

# Status of TOF systems: data reconstruction and preparation for future run

M. Rumyantsev on behalf of TOF group

## TOF400

#0	#5
#1	#6
#2	#7
#3	#8
#4	#9



#10	#15
#11	#16
#12	#17
#13	#18
#14	#19

- 4.3 m from target
- 20 mRPCs
- 1.1 x 1.2 m<sup>2</sup> x 2 arms
- 1960 FEE channels

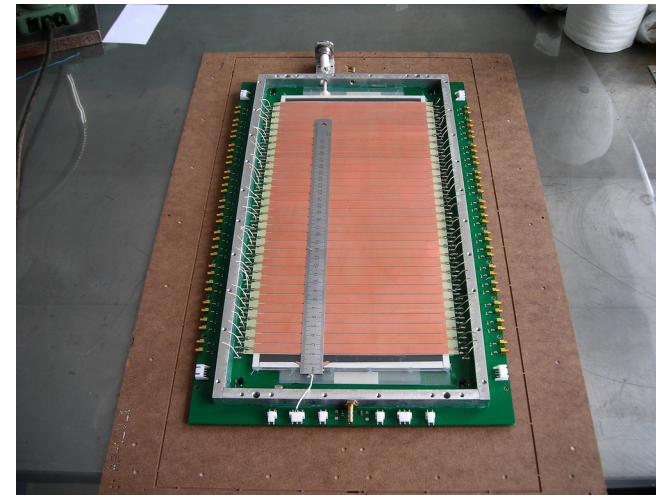
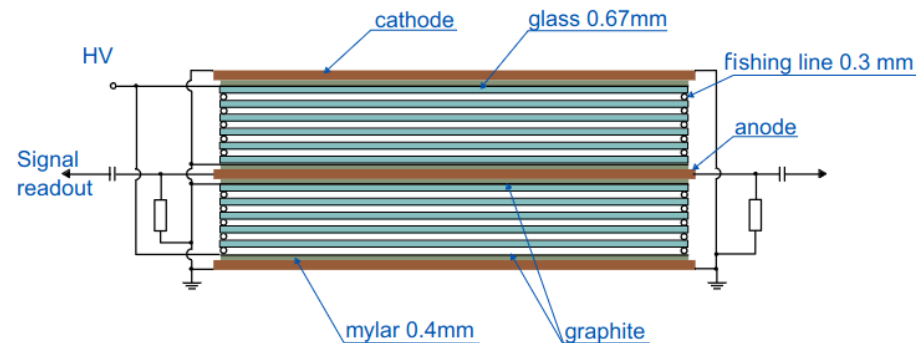
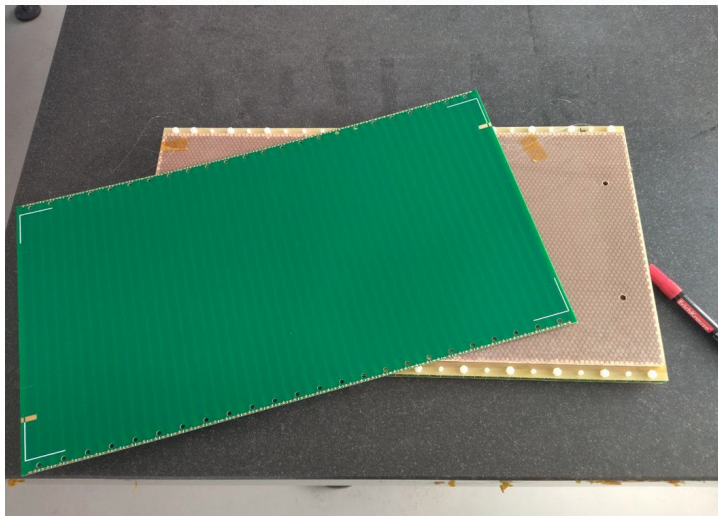
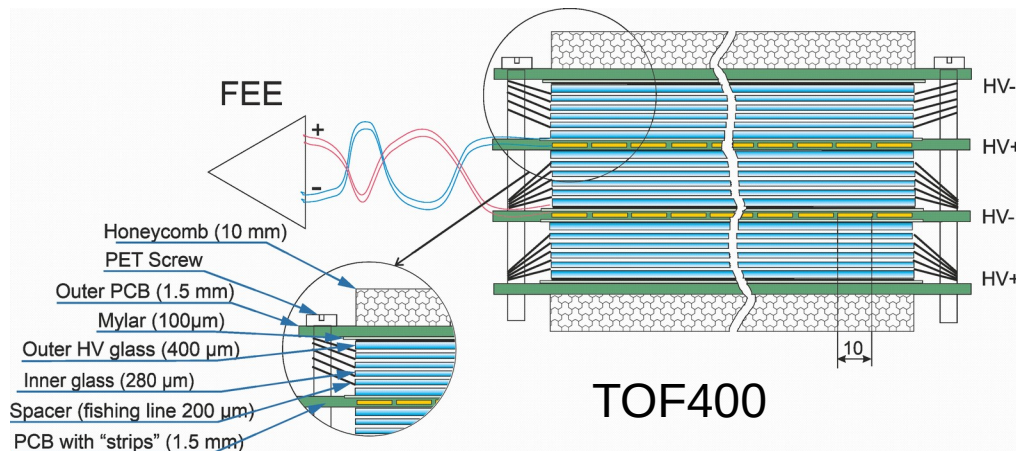
## TOF700

