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Development of a position-sensitive detector system using the CAEN Front-End Readout System DT5202 <u>Romakhov S.^{1,2}, Gavrishchuk O.¹, Enik T.¹</u>



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Introduction

A **position-sensitive detector** (PSD) has been designed based on a plastic scintillator plate, coupled to an array of silicon photomultipliers (SiPMs) through fiber strips. Main goal is to measure the transverse coordinate (x) of traversing charged particles such as cosmic-ray muons – by analyzing the light yield in multiple readout channels. This poster describes the detector's design, the electronic front-end provided by **CAEN FERS DT5202**, data acquisition methods, and the subsequent data processing and coordinate reconstruction in CERN ROOT.

Detector Design and Parameters

Scintillator and Fiber Geometry

- The detector uses a **plastic scintillator** with embedded or surface-mounted **lightguiding fibers** arranged in parallel strips.
- Each strip (4 fibers) transmits scintillation light produced by an ionizing particle to one of several **SiPM** readout channels.
- Current geometry has **7 strips**, each associated with one SiPM channel. The lateral size (transverse to the beam) is roughly 15×15 cm².

Position Reconstruction

• The coordinate along the direction of these fiber strips is extracted from the **amplitudes** of multiple channels.



Fig. 1. Close-up geometry, showing fiber arrangement from 10 mm up to 130 mm

Data Acquisition and Processing

- 1. Data Acquisition
 - Each event consists of digitized signals (ADC counts) from 7 channels.
 Time-stamp and event ID are also recorded to correlate hits in time.

- The distance between SiPMs is 20 mm, and the first channel starts at x = 10 mm, so the channels cover the region x = 10, 30, 50, 70, 90, 110, 130 mm.
- A weighted-sum approach (e.g $\Sigma A_i x_i / \Sigma A_i$) with normalization factors k is applied.





- 2. Calibration and Normalization
 - Each channel's raw amplitude distribution is fit with a **Landau** function (Fig. 3). This yields a mean or MPV-based normalization coefficient (k) to equalize the response across strips.
- 3. Coordinate Reconstruction
 - For each triggered event, channels with sufficiently high amplitude are selected.
 - Applyed a weighted approach:

$$x = \frac{\Sigma_i(A_i x_i k_i \omega_i)}{\Sigma_i(A_i k_i \omega_i)}$$

where $A_i k_i$ – is the normalized amplitude,

 $\omega_i = \exp(-\alpha |x_i - x_{max}|)$

can be an additional weighting factor (e.g., from geometry or exponential suppression).



FERS DT5202 electronics. Through amplitude-based reconstruction and calibration, this system can measure the transverse coordinate

of charged particles with good uniformity. The approach is readily

Fig. 4. The 2D histogram on the right depicts the particle coordinates (*x*) versus event timestamps. The projection along the *x*-axis on the left represents the spatial distribution of detected events.

adaptable to cosmic-ray muon detection, beam diagnostics, or general tracking applications.

Key Results:

- Demonstrated stable ADC calibration using Landau fits.
- Successfully implemented a weighted-sum coordinate reconstruction technique.
- Achieved continuous coverage from x = 10 mm to x = 130 mm using 7 strips, with potential extension using more channels.
- Confirmed consistent time vs. x distributions for random cosmicray events.

References:

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