

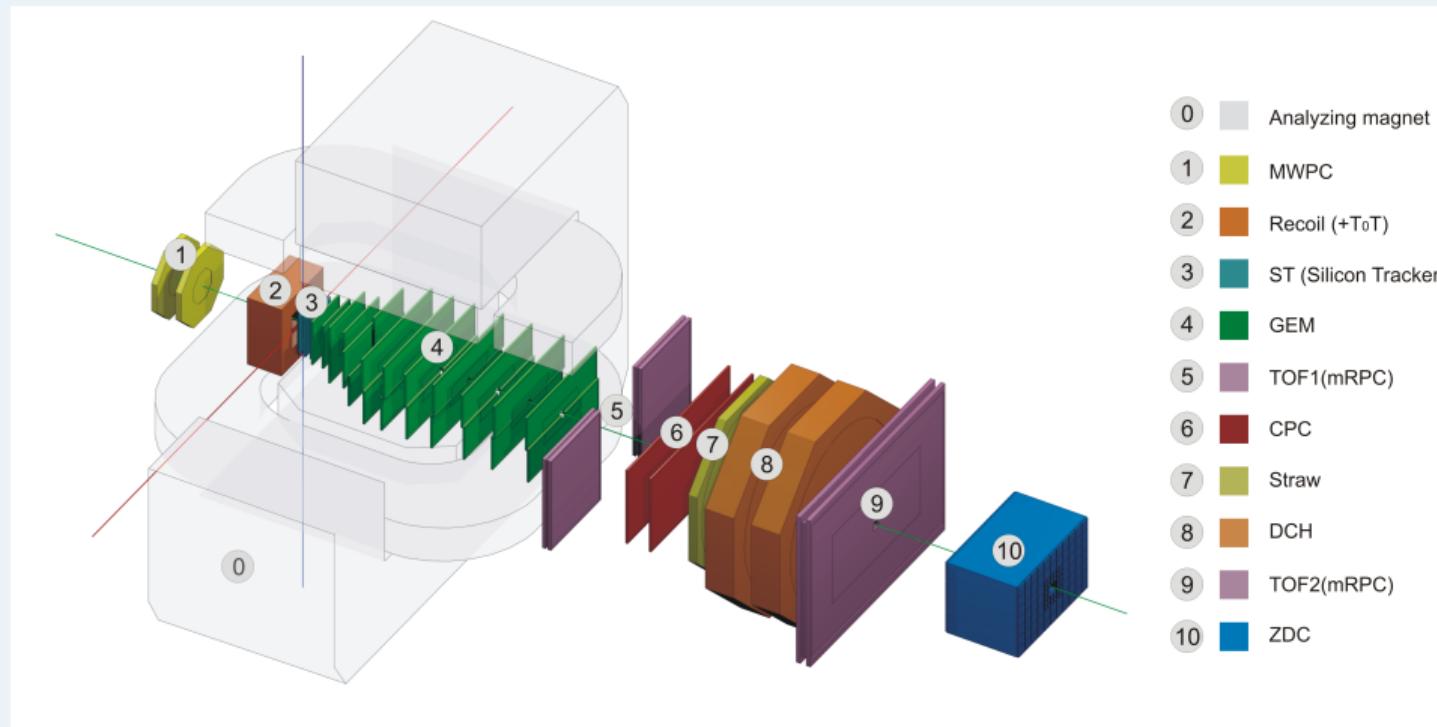
# Event reconstruction chain in GEM detector of the BM@N experiment