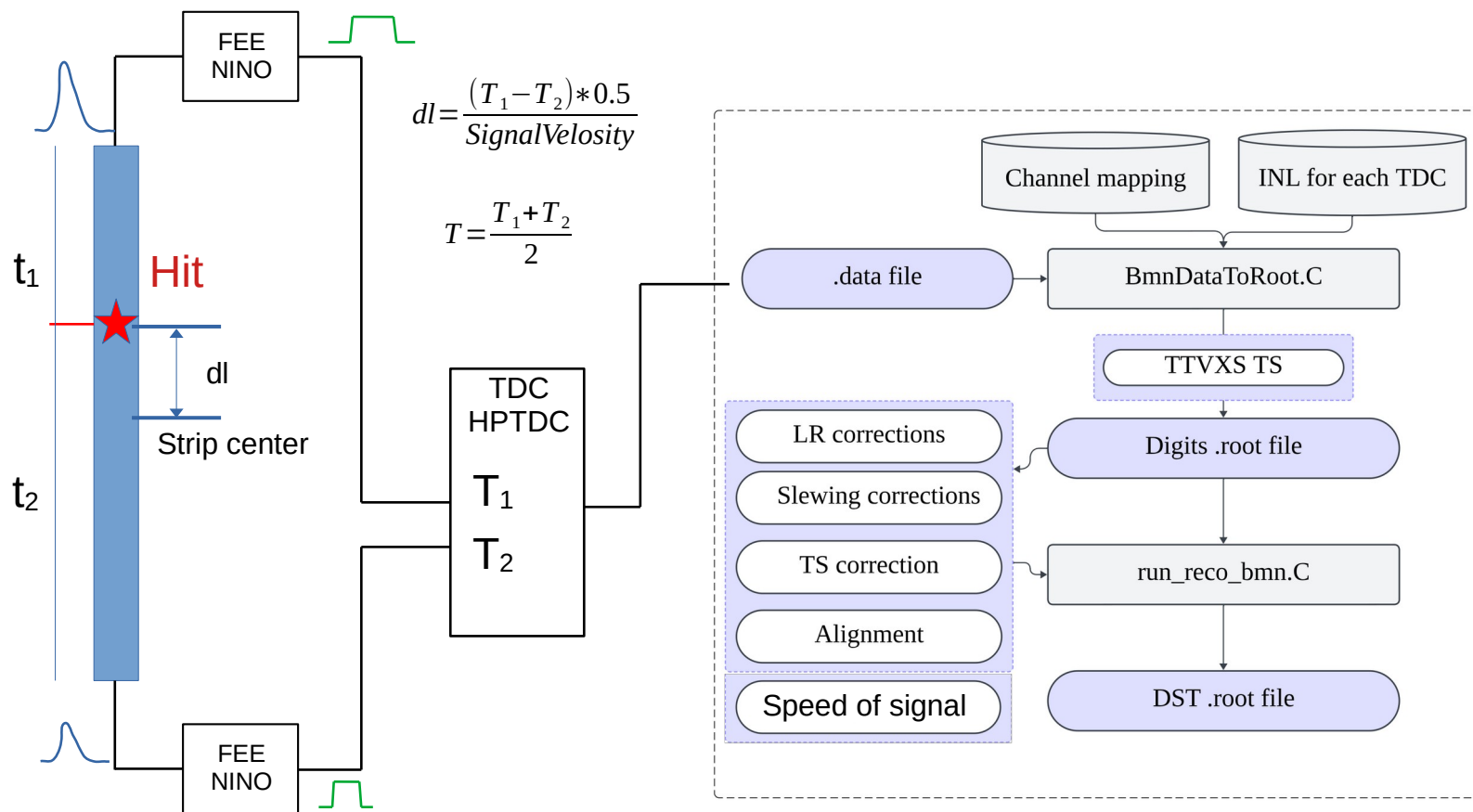
107.2-B Crate 0 Slot 9		108.2-A Crate 0 Slot 10		109.2-B Crate 0 Slot 9		110.2-A Crate 2 Slot 8		111.2-B Crate 2 Slot 8		112.2-A Crate 2 Slot 9				
④①		④②		④③		④④		④⑤		④⑥				
113.1-A Crate 1 Slot 5	⑦	⑧	⑨	⑩	⑪	⑫	⑬	⑭	⑮	⑯	⑰			
	1.1-B Crate 1 Slot 7	2.1-A Crate 1 Slot 15	3.1-B Crate 1 Slot 19	4.1-A Crate 1 Slot 14	5.1-B Crate 1 Slot 18	6.1-A Crate 1 Slot 13	7.1-B Crate 1 Slot 6	8.1-A Crate 3 Slot 8	9.1-B Crate 3 Slot 2	10.1-A Crate 3 Slot 10	11.1-B Crate 3 Slot 4	12.1-A Crate 3 Slot 12	13.1-B Crate 3 Slot 6	14.1-A Crate 3 Slot 14
④⑦		④⑧		④⑨		④⑩		④⑪		④⑫		④⑬		④⑭
115.2-A Crate 1 Slot 10	⑮	⑯	⑰	⑱	⑲	⑳	㉑	㉒	㉓	㉔	㉕	㉖	㉗	㉘
	15.2-B Crate 0 Slot 12	16.2-A Crate 0 Slot 13	17.2-B Crate 0 Slot 16	18.2-A Crate 0 Slot 14	19.2-B Crate 0 Slot 17	19.3-B Crate 0 Slot 11	20.2-A Crate 0 Slot 15	⊗	21.2-A Crate 2 Slot 2	22.2-B Crate 2 Slot 5	23.2-A Crate 2 Slot 3	24.2-B Crate 2 Slot 6	25.2-A Crate 2 Slot 4	26.2-B Crate 2 Slot 7
④⑮		④⑯		④⑰		④⑱		④㉑		④㉒		④㉓		④㉔
117.1-A Crate 1 Slot 5	㉗	㉘	㉙	㉚	㉛	㉜	㉝	㉞	㉟	㊱	㊲	㊳	㊴	㊵
	27.1-B Crate 1 Slot 8	28.1-A Crate 1 Slot 12	29.1-B Crate 1 Slot 17	30.1-A Crate 1 Slot 11	31.1-B Crate 1 Slot 16	32.1-A Crate 1 Slot 10	33.1-B Crate 1 Slot 9	34.1-A Crate 3 Slot 7	35.1-B Crate 3 Slot 1	36.1-A Crate 3 Slot 9	37.1-B Crate 1 Slot 7	38.1-A Crate 3 Slot 3	39.1-B Crate 3 Slot 5	40.1-A Crate 3 Slot 13
④㉗		④㉘		④㉙		④㉚		④㉛		④㉜		④㉝		④㉞
119.2-B Crate 0 Slot 7		120.2-A Crate 0 Slot 8		121.2-B Crate 0 Slot 8		122.2-A Crate 2 Slot 10		123.2-B Crate 2 Slot 10		124.2-A Crate 2 Slot 11				
④㉟		④㊱		④㊲		④㊳		④㊴		④㊵				

- 6.2 m from target
- 41 (small)+18(big) mRPCs
- 3.4 x 1.4 m<sup>2</sup> of active area
- 3200 FEE channels

# Detector scheme

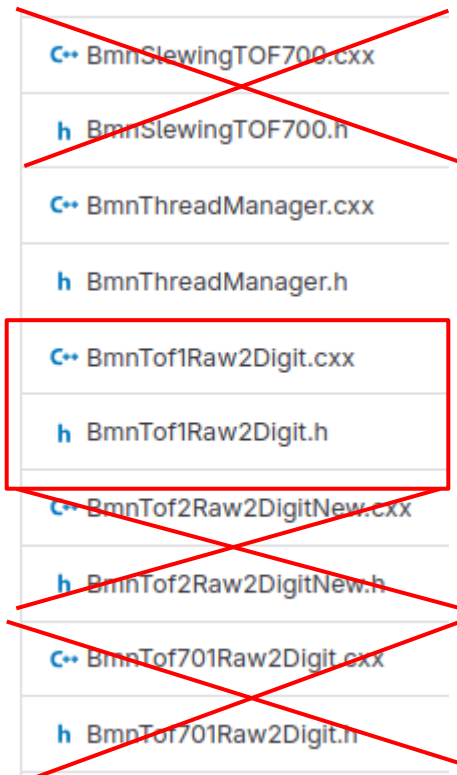
Both systems use mRPC detectors with a strip readout.





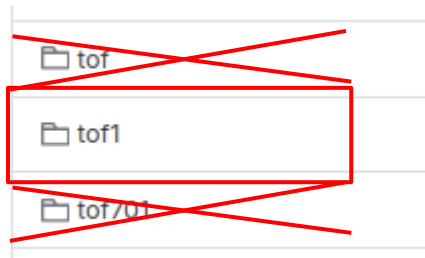
Both systems use a similar signal processing chain and data analysis pipeline.

bmnroot/decoder



It should to be done.

