



## Status of track reconstruction for SPD

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## Introduction

### **Track reconstruction** is usually divided on two separate sub-tasks:

- a) track finding (or pattern recognition);
- b) track fitting (in general on the base of Kalman filter method).

### **Track finding:**

- a) division set of measurements in the tracking detectors (vertex and tracker) into subsets;
- b) each subset contains measurements believed to originate from the same particle.

**Track fitting** - starts with the measurements inside one subset as was provided by the track finder.



**2D** 

- **3D** global fitting picking stereo hits Z-S fit + ambiguity tracks
- 1. Track finding algorithm starts from 2D (x-y plane) :
  - use the wire position of fired straw tubes as input;
  - apply conformal and Hough transformations;
  - consider z-axial straw tubes and find peaks;
  - provide 2D circle fitting;
  - picking stereo hits (hits from tilted straw tubes);
  - estimation of z and phi of track candidate;
  - finally apply 3D Kalman fitting.



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### **Event example**



Red points – hits in straw parallel to z-axis Green points – hits in straw tilted on  $+3^{\circ}$ Blue points – hits in straw tilted on  $-3^{\circ}$ 



![](_page_4_Figure_4.jpeg)

- 1. Use PYTHIA8 with open charm production option at  $\sqrt{s} = 27$  GeV as testing event sample
- 2. Middle plot presents fired z-axial straw tubes in XY projection
- 3. Transform (only rotate) global coordinate of straw tubes to the local coordinates system (or coordinates which coincide with system of Octant 3)
- 4. All further consideration will be done in local coordinate

![](_page_5_Figure_0.jpeg)

- 5) find peaks on 2D histogram and select axial hits;
- 4) 2D circle fitting;

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# **2D finding efficiency**

₠≖₩₩

1.4

1.4

1.6

1.8

2

Pt

1.6

1.8

2

Pt

![](_page_6_Figure_1.jpeg)

7

## Longitudinal track reconstruction

- 1. Charge particle trajectory in constant magnetic field is helix which can be described:
  - a) in XY plane as circle with radius  $R = PT / 0.3 \cdot B$ ;
  - b) z-coordinate is the function of arc length (s),  $z(s) = z0 + s \cdot tan\lambda$ , where  $s = (\Phi \Phi 0) \cdot R \cdot q$ ,

 $\Phi$  – azimuthal angle,  $\lambda$  – dip angle, z0 and  $\Phi$ 0 – track parameters in starting point or in primary vertex

![](_page_7_Figure_5.jpeg)

2. The z-position for each hit in a tilted straw tube is extracted through an alignment procedure as illustrated below. The track radius is determined before by the pattern recognition procedure in XY-plane.

Since these tubes are tilted, the projection of the drift radius onto the XY-plane becomes an ellipse. The drift ellipse is aligned such way that its center position lies along x-axis of layer and is tangential to the particle trajectory.

This alignment provides two solutions, introducing a left/right ambiguity with one solution on each side of the trajectory

## Longitudinal track reconstruction (2)

#### Recursive annealing fit:

- a) fit by line to all points;
- b) remove point with largest residual;
- c) calculate new line fit;
- d) repeat until one point has been rejected for each straw tube;
- e) do final line fit.

![](_page_8_Figure_7.jpeg)

![](_page_8_Figure_8.jpeg)

### Recursive annealing fit is used in our case.

# Example of recursive fit

![](_page_9_Figure_1.jpeg)

Another event example (only 1-st generation tracks)

![](_page_10_Figure_1.jpeg)

80 100 x, cm

# Another event example (all generation tracks)

Red points – hits in straw parallel to z-axis

Green points – hits in straw tilted on +3°

Blue points - hits in straw tilted on -3°

![](_page_11_Figure_4.jpeg)

![](_page_11_Figure_5.jpeg)

![](_page_11_Figure_6.jpeg)

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# Another event example (2)

![](_page_12_Figure_1.jpeg)

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## Another event example (longitudinal track finding)

![](_page_13_Picture_1.jpeg)

# **3D global fitting**

This longitudinal hits finding procedure provides the next track candidate parameters:

- a) tilted hits which are belong to the considered track candidate;
- b) estimation of theta and phi angles;
- c) estimation of primary vertex position or track position at the first point.

Last step of reconstruction is the fitting procedure of track candidates:

- a) we have set of straw tubes (or hits) which are belonged to the track candidate;
- b) estimated position of 1-st track point;
- c) estimation of track momentum (Px, Py, Pz) at the 1-st track point (or in the primary vertex);
- d) then standard SPD fitting procedure (on the base Kalman filter from Genfit2) can be applied.

### Conclusion - track reconstruction procedure using the only straw detector works.

## Track reconstruction (only 1-st generation, Ts hits > 6)

![](_page_15_Figure_1.jpeg)

### Reconstruction track (only 1-st generation)

![](_page_16_Figure_1.jpeg)

## Reconstruction efficiency (only 1-st generation)

![](_page_17_Figure_1.jpeg)

# Track reconstruction (all generation)

![](_page_18_Figure_1.jpeg)

## Reconstruction efficiency (all generations)

![](_page_19_Figure_1.jpeg)

![](_page_19_Figure_2.jpeg)

![](_page_19_Figure_3.jpeg)

![](_page_19_Figure_4.jpeg)

Eff vs θ

## **Summary**

- 1. General schema for track reconstruction works.
- 2. It provides relatively good track reconstruction efficiency.
- 3. Need to check some points and tune the reconstruction procedure.
- 4. Preliminary conclusion present tracker geometry is "acceptable" for the track reconstruction using only straw tracker.