# Centrality determination by forward detectors

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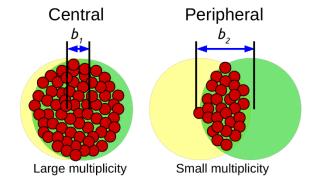


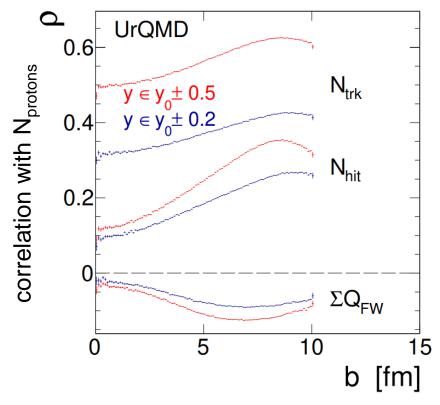
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## **Centrality**

- Evolution of matter produced in heavy-ion collisions depend on its initial geometry
- Centrality procedure maps initial geometry parameters with measurable quantities (multiplicity or energy of the spectators)
- This allows comparison of the future BMAN results with the data from other experiments (STAR BES, NA49/NA61 scans) and theoretical models

$$c(b) = \frac{\int_0^b \frac{d\sigma}{db'} db'}{\int_0^\infty \frac{d\sigma}{db'} db'} = \frac{1}{\sigma_{A-A}} \int_0^b \frac{d\sigma}{db'} db'$$