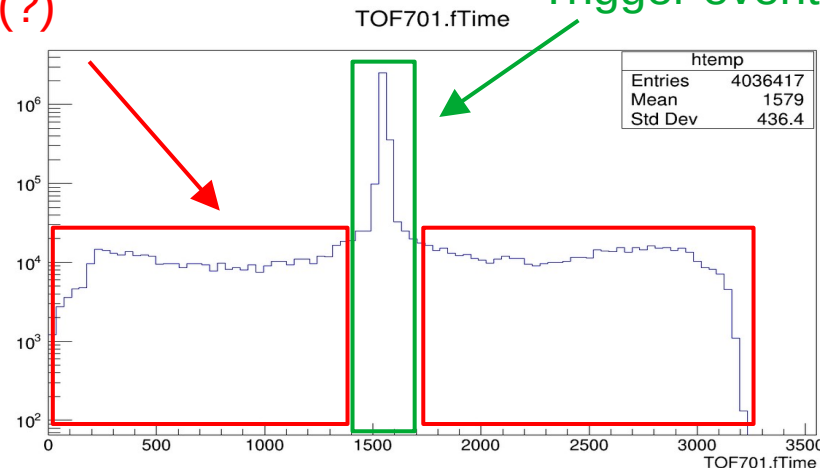
bmnroot/detectors



In progress

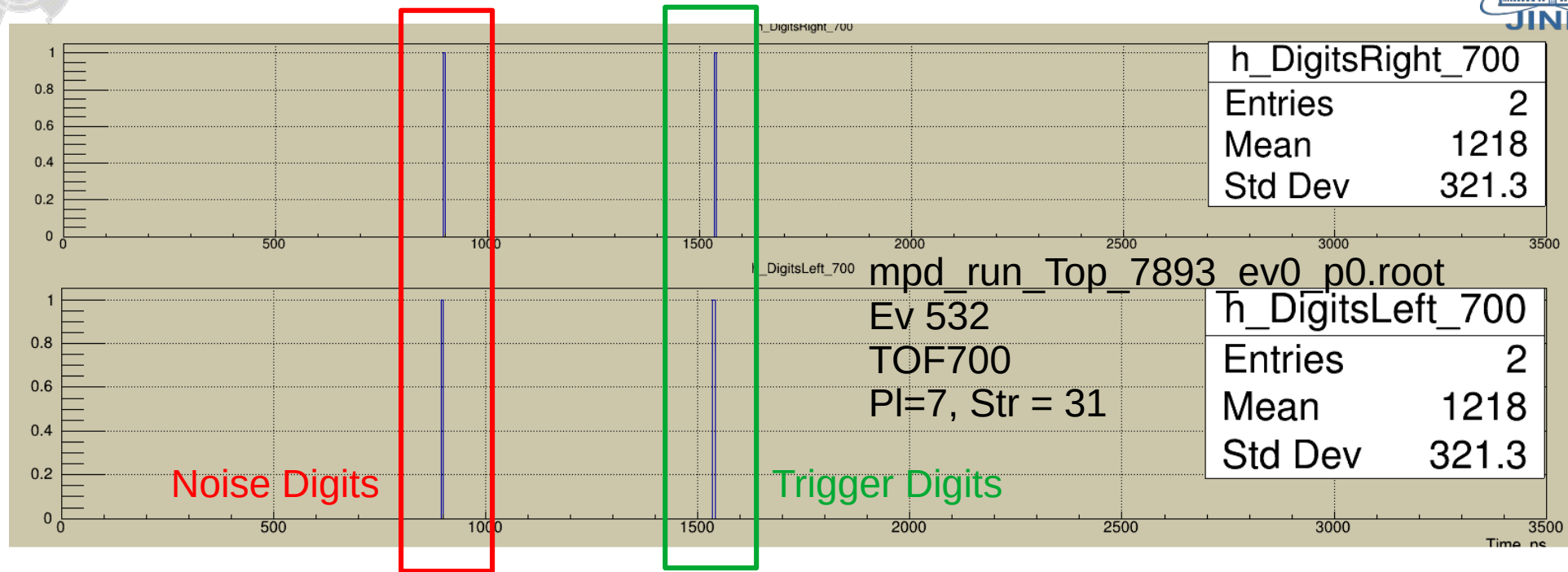
Noise (?)

Trigger events



Since the mRPC detector has been shown to have low noise, **only one hit (the first one in time) was reconstructed on each strip**. However due to the large reading window ( $\sim 3\mu\text{s}$ ), there may be situations when more than one “particle” gets into the strip, from trigger event and from a noise.

# “New” HitProducer procedure



A hit is “possible” if there are digits on both sides of the strip and the reconstructed coordinate is located within the length of the strip:

$$\frac{(T_1 - T_2) * 0.5}{SignalVelocity} \leq \frac{StripLength}{2}$$

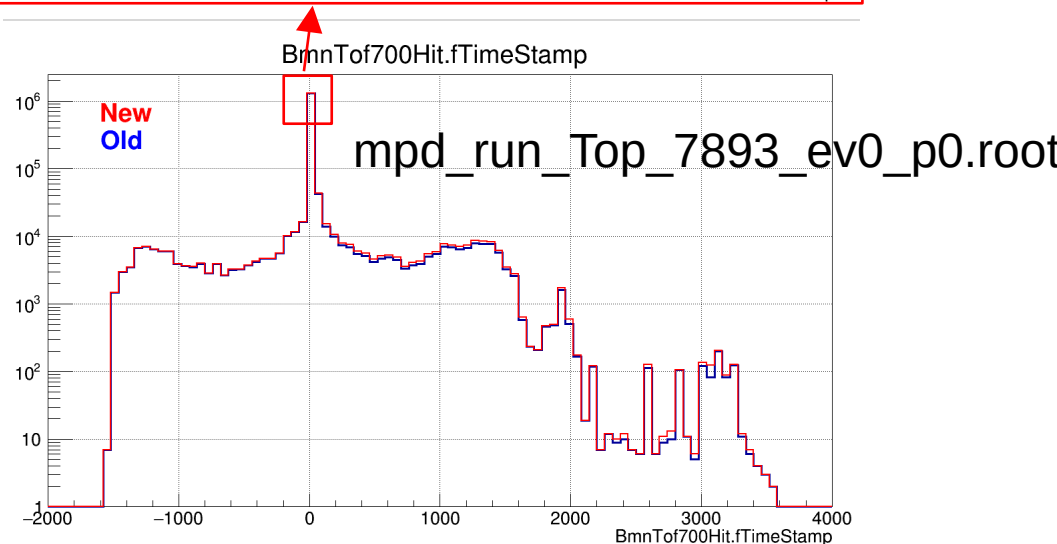
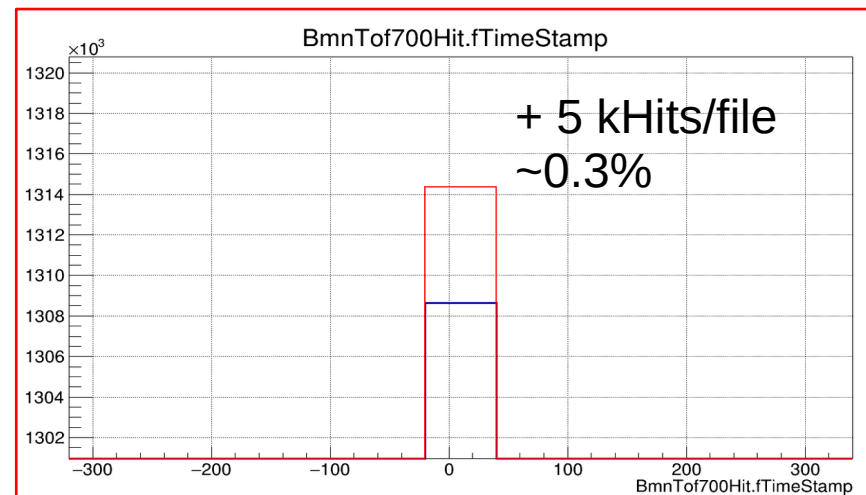
In the old version of the software, only the first “noise” hit would be reconstructed, as it was the first in time. In the updated version, both hits will be reconstructed.