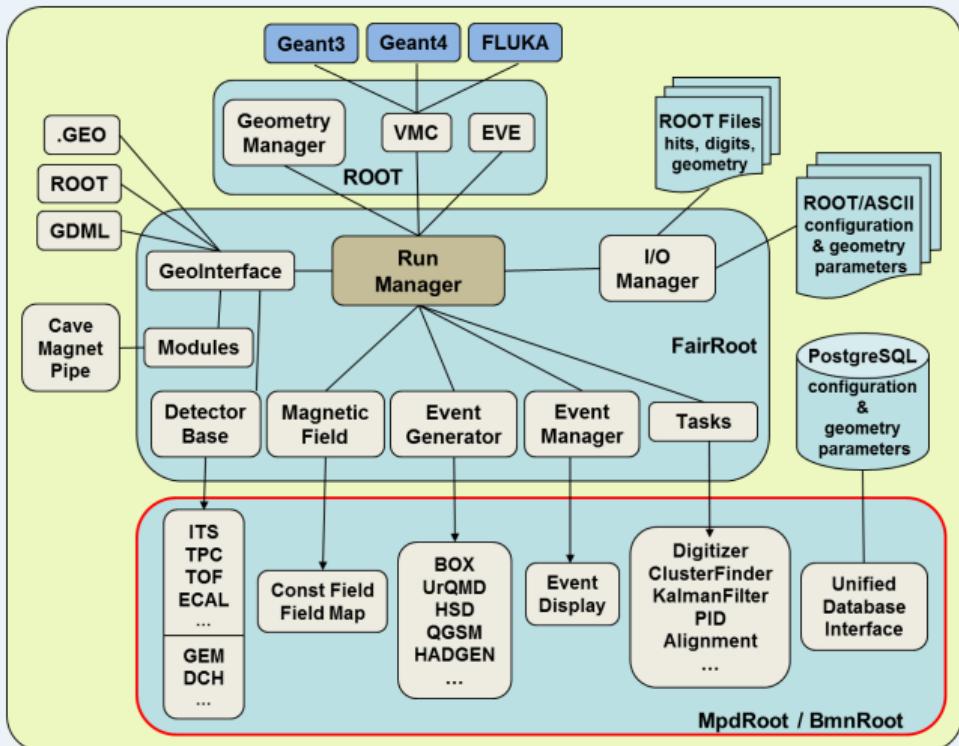
Sergei Merts  
AYSS-2018

VBLHEP

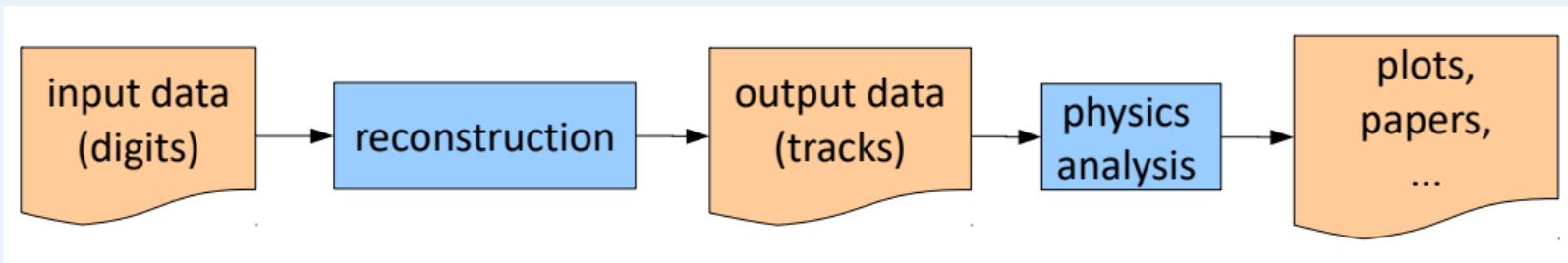
April 26, 2018



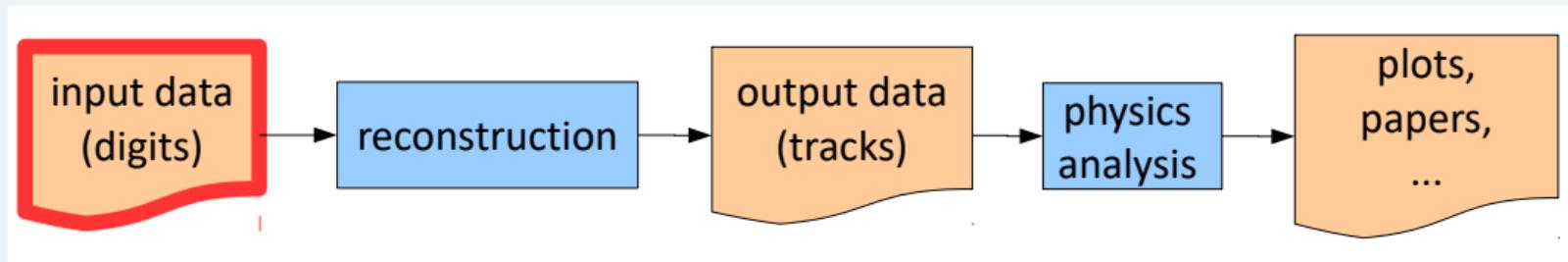
- uses FairSoft external packages (ROOT, MillePede, Geant3/4, PLUTO, etc.)
- has a part inherited from FairRoot (GSI, Darmstadt)
- includes experiment-specific parts for each detector
- has flexible and scalable structure



