▲圖▶▲≣▶▲≣▶ ≣ のQで

Theorem

(V.P. Maslov, \sim 1965). Under certain technical conditions the solution u(x, t, h) can be represented as asymptotic series

$$u \sim \sum_{k=1}^{ml} K_{\Lambda_k^t, \sigma_k^t} (\sum_{s=0}^{\infty} h^s \varphi_{k,s}),$$

 $K: C_0^{\infty}(\Lambda_k^t) \to C^{\infty}(\mathbb{R}_x^n)$ is the Maslov canonical operator, $\varphi_{k,s}$ are smooth functions on Λ_t^t , computed recurrently in terms of Hamiltonian trajectories; $\varphi_{k,0}$ are eigenvectors of $A_m(t, x, -H_k, p)$.

Sqeezed states. Simplest case:

$$S_0 = (p_0, x - x_0) + rac{1}{2}(x - x_0, Q_0(x - x_0))), \quad p_0 \in \mathbb{R}^n, Q^t = Q, \Im Q > 0.$$

 W_0 is the point x_0 , $\rho_0 : \xi_p = Q_0 \xi_x$.

$$u(x,t,h) \sim \sum_{k=1}^{ml} e^{\frac{iS_k(x,t)}{h}} \sum_{s=0}^{\infty} (h^s \varphi_{k,s}(x,t)).$$

$$S_k = q_k(t) + (P_k(t), x - X_k(t)) + \frac{1}{2}(x - X_k(t), Q_k(t)(x - X_k(t))),$$
$$\dot{X}_k = \frac{\partial H_k}{\partial p}, \quad \dot{P}_k = -\frac{\partial H_k}{\partial x},$$

イロト イポト イヨト イヨト

Q can be expressed explicitly in terms of solutions of the linearized system.

Solutions, corresponding to complex vector bundles

Solutions, corresponding to complex vector bundles Localized ("squeezed") initial state $S_0(x)$ is complex, $\Im S_0 \ge 0$, $\Im S_0 = 0$ on the smooth *k*-dimensional surface W_0 , $d^2 \Im S_0|_{NL_0} > 0$. Consider *k*-dimensional isotropic surface $\Lambda_0 \subset \mathbb{R}^{2n}$: $x \in W_0$, $p = \frac{\partial S_0}{\partial x}$ and *n*-dimensional complex vector bundle ρ_0 over Λ_0 (Maslov complex germ): fiber $\rho(x, p)$ is the plane in ${}^{\mathbb{C}} T_{x,p} \mathbb{R}^{2n}$, $\xi_p = \frac{\partial^2 S_0}{\partial x^2} \xi_x$. Shifted bundle $\Lambda_k^t = g_k^t \Lambda_0$, $\rho_k^t = dg_k^t \rho_0$.

Theorem (V.P. Maslov)

Under certain technical conditions the solution u(x, t, h) can be represented as asymptotic series

$$u \sim \sum_{k=1}^{ml} \hat{K}_{\Lambda_k^t, \rho_k^t} (\sum_{s=0} h^s \varphi_{k,s}),$$

 $\hat{K}: C_0^{\infty}(\Lambda_k^t) \to C^{\infty}(\mathbb{R}_x^n)$ is the Maslov canonical operator on the complex germ, $\varphi_{k,s}$ are smooth functions on Λ_k^t .

Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coe Smoothed discontinuity. Model equation.

$$\begin{split} &(-i\frac{\partial}{\partial t})^{m}u = A(t,x,-i\frac{\partial}{\partial t},-i\frac{\partial}{\partial x})u, \\ &x \in \mathbb{R}^{n}, \quad u \in \mathbb{C}^{I}, \quad A(t,x,p_{0},p)-I \times I \quad matrix. \end{split}$$

We consider two situations.

- A is discontinuous on an orientable hypersurface Mⁿ⁻¹ ⊂ ℝⁿ_x and smooth outside M, A = A[±](t, x, p₀, p) at the positive (negative) side of M.
- 2 A is rapidly varying near *M*:

 $A = A(\frac{\Phi(x)}{h}, t, x, p_0, p), A(y, t, x, p_0, p) = A^{\pm}(t, x, p_0, p)$ as $y \notin [y_-, y_+]$, where *M* is defined by the equation $\Phi(x) = 0$.

For each side of *M* we have Hamiltonians H_k^{\pm} and corresponding trajectories. We assume that $\operatorname{supp} \varphi^0$ is small and

 $\Phi|_{\operatorname{supp}\varphi^0} < 0.$ For sufficiently small *t* (until trajectories of Hamiltonan systems reach *M*) solution is the same as for smooth coefficients.

The main problem: what happens with Lagrangian surfaces and amplitudes $\varphi_{k,s}$ near *M*?

Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coe



Figure: Scattering

< ロ > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

Reflection and transmission of Lagrangian manifolds. Ramifying Ha Amplitudes of transmitted and reflected waves. Discontinuous coef Smoothed discontinuity. Model equation.

イロト イポト イヨト イヨト

Main effects

1. Many reflected and transmitted waves, defined by different Lagrangian surfaces.

2. Total reflection. Transmitted wave can dissapear.

Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coe Smoothed discontinuity. Model equation.



Figure: Total reflection



Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coel Smoothed discontinuity. Model equation.

< ロ > < 同 > < 三 >

Outline

Strictly hyperbolic systems with smooth coefficients

2 Strictly hyperbolic systems with singular coefficients

- Reflection and transmission of Lagrangian manifolds. Ramifying Hamiltonian billiards and Petrovsky surfaces.
- Amplitudes of transmitted and reflected waves. Discontinuous coefficients.
- Smoothed discontinuity. Model equation.

 $\Lambda_k =$

Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coef Smoothed discontinuity. Model equation.

Lagrangian surfaces, corresponding to incident waves Extended phase space. $\Lambda_k^0 \subset \mathbb{R}^{2n+2}$, $p = \frac{\partial S_0}{\partial x}$, t = 0, $p_0 + H_k^-(t, x, p) = 0$, Hamiltonian systems

$$\dot{x} = \frac{\partial H_k^-}{\partial \rho}, \quad \dot{\rho} = -\frac{\partial H_k^-}{\partial x}, \quad \dot{t} = 1, \quad \dot{\rho}_0 = -\frac{\partial H_k^-}{\partial t},$$
$$\cup_s g_{\pm}^s \Lambda_k^0$$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ ○臣 - の々で

ヘロン 人間 とくほ とくほ とう

Consider small interval of time, when trajectories of the Hamiltonian H_1^- intersect M (for others Hamiltonians trajectories still stay it the domain $\Phi < 0$). Surface $\hat{M} \subset \mathbb{R}^{2n+2}$: $x \in M$, t, p_0, p — arbitrary (the lifting of M to the phase space), $N = \Lambda_1 \cap \hat{M}$.

We assume that on the surface *N*, for some $\delta > 0$, $\frac{\partial H_1^-}{\partial p_n} \ge \delta$. (p_n — normal to *M* component of the vector *p*) — trajectories are transversal to *M*.

Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coe Smoothed discontinuity. Model equation.

In order to describe reflected and transmitted waves, we have to consider roots of the following equations

Reflecting roots

$$H_k^-(t,x,p_0,p_\tau,\varkappa) = H_1^-(t,x,p_0,p_\tau,p_n), \quad \frac{\partial H_k^-}{\partial p_n} < 0$$

or

2 Transmitting roots

$$H_k^+(t, x, p_0, p_\tau, \varkappa) = H_1^-(t, x, p_0, p_\tau, p_n), \quad \frac{\partial H_k^+}{\partial p_n} > 0$$

- - I

Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coe Smoothed discontinuity. Model equation.



Figure: Ramifying billiard



Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coel Smoothed discontinuity. Model equation.

イロン イロン イヨン イヨン

Lemma

(A.I. Allilueva, A.S.) There exists at least one either reflecting or transmitting root

Consider also complex roots; in the first case we choose $\Im \varkappa < 0$, in the second — $\Im \varkappa > 0$.

Lemma

(A.I. Allilueva, A.S.) # (complex reflecting roots)+# (complex transmitting roots)=ml.

Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coel Smoothed discontinuity. Model equation.

イロト イポト イヨト イヨト

Proof is based on the study of intersections of a certain line in $\mathbb{R}P^n$ with the Petrovsky surfaces

$$\Gamma: \det(\rho_0^m - A_m^{\pm}) = 0$$

Theorem

(I.G. Petrovskii, 1945)
$$\Gamma = \bigcup_{j}^{ml/2} \Gamma_{j}$$
, if ml is even,
 $\Gamma = \bigcup_{j}^{[ml/2]} \Gamma_{j} \bigcup \Gamma_{0}$, if ml is odd.
 $\Gamma_{j} \cong S^{n-1}$, $\Gamma_{0} \cong \mathbb{R}P^{n-1}$.

Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coel Smoothed discontinuity. Model equation.



Figure: Petrovsky surface



Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coel Smoothed discontinuity. Model equation.