A hit is called “possible” if its reconstructed coordinate is within the length of the strip.

“Old” procedure: only one possible hit (the first one in time) is reconstructed on the strip.

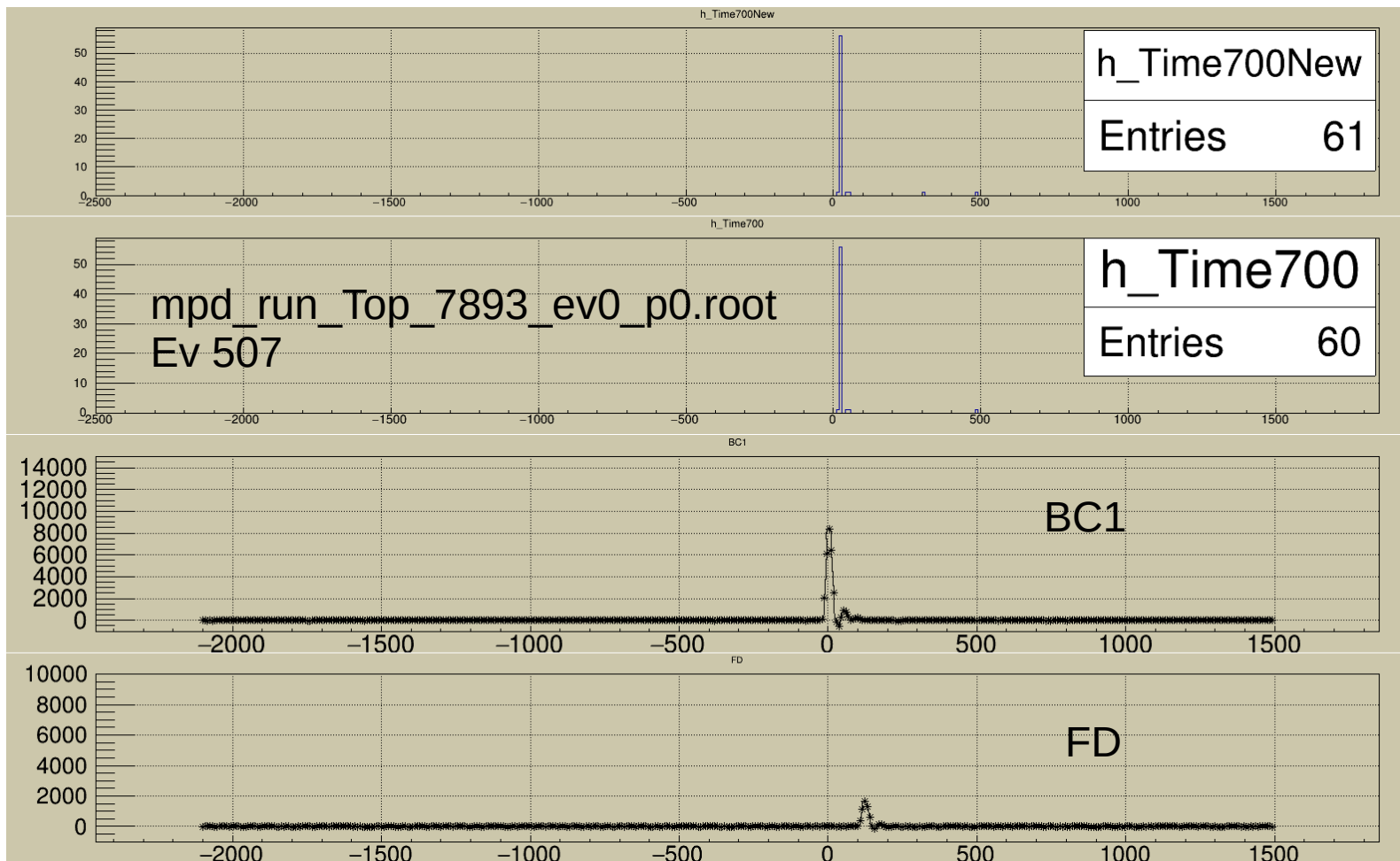
“New” procedure: all possible hits are reconstructed on the strip.

All the "old" hits have been reconstructed by the new algorithm!



