A computational algorithm for covariant series expansions in general relativity

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### References

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### Normal neighborhood of a submanifold

A real analytic manifold  $H, \ \dim H \!=\! n \!+\! m, \ n \!>\! m \!\geqslant\! 0$ 

A connected parallelizable submanifold  $M, \ \dim M \!=\! m$  If  $\dim M \!=\! m \!=\! 0$  then M is a point on H

$$p \in M, \quad T_p(H) = T_p(M) \oplus O_p, \quad X = X^i \mathbf{e}_i = X^{\alpha} \mathbf{e}_{\alpha} + X^a \mathbf{e}_a$$

The Latin indices  $i, j, \ldots$  run from 1 to n + m:  $T_p(H)$ The Greek indices  $\alpha, \beta, \ldots$  run from 1 to n:  $O_p$ The Latin indices  $a, b, \ldots$  run from m+1 to n+m:  $T_p(M)$ 

A linear connection  $\nabla$  on H:  $\nabla_k = \nabla_{e_k}, \ \nabla_i e_j = \Gamma_{ij}^k e_k$ 

The exponential map:  $\gamma_{X}(0) = p, \ \gamma_{X}(1) = q$ 



$$p \in M$$
,  $X \in O_p$   
 $O_p = \langle e_1, e_2 \rangle$   
 $T_p(M) = \langle e_3 \rangle$ 

 $\begin{array}{l} \gamma_{\!_X} \text{ is a geodesic on } H \\ \text{in the direction of } X \\ \text{starting at } p \in M \end{array}$ 

At each point  $p \in M$  we choose a basis  $\{e_i\}_1^{m+n}$  such that the vectors  $\{e_a\}_{m+1}^{m+n}$  are tangent to M and the vectors  $\{e_a\}_1^n$  are transverse to M

# General form of the covariant expansion I

$$\begin{split} \left(Q_{i_{1}\dots i_{r}}^{j_{1}\dots j_{s}}\right)_{q} &= \sum_{\sigma+|\mu|+|\nu|\geq 0} \frac{1}{\sigma!} X^{\gamma_{1}}\dots X^{\gamma_{\sigma}} \left(Q_{k_{1}\dots k_{r};\gamma_{1}\dots\gamma_{\sigma}}^{l_{1}\dots l_{s}}\right)_{p} \times \\ & \times u_{(\mu_{1})^{i_{1}}}^{k_{1}}\dots u_{(\mu_{r})^{i_{r}}(\nu_{1})^{l_{1}}}^{k_{r}}\dots u_{(\nu_{s})^{i_{s}}}^{k_{s}}, \\ & \sigma,\mu_{1},\dots,\mu_{r},\nu_{1},\dots,\nu_{s}\geq 0, \quad |\mu|=\mu_{1}+\dots+\mu_{r}, \quad |\nu|=\nu_{1}+\dots+\nu_{s}, \\ & v_{(\mu)}^{k} = -\sum_{\sigma=1}^{\mu} v_{(\mu-\sigma)}^{k} u_{(\sigma)}^{l}, \quad \mu \geq 1. \\ & v_{(\mu)}^{k} = \delta_{i}^{k}, \quad u_{\alpha}^{k} = \frac{1}{2} X^{\beta} (T_{\beta\alpha}^{k})_{p}, \quad u_{\alpha}^{k} = X^{\beta} (\Gamma_{\beta a}^{k}+T_{\beta a}^{k})_{p}, \end{split}$$

### General form of the covariant expansion II

$$\begin{aligned} u_{(\mu)}^{k} &= \\ \frac{2}{2\mu + \varepsilon(i) + 1} \sum_{\sigma=1}^{\mu} \frac{1}{(\sigma - 1)!} X^{\alpha_{1}} \dots X^{\alpha_{\sigma}} (T_{\alpha_{1}l; \alpha_{2} \dots \alpha_{\sigma}}^{k})_{p} \underbrace{u_{(\mu - \sigma)}^{l}}_{(\mu - \sigma)^{i}} + \\ \frac{1}{\mu(\mu + \varepsilon(i))} \sum_{\sigma=2}^{\mu} \frac{1}{(\sigma - 2)!} X^{\alpha_{1}} \dots X^{\alpha_{\sigma}} (R_{\alpha_{1}\alpha_{2}l; \alpha_{3} \dots \alpha_{\sigma}}^{k})_{p} \underbrace{u_{(\mu - \sigma)}^{l}}_{(\mu - \sigma)^{i}}, \\ \mu \geq 2, \quad \varepsilon(\alpha) = 1, \quad \varepsilon(a) = -1, \end{aligned}$$

# The expansion of a Riemannian metric

$$(g_{ik})_q = \sum_{\mu+\nu \ge 0} (g_{jl})_p \underbrace{u_j^i u_{(\nu)}^k}_{(\nu)i},$$
$$\underbrace{u_{(0)}^k = \delta_i^k, \quad u_{(1)}^k = 0, \quad u_{(1)}^k = X^\beta (\Gamma_{\beta a}^k)_p,$$
$$\underbrace{u_{(\mu)}^k}_i =$$
$$\frac{1}{\mu(\mu+\varepsilon(i))} \sum_{\sigma=2}^{\mu} \frac{1}{(\sigma-2)!} X^{\alpha_1} \dots X^{\alpha_\sigma} (R_{\alpha_1 \alpha_2 l; \alpha_3 \dots \alpha_\sigma}^k)_p \underbrace{u_{(\mu-\sigma)}^l}_{(\mu-\sigma)i}$$
$$\mu \ge 2, \quad \varepsilon(\alpha) = 1, \quad \varepsilon(a) = -1,$$

## Some problems in the general statement

- Spacetime metric is known. It is necessary to find the metric in some domain in normal coordinates (eg., in the tube neighborhood of the worldline of a particle).
- Spacetime metric has a high-dimensional isometry group (eg., in a spherically symmetric spacetime). It is necessary to solve the Cauchy problem with initial data on some spacelike or null hypersurface using the covariant expansions.
- It is necessary to find the formal covariant power series solution of the Einstein equations in a spacetime with some additional conditions (eg., in static or stationary spacetimes).

# Outline of the algorithm



#### Time computational complexity

Let N be the degree of a monomial. An arbitrary monomial has the form  $(X_1)^{A_1} (X^2)^{A_2} \dots (X^n) A_n$ ,  $A_1 + A_2 + \dots + A_n = N$ ,

The computational complexity of the algorithm is not worse than exponential,  $O(2^N)$ , in N. This estimation can be obtained by using the Hardy–Ramanujan formula for the number of partitions of N.

The computational complexity of the algorithm is factorial, O(n!), in the dimension n of  $O_p$ .