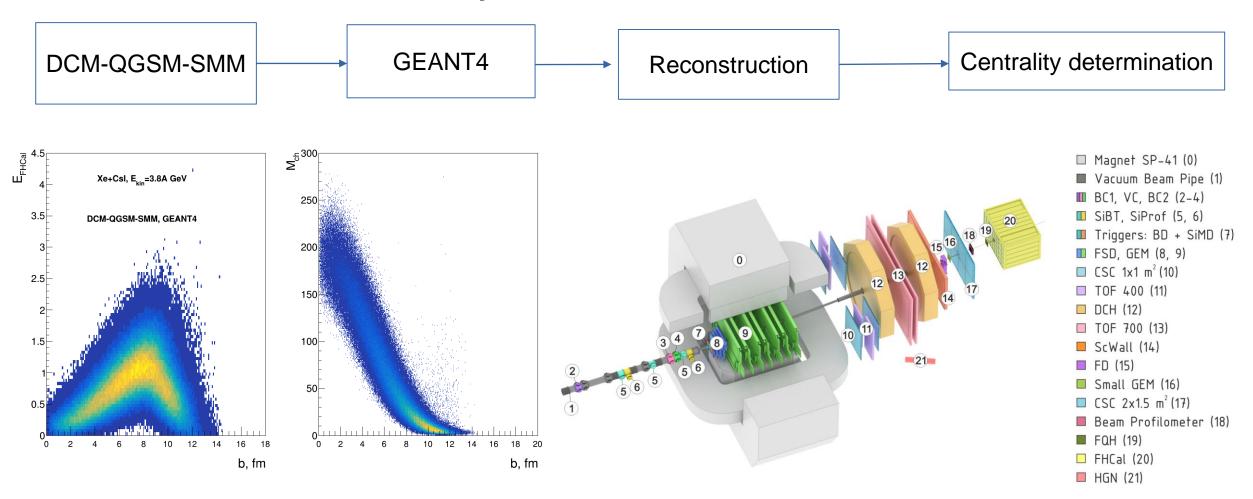




HADES; Phys.Rev.C 102 (2020) 2, 024914

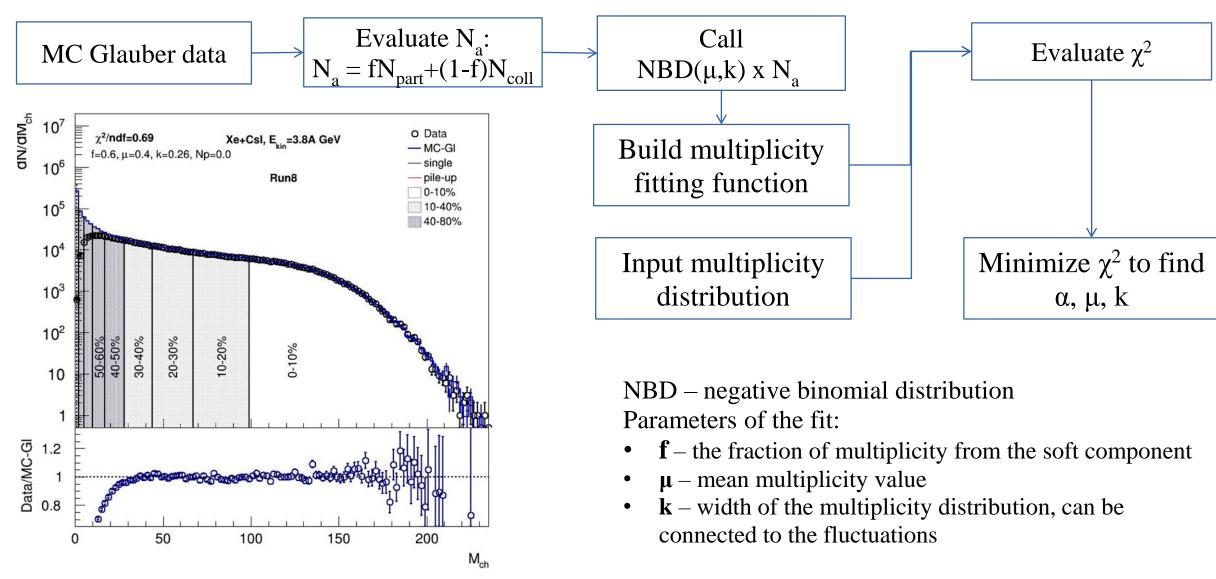
- A number of produced protons is stronger correlated with the number of produced particles (track & RPC+TOF hits) than with the total charge of spectator fragments (FW)
- to suppress self-correlation biases, it is necessary to use spectators fragments for centrality estimation

# Centrality determination in BM@N



Dependence of energy in FHCal and track multiplicity on the impact parameter

### MC-Glauber based centrality framework



Implementation for MPD: <a href="https://github.com/FlowNICA/CentralityFramework">https://github.com/FlowNICA/CentralityFramework</a>

Provided at the Postfolia 2021, 4(2):275, 287

4

### The Bayesian inversion method (Γ-fit): DCM-QSM-SMM based

• The fluctuation kernel Gamma distr.:

$$P(M \mid c_b) = \frac{1}{\Gamma(k(c_b))\theta^2} M^{k(c_b)-1} e^{-M/\theta}$$

$$c_b = \int_0^b P(b')db'$$
 – centrality based on impact parameter

$$\theta = \frac{D(M)}{\langle M \rangle}, \quad k = \frac{\langle M \rangle}{\theta}$$

 $\langle M \rangle, D(M)$  – average and variance of Multiplicty

$$P(M) = \int_{0}^{1} P(M \mid c_b) dc_b$$

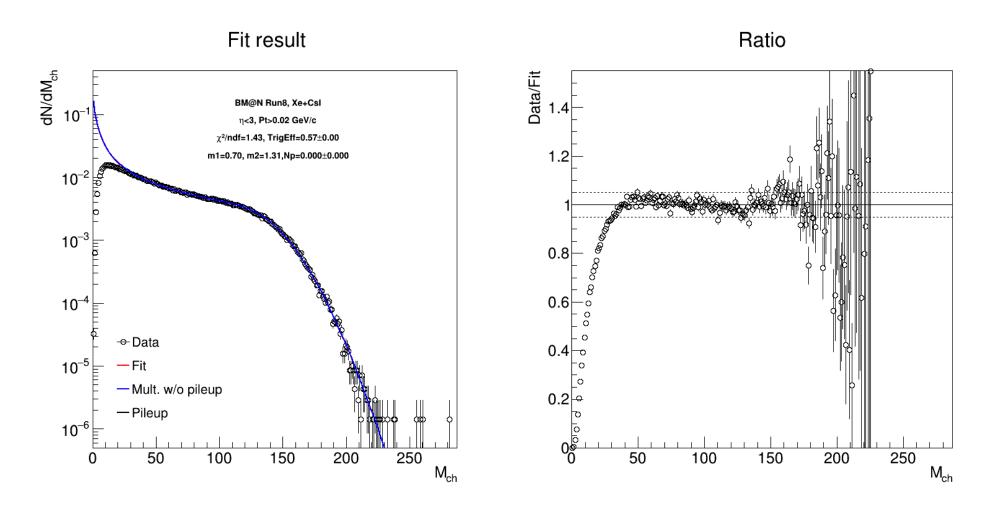
$$\langle M \rangle = m_1 \cdot \langle M' \rangle$$

$$D(M) = m_1^2 \cdot D(M') + m_1 \cdot m_2 \langle M' \rangle$$

$$\left\langle M \ '(c_b) \right\rangle \qquad \text{- average value and var. of energy/mult.}$$
 
$$D(M \ '(c_b)) \qquad \text{from the rec. model data}$$

 can be approximated by polynomials and exponential polynomial

#### Fit results



Vertex Cuts: CCT2,  $N_{vtxTr} > 1$ ,  $|V_{x,y}| - (0.3,0.14) | < 1$  cm,  $|V_z| - 0.07 | < 0.2$  cm