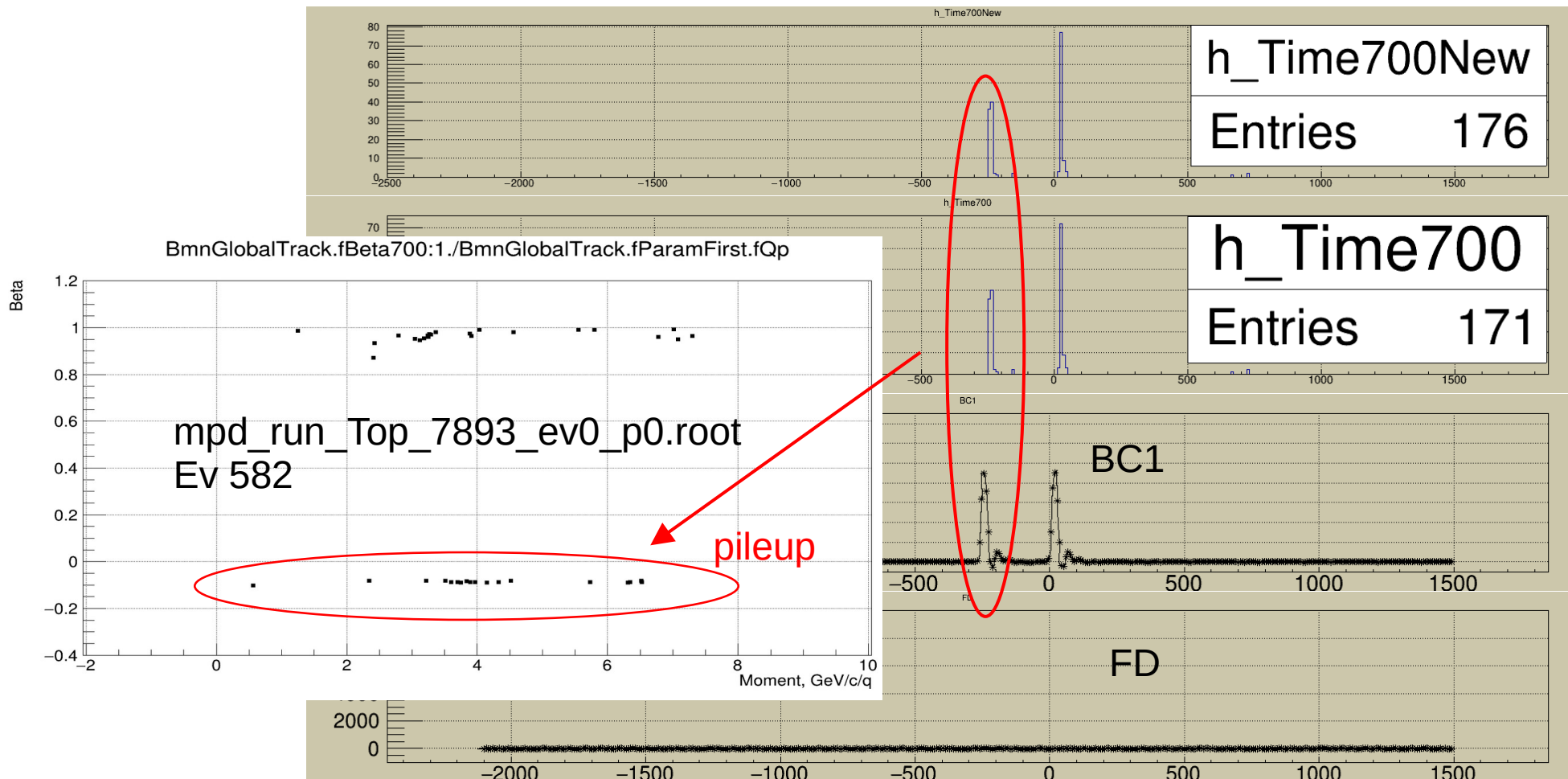


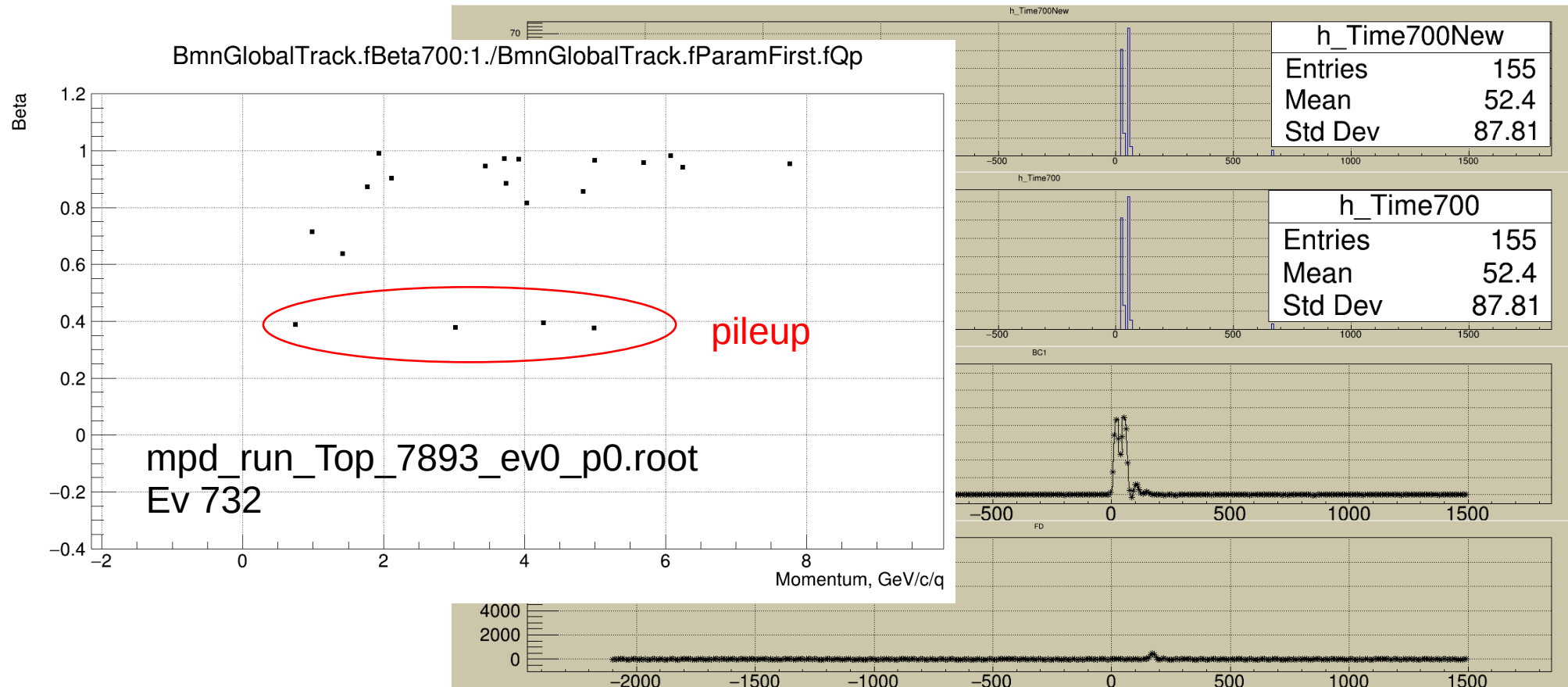
# “New” HitProducer procedure



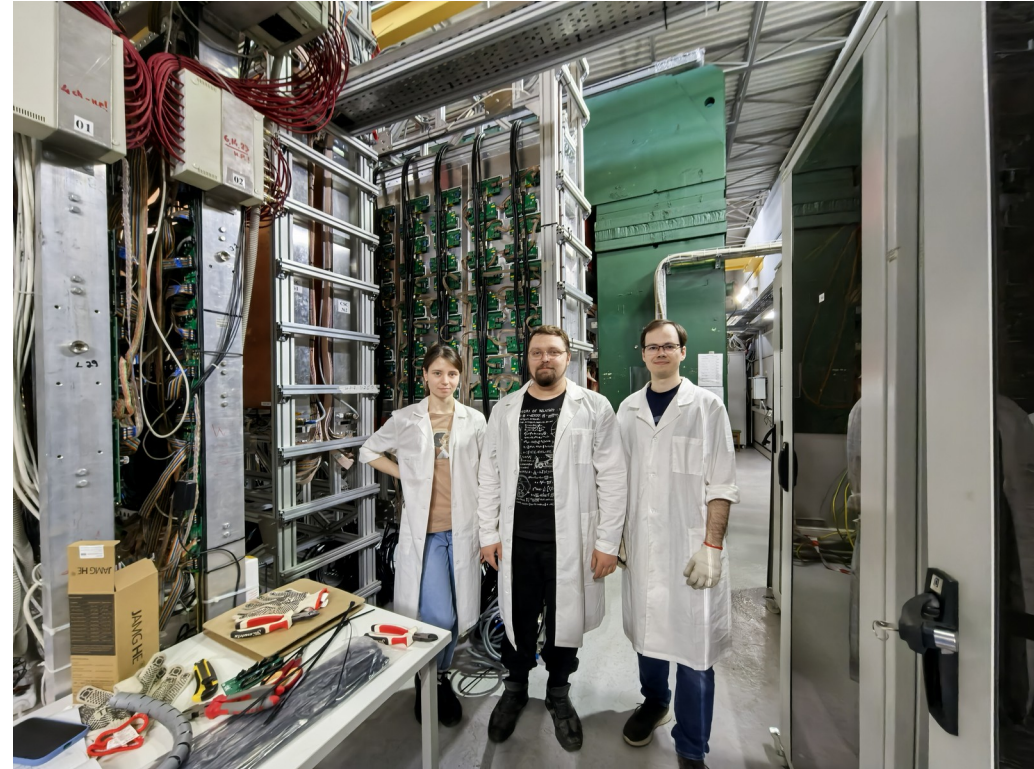


# “New” HitProducer procedure



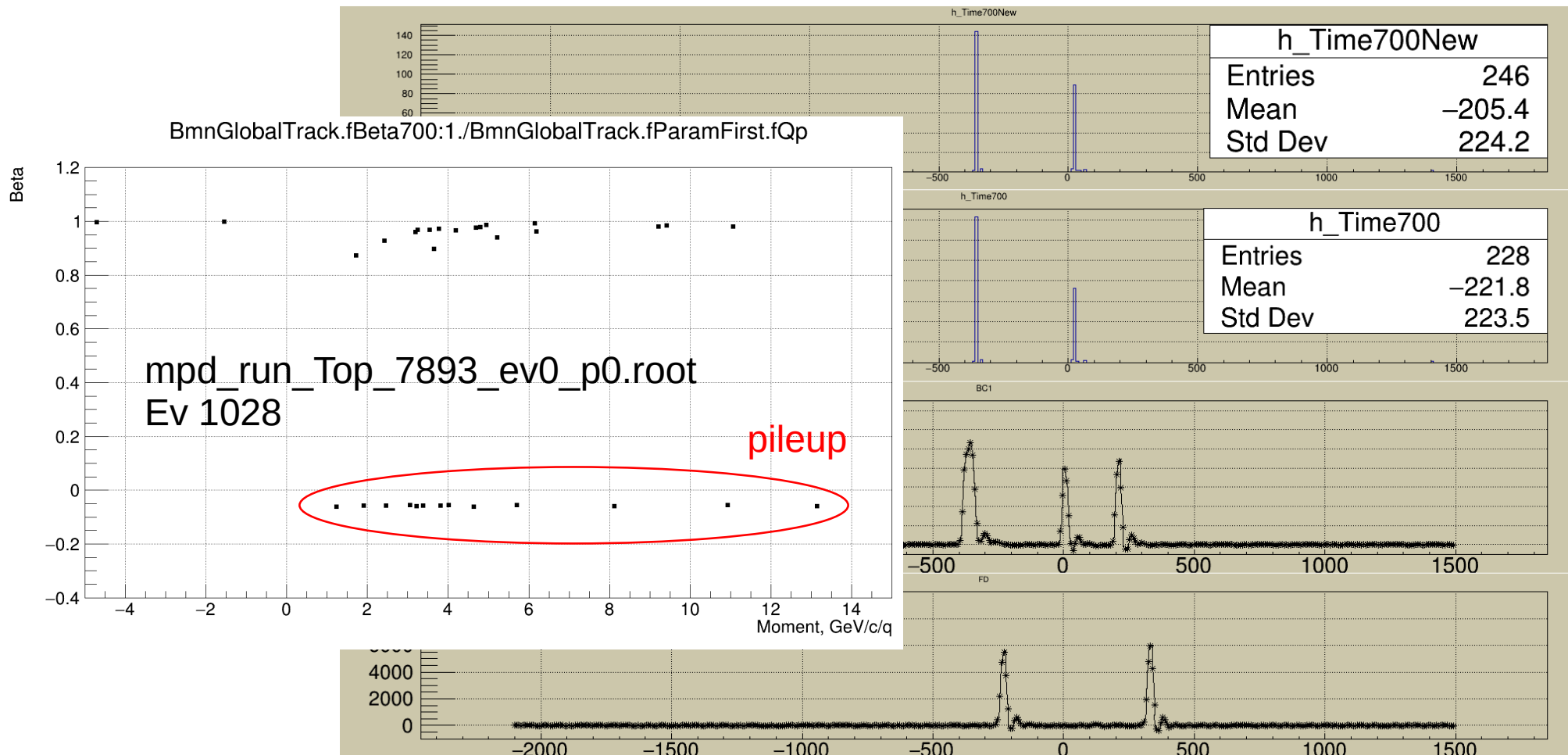


- A new advanced procedure for hits reconstruction is being prepared for the commit.
- There is an possibility to untangle pileup events using time information from trigger counters and TOFs(or mark pileup tracks/hits).
