Anisotropic flow in MPD-FXT: first look at the production 36

P. Parfenov, M. Mamaev and A. Taranenko (NRNU MEPhI, JINR)

Anisotropic flow & spectators



The azimuthal angle distribution is decomposed in a Fourier series relative to reaction plane angle:

$$ho(arphi-\Psi_{RP})=rac{1}{2\pi}(1+2\sum_{n=1}^\infty v_n\cos n(arphi-\Psi_{RP}))$$

Anisotropic flow:

$$v_n = \langle \cos \left[n (arphi - \Psi_{RP})
ight]
angle$$

Anisotropic flow is sensitive to:

- Time of the interaction between overlap region and spectators
- Compressibility of the created matter

MPD in Fixed-Target Mode (FXT)



- Model used: UrQMD mean-field
 - Xe+Xe, E_{kin} =2.5 AGeV ($\sqrt{s_{NN}}$ =2.87 GeV)
 - Xe+W, E_{kin} =2.5 AGeV ($\sqrt{s_{NN}}$ =2.87 GeV)
- Point-like target
- GEANT4 transport
- Particle species selection via TPC and TOF

Flow vectors

From momentum of each measured particle define a u_n -vector in transverse plane:

$$u_n = e^{in\phi}$$

where ϕ is the azimuthal angle

Sum over a group of u_n -vectors in one event forms Q_n -vector:

$$Q_n = rac{\sum_{k=1}^N w_n^k u_n^k}{\sum_{k=1}^N w_n^k} = |Q_n| e^{in \Psi_n^{EP}}$$

 $\Psi_{n}^{\ \text{EP}}$ is the event plane angle

Modules of FHCal divided into 3 groups





Additional subevents from tracks not pointing at FHCal: Tp: p; -1.0<y<-0.6; Tπ: π-; -1.5<y<-0.2;

Flow methods for v_n calculation

Tested in HADES:

M Mamaev et al 2020 PPNuclei 53, 277–281 M Mamaev et al 2020 J. Phys.: Conf. Ser. 1690 012122

Scalar product (SP) method:

$$v_1 = rac{\langle u_1 Q_1^{F1}
angle}{R_1^{F1}} \qquad v_2 = rac{\langle u_2 Q_1^{F1} Q_1^{F3}
angle}{R_1^{F1} R_1^{F3}}$$

Where R_1 is the resolution correction factor

$$R_1^{F1}=\langle \cos(\Psi_1^{F1}-\Psi_1^{RP})
angle$$

Symbol "F2(F1,F3)" means R₁ calculated via (3S resolution):

$$R_1^{F2(F1,F3)} = rac{\sqrt{\langle Q_1^{F2}Q_1^{F1}
angle \langle Q_1^{F2}Q_1^{F3}
angle}}{\sqrt{\langle Q_1^{F1}Q_1^{F3}
angle}}$$

Method helps to eliminate non-flow Using 2-subevents doesn't



Symbol "F2{Tp}(F1,F3)" means R₁ calculated via (4S resolution):

$$R_1^{F2\{Tp\}(F1,F3)} = \langle Q_1^{F2}Q_1^{Tp}
angle rac{\sqrt{\langle Q_1^{F1}Q_1^{F3}
angle}}{\sqrt{\langle Q_1^{Tp}Q_1^{F1}
angle \langle Q_1^{Tp}Q_1^{F3}
angle}}$$

PID procedure



 W. Blum, W. Riegler, L. Rolandi, Particle Detection with Drift Chambers (2nd ed.), Springer, Verlag (2008)

Fit dE/dx distributions with Bethe-Bloch parametrization:

Fit m² with gaus in the slices of p/q and get $\sigma_p(m^2)$

 $(dE/dx,m) \rightarrow (x,y)$ coordinates for PID:

$$x_{p} = \frac{(dE/dx)^{meas} - (dE/dx)_{p}^{fit}}{(dE/dx)_{p}^{fit}\sigma_{p}^{dE/dx}}, \ y_{p} = \frac{m^{2} - m_{p}^{2}}{\sigma_{p}^{m^{2}}}$$

PID procedure: Results







Results: $v_1(y)$

Systematics: xx, yy, F1, F2, F3



Results: $v_1(y^*)$

Systematics: xx, yy, F1, F2, F3



 $y_{cm}^* = y_{lab}^- A_{proj}^- / (A_{proj}^+ A_{targ}^-)^* 0.5^* log((E_{lab}^- P_{lab}^-)/(E_{lab}^- P_{lab}^-)); y_{cm}^* = y_{cm}^- for symmetric systems$

Results: $v_1(p_T)$

Systematics: xx, yy, F1, F2, F3







 $y_{cm}^* = y_{lab}^- A_{proj}^- / (A_{proj}^+ A_{targ}^-)^* 0.5^* log((E_{lab}^- P_{lab}^-)/(E_{lab}^- P_{lab}^-)); y_{cm}^* = y_{cm}^- for symmetric systems$



Summary

- Realistic procedures for centrality determination, primary track selection and PID were used
 - Multiplicity-based centrality determination using MC-Glauber was used
- Basic PID was performed using dE/dx from TPC and m² from TOF
- Good agreement between "reco" and "mc" within corresponding acceptance window for protons, discrepancy for pions