Good agreement with data

Track selection: Nhit>4,  $\eta$ <3, Pt>0.05 GeV/c

# The Bayesian inversion method (Γ-fit): 2D fit

• The fluctuation kernel for energy and multiplicity at fixed impact parameter can be describe by 2D Gamma distr.:

$$P(E, M \mid c_b) = G_{2D}(E, M, \langle E \rangle, \langle M \rangle, D(E), D(M), R)$$

$$c_b = \int_0^b P(b')db'$$
 – centrality based on impact parameter

 $\langle E \rangle, D(E)$  — average value and variance of energy

 $\langle M \rangle$ , D(M) – average value and variance of mult.

 Pirson correlation coefficient R(E,M)

$$R(E,M) = \frac{\varepsilon_1^2 m_1^2}{\varepsilon_2 m_2} R(E',M')$$
  $\varepsilon_1, \varepsilon_2, m_1, m_2$  - fit parameters

 $\langle E'(c_h) \rangle$  average value and var. of energy/mult.  $D(E'(c_h))$ from the rec. model data

$$\langle E \rangle = \varepsilon_1 \langle E'(c_b) \rangle, \quad D(E) = \varepsilon_2 D(E'(c_b))$$
  
 $\langle M \rangle = m_1 \langle M'(c_b) \rangle, \quad D(M) = m_2 D(M'(c_b))$ 

 $\langle E'(c_b) \rangle$ ,  $D(E'(c_b))$  - can be approximated by polynomials

$$\langle E'(c_b) \rangle = \sum_{j=1}^{8} a_j c_b^j, \quad D(E'(c_b)) = \sum_{j=1}^{6} b_j c_b^j$$

$$\langle M'(c_b) \rangle = \sum_{j=1}^{8} a_j c_b^j, \quad D(M'(c_b)) = \sum_{j=1}^{6} b_j c_b^j$$

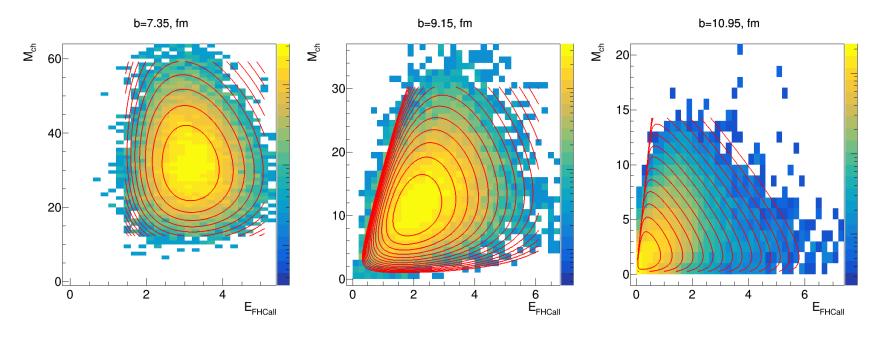
# The fluctuation of energy and multiplicity at fixed impact parameter

It is possible to find such a rotation angle of the system that cov(x, y) = 0

$$\langle x \rangle = \cos(\alpha) \langle E \rangle + \sin(\alpha) \langle M \rangle$$

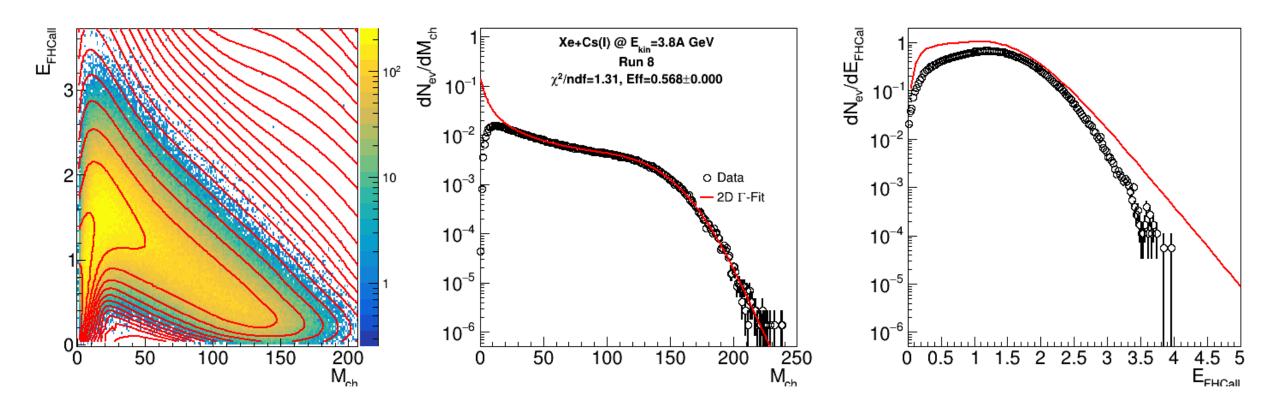
$$\langle y \rangle = -\sin(\alpha) \langle E \rangle + \cos(\alpha) \langle M \rangle$$