- All TOF400 new boxes are installed in the BM@N area (thanks to MEPhi group).
- The boxes are checked for gas leak.
- All service cables (HL, LV, SlowControl) are connected.
- The signal cables should be connect this week.
- TOF700 system does not have any changes compared to the previous run.



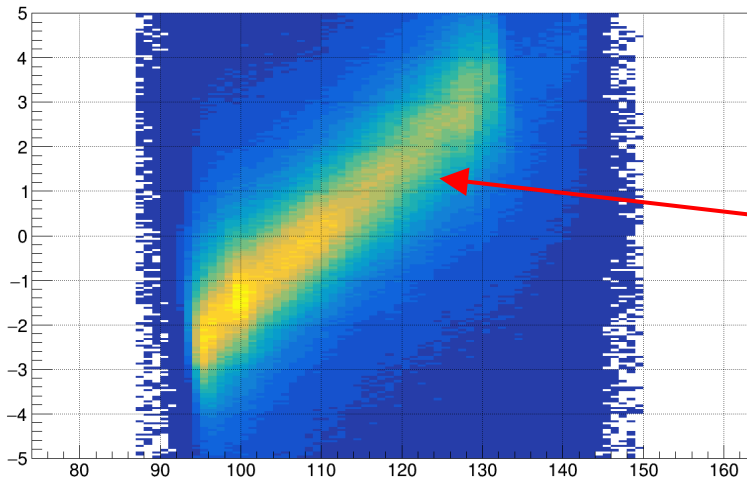
# Backup

# “New” HitProducer procedure



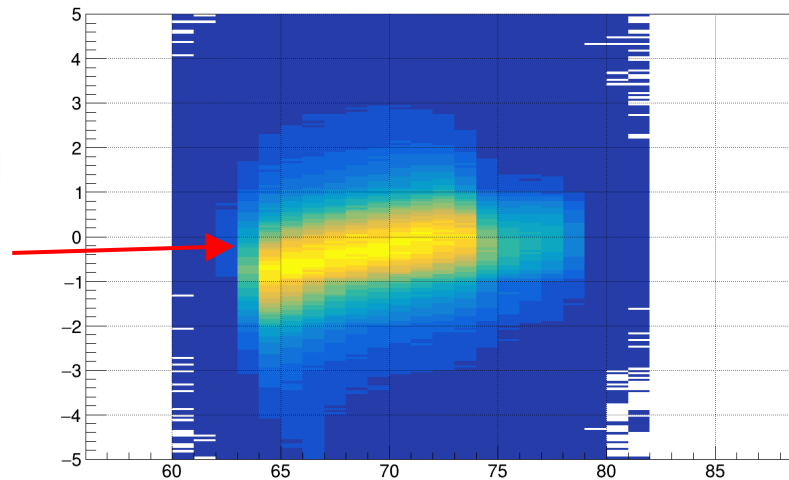
# Matching problem along a strip (x coordinate)