ヘロト ヘアト ヘビト ヘビト

Reflected and transmitted Lagrangian surfaces Mappings $Q_k^{\pm}: \hat{M} \to \hat{M}$: $Q_k^{\pm}(t, x, p_0, p_{\tau}, p_n) = (t, x, p_0, p_{\tau}, \varkappa_k(t, x, p)), \varkappa_k$ — real (transmitting or reflecting) roots. $N_k^{\pm} = Q_k^{\pm}(N)$. We shift N_k^{\pm} along the trajectories of the Hamiltonian systems with Hamiltonians H_k^{\pm} .

$$\Lambda^\pm_k = igcup_{oldsymbol{s},k} g^\pm_{oldsymbol{s},k} N^\pm$$

For complex roots let

$$\Lambda_k^{\pm} = N \subset T^*(M_x \times \mathbb{R}_t)$$

Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coel Smoothed discontinuity. Model equation.

WKB-case (no focal points). Construction of phases for reflected and transmitted waves.

$$\begin{split} \frac{\partial S_k^{\pm}}{\partial t} + H_k^{\pm}(t, x, \frac{\partial S_k^{\pm}}{\partial x}) &= 0, \\ S_k^{\pm}|_M &= S_1|_M, \quad \frac{\partial S_k^{\pm}}{\partial \nu}|_M = \varkappa_k^{\pm}(t, x, \frac{\partial S_1}{\partial t}, \frac{\partial S_1}{\partial x})|_M \end{split}$$

 ν — unit normal to *M*.

◆□> ◆□> ◆豆> ◆豆> ・豆 ・ ��や

Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coe Smoothed discontinuity. Model equation.

Outline

Strictly hyperbolic systems with smooth coefficients

Strictly hyperbolic systems with singular coefficients

- Reflection and transmission of Lagrangian manifolds. Ramifying Hamiltonian billiards and Petrovsky surfaces.
- Amplitudes of transmitted and reflected waves. Discontinuous coefficients.
- Smoothed discontinuity. Model equation.

Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coe Smoothed discontinuity. Model equation.

Let A be discontinuous.

Theorem

(A.I. Allilueva, A.S.) During certain time interval

$$\begin{split} u &\sim \sum_{k=1}^{ml} \mathcal{K}_{\Lambda_k} (\sum_{s=0}^{\infty} h^s \varphi_{k,s}) + \\ &+ \sum_{k'} \mathcal{K}_{\Lambda_{k'}^-} (\sum_{s=0}^{\infty} h^s \varphi_{k',s}^-) + \sum_{k''} \mathcal{K}_{\Lambda_{k''}^-} (\mathrm{e}^{\frac{i \varkappa_k^- \Phi}{h}} \sum_{s=0}^{\infty} h^s \varphi_{k'',s}^-), \end{split}$$

on the negative part of M,

$$u \sim \sum_{k'} K_{\Lambda_{k'}^+} (\sum_{s=0}^{\infty} h^s \varphi_{k',s}^+) + \sum_{k''} K_{\Lambda_{k''}^+} (e^{\frac{i \varkappa_k^+ \Phi}{h}} \sum_{s=0}^{\infty} h^s \varphi_{k'',s}^+)$$

on the positive part of M.

Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coe Smoothed discontinuity. Model equation.

Here indexes k' correspond to real and k'' — to complex reflecting and transmitting roots; amplitudes $\varphi_{k',s}^{\pm}$ are computed explicitly in terms of corresponding Hamiltonian trajectories, $\varphi_{k'',s}^{\pm}$ are computed algebraically. On the surface \hat{M} the leading amplitudes have the following form

$$\varphi_{k,0}^+ = \sigma_1 \tau_k \boldsymbol{e}_k^+, \quad \varphi_{k,0}^- = \sigma_1 \boldsymbol{r}_k \boldsymbol{e}_k^-,$$

where $\varphi_1 = \sigma_1 e_1^-$, τ_k , r_k are defined by the system of *ml* linear equations

$$\sum_{k} \tau_{k} (\varkappa_{k}^{+})^{j} e_{k}^{+} - \sum_{k} r_{k} (\varkappa_{k}^{-})^{j} e_{k}^{-} = p_{n}^{j} e_{1}, \quad j = 0, \dots, m-1,$$

 e_k^{\pm} are eigenvectors of the matrix A_m^{\pm} , corresponding to eigenvalues $(-H_k^{\pm})^m$.

Outline

Reflection and transmission of Lagrangian manifolds. Ramifying H-Amplitudes of transmitted and reflected waves. Discontinuous coef Smoothed discontinuity. Model equation.

<ロト < 回 > < 回 > <

Strictly hyperbolic systems with smooth coefficients

Strictly hyperbolic systems with singular coefficients

- Reflection and transmission of Lagrangian manifolds. Ramifying Hamiltonian billiards and Petrovsky surfaces.
- Amplitudes of transmitted and reflected waves. Discontinuous coefficients.
- Smoothed discontinuity. Model equation.

Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coe Smoothed discontinuity. Model equation.

Let $A = A(\frac{\Phi(x)}{h}, t, x, p_0, p)$. In order to compute amplitudes consider at points of *N* scattering problem for the model equation

$$(A_m(y,t,x,p_0,p_{\tau},-i\frac{d}{dy})-p_0^m)w=0.$$

If $y \notin [y_-, y_+]$ we have equations with constant coefficients A_m^{\pm} ; let L^{\pm} are spaces of their solutions and $B : L^+ \to L^-$ — the monodromy operator ($ml \times ml$ -matrix). Transmitting and reflecting roots correspond to subspaces $O^{\pm} \subset L^{\pm}$, $\dim O^- + \dim O^+ = ml$. We assume that the following condition of general position hold on N

$$B(O^+)\oplus O^-=L^-.$$

Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coe Smoothed discontinuity. Model equation.

We have to consider Lagrangian manifolds, corresponding to real reflecting and transmitting roots only.

Theorem

(A.I. Allilueva, A.S.) During certain time interval

$$\begin{split} u &\sim \sum_{k=2}^{ml} \mathcal{K}_{\Lambda_k} (\sum_{s=0}^{\infty} h^s \varphi_{k,s}) + \mathcal{K}_{\Lambda_1} (\sum_{s=0}^{\infty} h^s f_{1,s} (\frac{\Phi(x)}{h}, \cdot)) \\ &+ \sum_k \mathcal{K}_{\Lambda_k^-} (\sum_{s=0}^{\infty} h^s f_{k,s}^- (\frac{\Phi(x)}{h}, \cdot)) + \\ &+ \sum_k \mathcal{K}_{\Lambda_k^+} (\sum_{s=0}^{\infty} h^s f_{k,s}^+ (\frac{\Phi(x)}{h}, \cdot)) \end{split}$$

Functions $f_{k,s}^{\pm}$ are expressed in terms of the model equation. Leading term.

The incident wave $K_{\Lambda_1}(\varphi_{1,0})$ defines at the points of the surface N vector $\varphi_{1,0}e^{ip_ny} = \sigma_1\xi \in L^-$; $\xi = e_1^-e^{ip_ny}$, e_1 — eigenvector of A_m^- . Let $w^+ = B^{-1}\Pi(\xi)$, Π — projection to $B(O^+)$ along O^- and $w^- = (\Pi - 1)\xi$. We fix the solution w of the model equation by the conditions

$$w = \xi + w^-, \quad y < y_-, \quad w = w^+, \quad y > y_+.$$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ ─臣 ─の�?

Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coe Smoothed discontinuity. Model equation.

Asymptotics of w:

$$egin{aligned} & m{w}
ightarrow \xi + \sum_k r_k m{e}_k^- \mathrm{e}^{i arkappa_k^- m{y}}, \quad m{y}
ightarrow -\infty, \ & m{w}
ightarrow \sum_k au_k m{e}_k^+ \mathrm{e}^{i arkappa_k^+ m{y}}, \quad m{y}
ightarrow +\infty, \end{aligned}$$

 \varkappa_k^{\pm} — real reflecting and transmitting roots. We shift $\sigma_1 r_k e_k^-$ and $\sigma_1 \tau_k e_k^+$ along corresponding Hamiltonian trajectories, obtaining $\varphi_{k,0}^{\pm}$.

Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coe Smoothed discontinuity. Model equation.

Let
$$\eta(y) = \frac{1}{2}(1 + \tanh y)$$
. We construct $f_{k,0}^{\pm}$, $f_{1,0}$ as follows
 $f_{k,0}^{+} = \eta(y)\varphi_{k,0}^{+}$, $f_{k,0}^{-} = (1 - \eta(y))\varphi_{k,0}^{-}$,
 $f_{1,0} = \varphi_{1,0}(1 - \eta) + e^{-i\rho_{1}y}(w - \sum_{k} f_{k,0}^{-}e^{i\varkappa_{k}^{-}y} - \sum_{k} f_{k,0}^{+}e^{i\varkappa_{k}^{+}y})$.

(日) (四) (三) (三) (三) (三) (○) (○)

Reflection and transmission of vector bundles. Complex Lagrangian planes correspond to quadratic forms — matrices Q^{\pm} : $\rho : \rho = Qx$. Rules of reflection:

$$Q^-|_{T_M}=Q^+|_{T_M}+2p_nb,$$

b is the second fundamental form of *M*.

Reflection and transmission of Lagrangian manifolds. Ramifying H Amplitudes of transmitted and reflected waves. Discontinuous coe Smoothed discontinuity. Model equation.

ヘロト 人間 とくほとくほとう

3

THANK YOU FOR YOUR ATTENTION!