$$G_{2D}(E_{FH}, M_{ch}, \langle E \rangle, \langle M \rangle, D(E), D(M), R) = G(x, \theta_x, k_x) \cdot G(y, \theta_y, k_y)$$



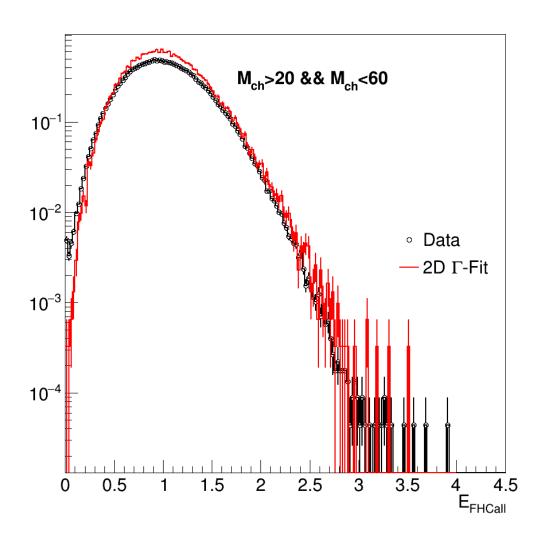
The distribution of energy and multiplicity at a fixed impact parameter is well described by the gamma distribution

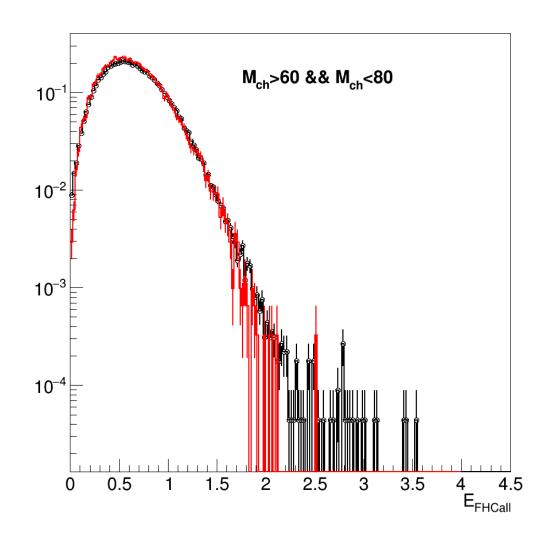
### 2D fit results



The fit function qualitatively reproduces the multiplicity-energy correlation from FHCal

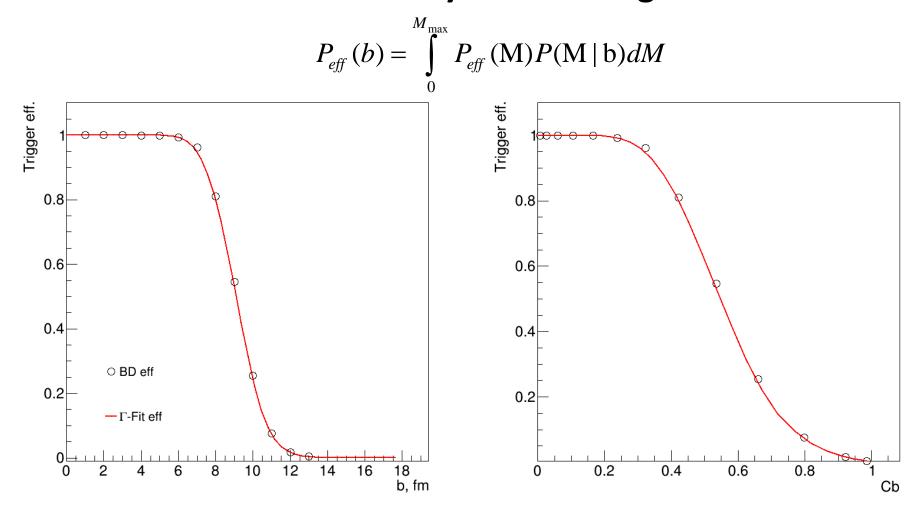
# **Energy distributions from FHCal for different multiplicity cuts**