dx\_vs\_x\_Plane42

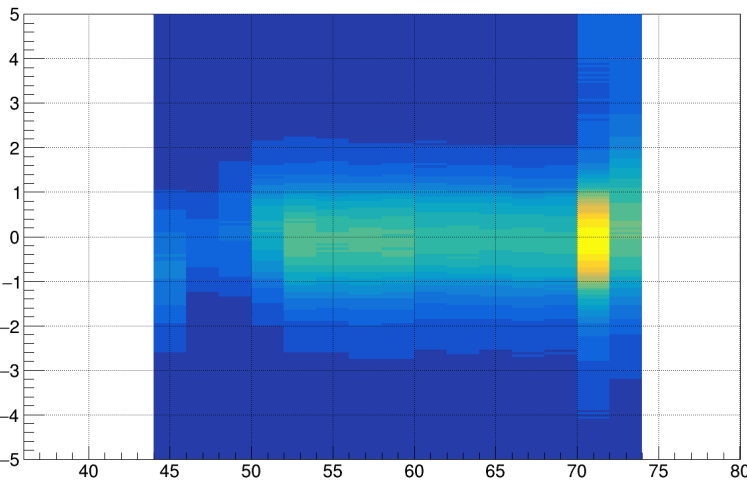


Slope is observed  
only for dx\_vs\_x  
distribution

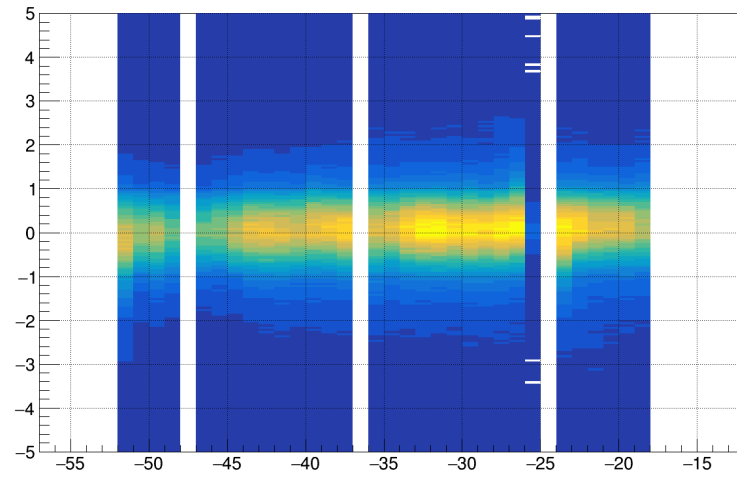
dx\_vs\_x\_Plane32



dy\_vs\_y\_Plane42

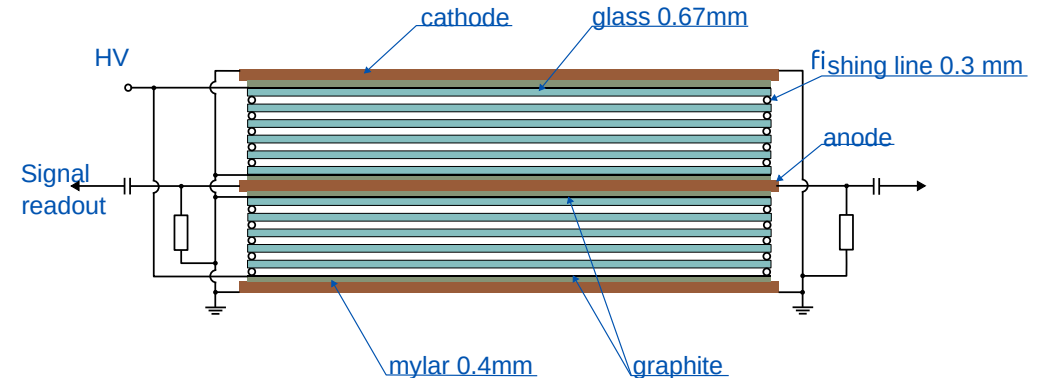
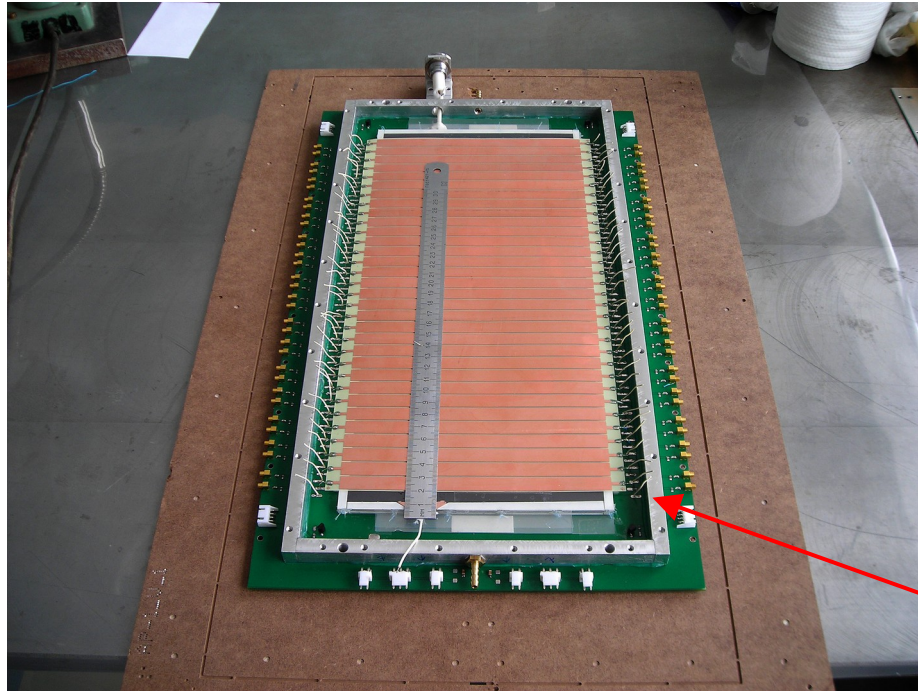


dy\_vs\_y\_Plane32





## Matching problem along a strip (x coordinate)



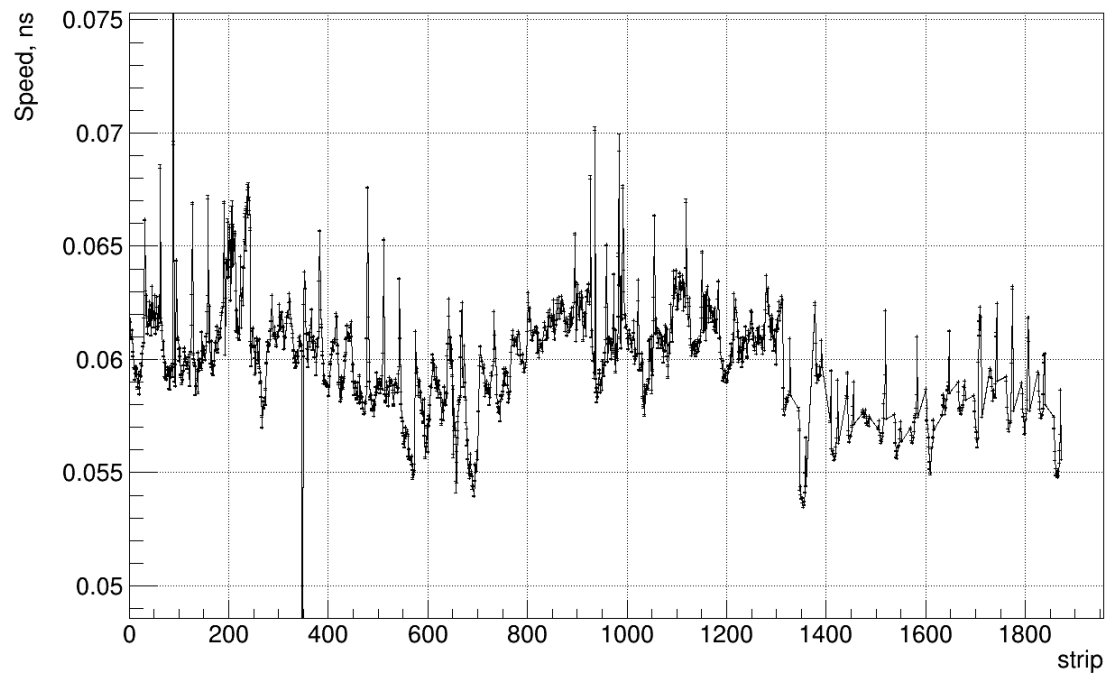
The robust frame prevent capacitance changes at the edges of the detector

For coordinate reconstruction the "speed of signal" constant is used. It depends on the dielectric environment and the capacitance between the strip and ground. Our assumption is that when voltage is applied, the capacitance between the ground and the strip in the center of the detector changes. So we need to **calculate the "speed of signal" for each strip**, instead of using a single constant.

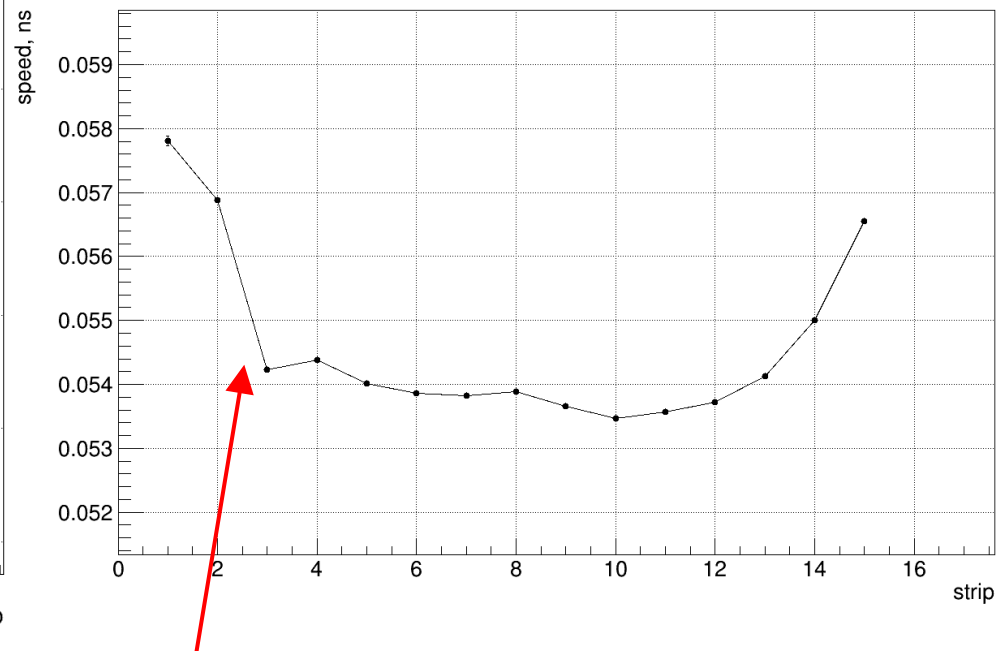


# Matching problem along a strip (x coordinate)

gr\_Speed\_for\_Planes



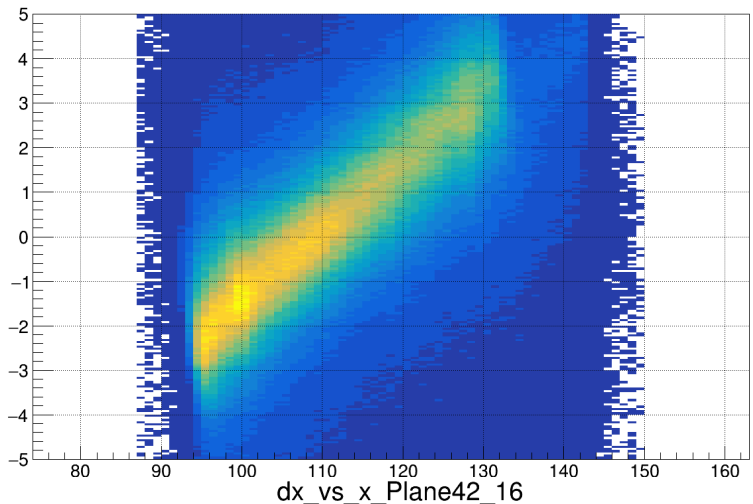
gr\_Speed\_for\_Plane\_42



A speed difference of 4 ps/cm results in a coordinate error of about 4 cm on a 56 cm long strip. The shape of the curve confirms the assumption that the speed changes due to the change in capacity in central region of the detector.

# Matching problem along a strip (x coordinate)

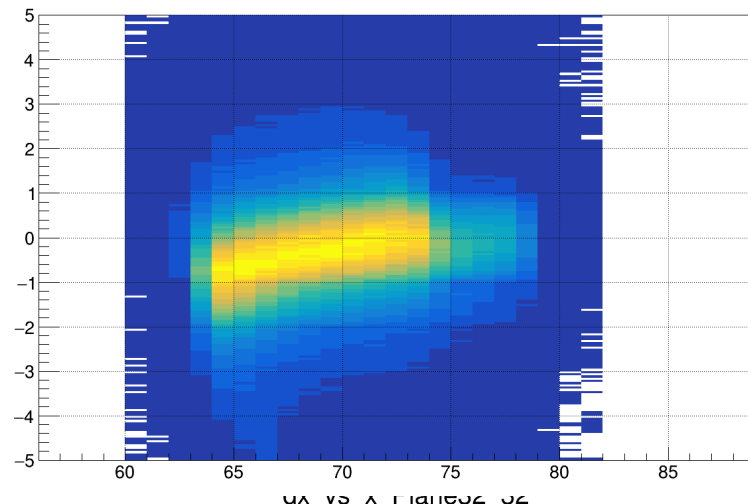
dx\_vs\_x\_Plane42



before

After “speed of signal”  
correction the  
distribution looks better.  
But we need to align  
detectors again.

dx\_vs\_x\_Plane32



after