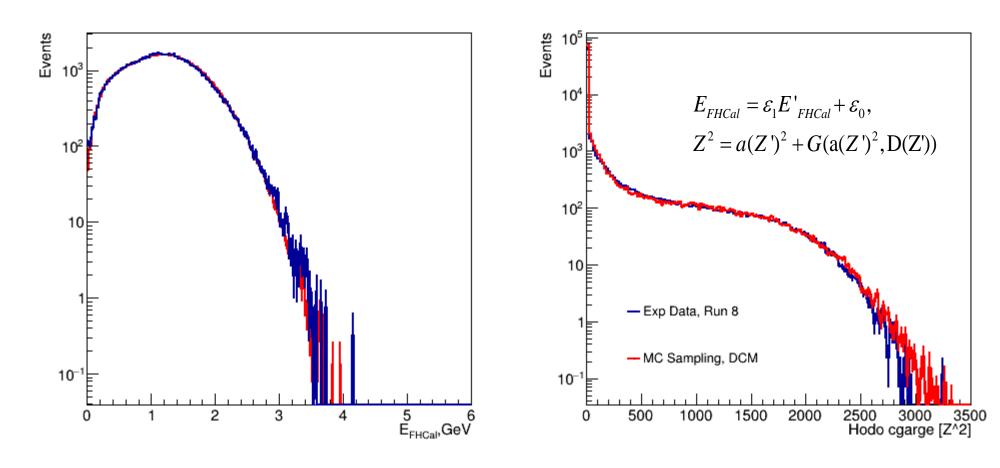
Good agreement between fit and data for the area below the anchorpoint

#### The total efficiency of event registration



The trigger efficiency obtained from the Bayesian approach is consistent with the results, obtained on the basis of simulations

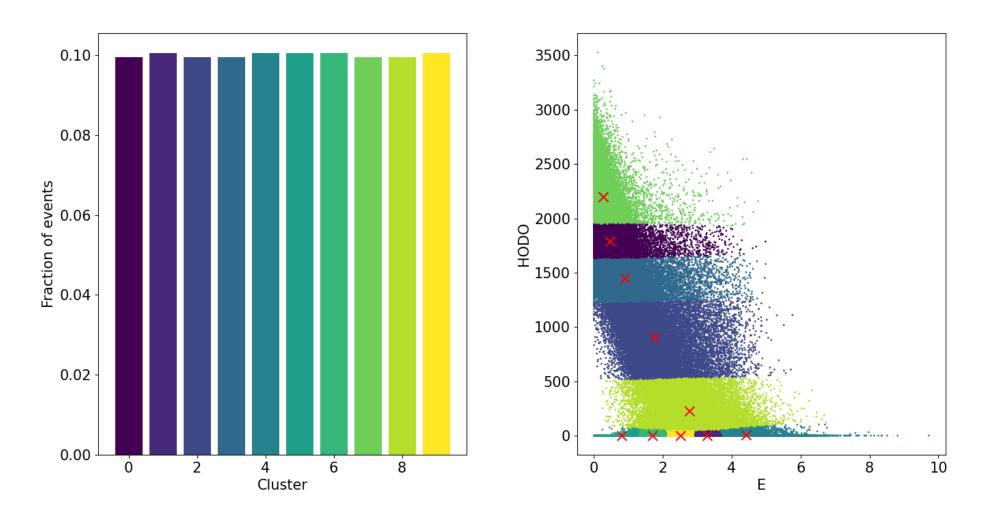
# The results of the fit signals from the calorimeter and hodoscope



Good agreement of fit results for the calorimeter

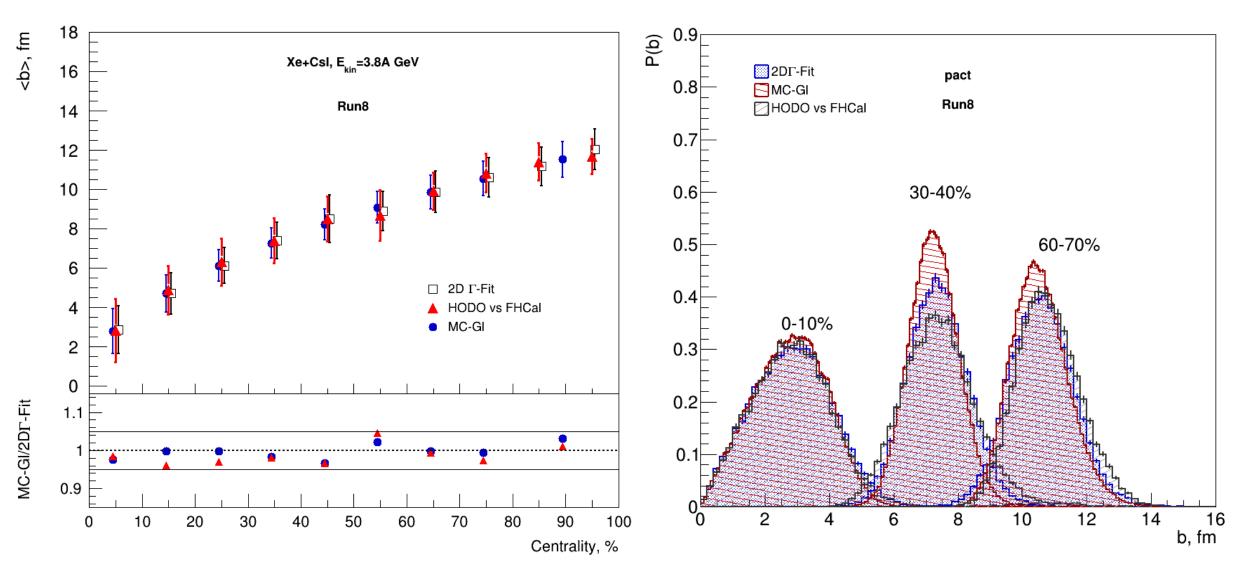
The fit procedure for the hodoscope is in the process of developing

# Centrality determination using an forward calorimeter and hodoscope



The K-means method allows to divide a two-dimensional distribution into centrality classes. In order to correctly apply the class boundaries, it is necessary to match the simulation results with the experiment

# **Comparison with MC-Glauber fit**



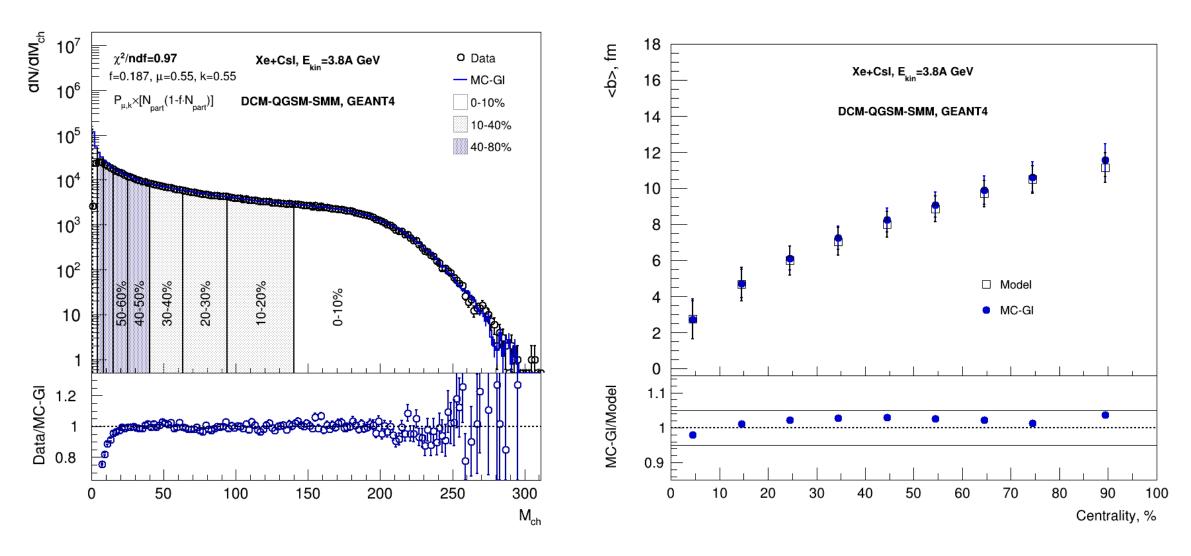
There is agreement within 5%.

### **Summary**

- The Bayesian inversion method reproduce charged particle multiplicity for fixed-target experiment at BM@N
- A new approach for centrality determination with energy of spectators and multiplicity of charged particles was proposed and tested on the data from BM@N experiment
- The procedure for centrality determination based on the signal from the hodoscope and the energy from the FHCal was developed
- The proposed methods for centrality determination are in good agreement with the classical approach based on the Glauber model

# Конфуз матрицы

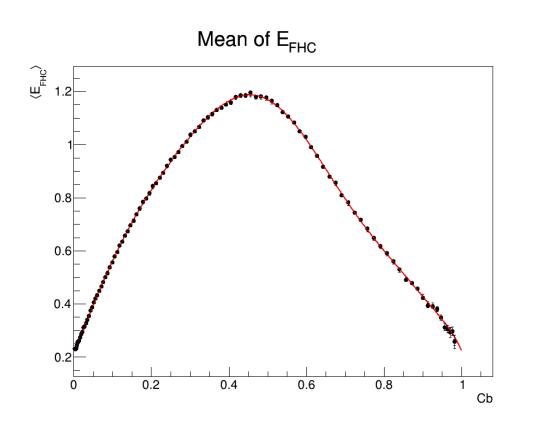
# **Centrality determination for reconstructed data**

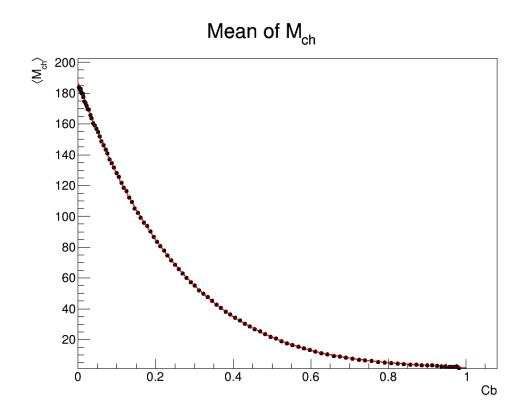


Good agreement with data

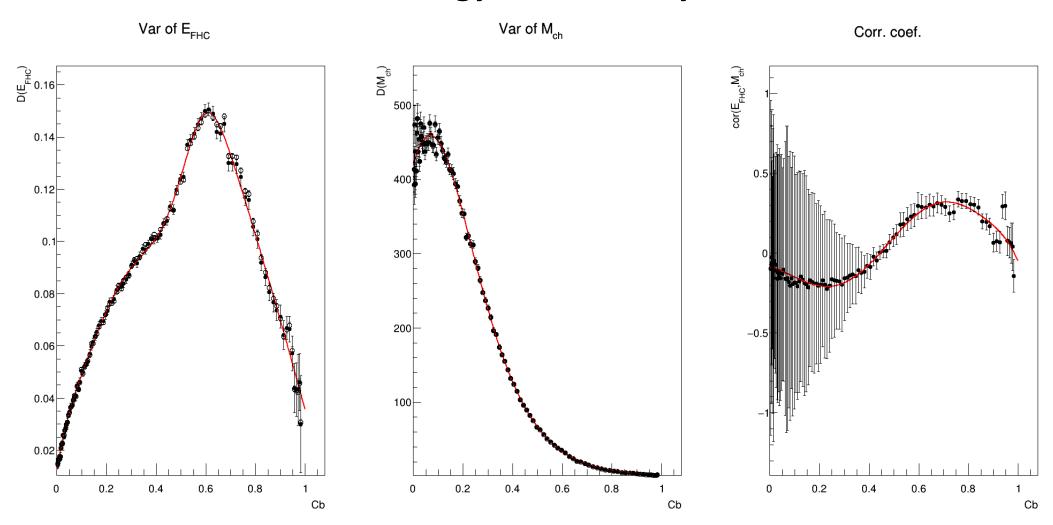
# Thank you for your attention!

# Dependence of the average value of multiplicity and energy on centrality





# Dependence of the variance of multiplicity and energy on centrality



#### **Corrections for efficiency and pileup**

Correction for efficiency of normalized multiplicity distribution P(M)

$$P(M) = \frac{dN}{dM} / N_{ideal}^{ev} = \underbrace{\frac{N_{raw}^{ev}}{N_{ideal}^{ev}} \frac{1}{N_{raw}^{ev}} \frac{dN_r}{dM}}_{N_{raw}^{ev}} = \frac{1}{K} \cdot Norm.Histogr$$

$$Eff = \frac{N_{raw}^{ev}}{N_{ideal}^{ev}} = \frac{1}{K}$$
 integral efficiency

Fit function for multiplicity distribution P(M)

$$F(M) = K \cdot P_{total}(M), P_{total}(M) = N_p \cdot P_{pu}(M) + (1 - N_p) \cdot P(M)$$

 $\mu, f, k, K, N_p$ - fit parameters, F(M) – fit function, corrected for efficiency and pileup

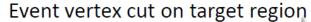
# **Event cleaning in HADES**

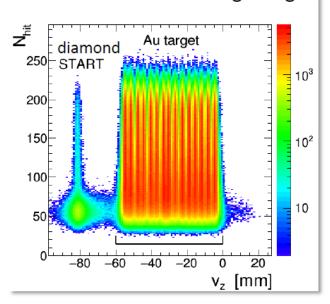
#### Segmented gold target:

- 197Au material
- 15 discs of Ø = 2.2 mm mounted on kapton strips
- $\Delta z = 3.6 \text{ mm}$
- 2.0% interaction prob.

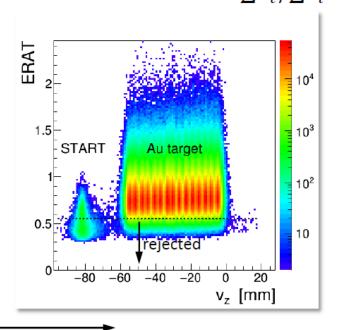


Kindler et al., NIM A 655 (2011) 95



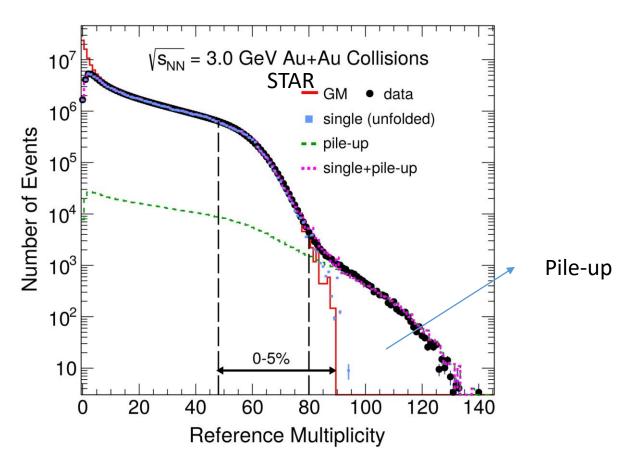


Remove Au+C bkgd on the kapton with a cut on  $ERAT = \sum E_t / \sum E_l$ 



beam direction

# Centrality determination in the FIX-target experiments



dα/dN [mb] **HADES** Data min. bias Au+Au 1.23 AGeV Data central (PT3) GlauberMC  $\times$  NBD( $\mu$ , k)  $\times$   $\epsilon(\alpha)$  $\mu$ =0.24, k=20.34,  $\alpha$ =-1.10e-07 10-20% 0-10% 10<sup>-1</sup> 10 20 60 80 40 100  $N_{\text{tracks}}$ 

Reference multiplicity distributions (black markers) in the kinematic acceptance within -0.5 < y < 0 and 0.4 < pT < 2.0 GeV/c , GM (red histogram), and single and pile-up contributions from unfolding.

The cross section as a function of Ntracks for minimum bias (blue symbols) and central (PT3 trigger, green symbols) data in comparison with a fit using the Glauber MC model (red histogram).

# Reconstruction of b

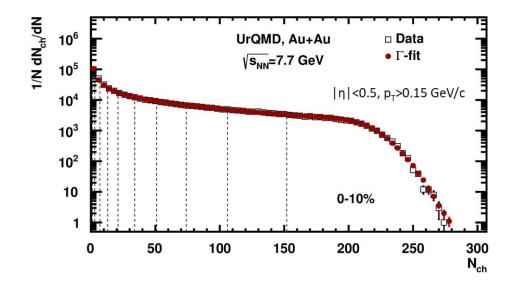
Normalized multiplicity distribution P(N<sub>ch</sub>)

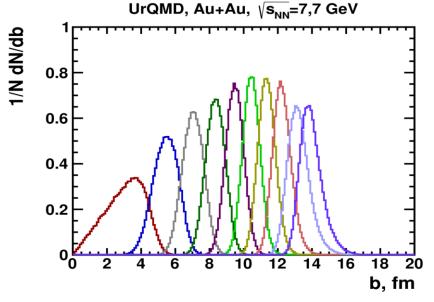
$$P(N_{ch}) = \int_0^1 P(N_{ch}|c_b) dc_b$$

• Find probability of b for fixed range of  $N_{ch}$  using Bayes' theorem:

$$P(b|n_1 < N_{ch} < n_2) = P(b) \frac{\int_{n_1}^{n_2} P(N_{ch}|b) dN_{ch}}{\int_{n_1}^{n_2} P(N_{ch}) dN_{ch}}$$

- The Bayesian inversion method consists of 2 steps:
- -Fit normalized multiplicity distribution with P(N<sub>ch</sub>)
- –Construct  $P(b|N_{ch})$  using Bayes' theorem with parameters from the fit





R. Rogly, G. Giacalone and J. Y. Ollitrault, Phys.Rev. C98 (2018) no.2, 024902