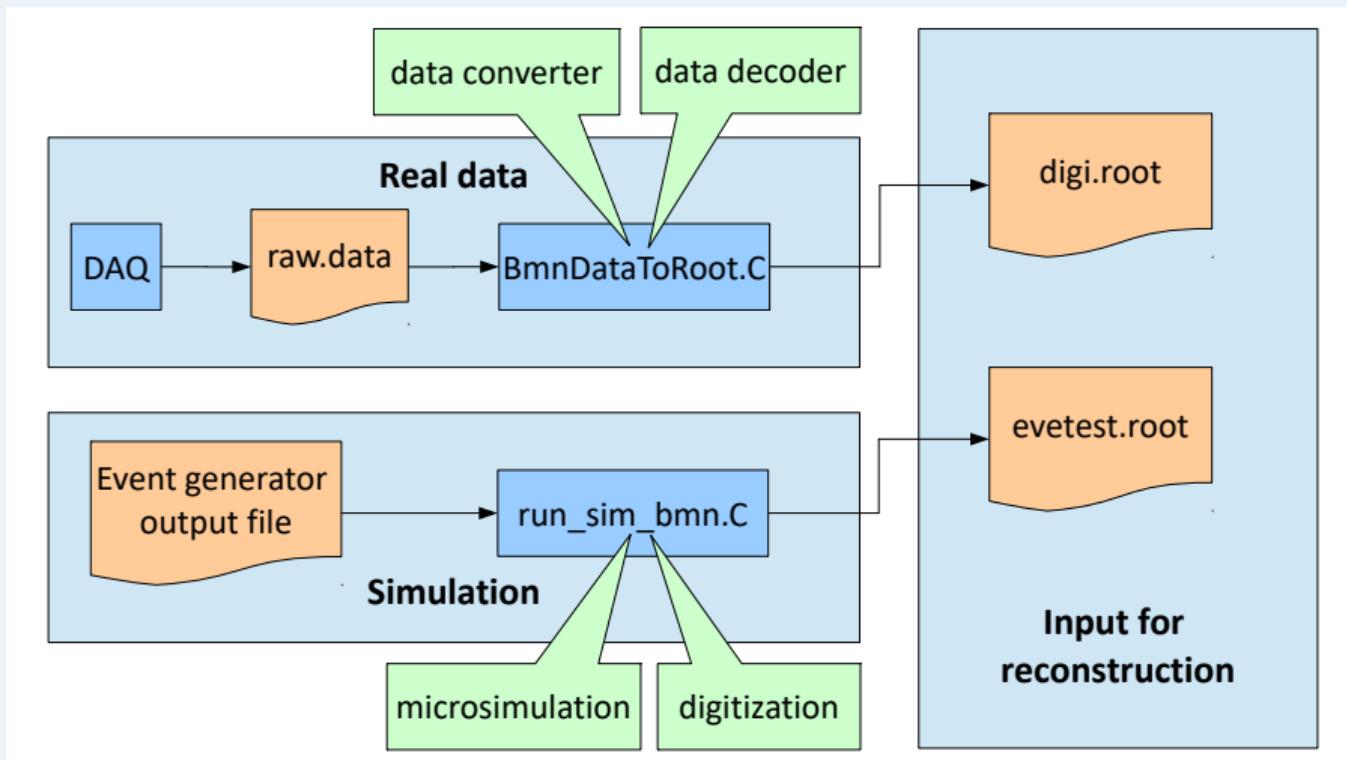
- Everybody knows how important are two procedures in blue rectangles
- But what about input data?

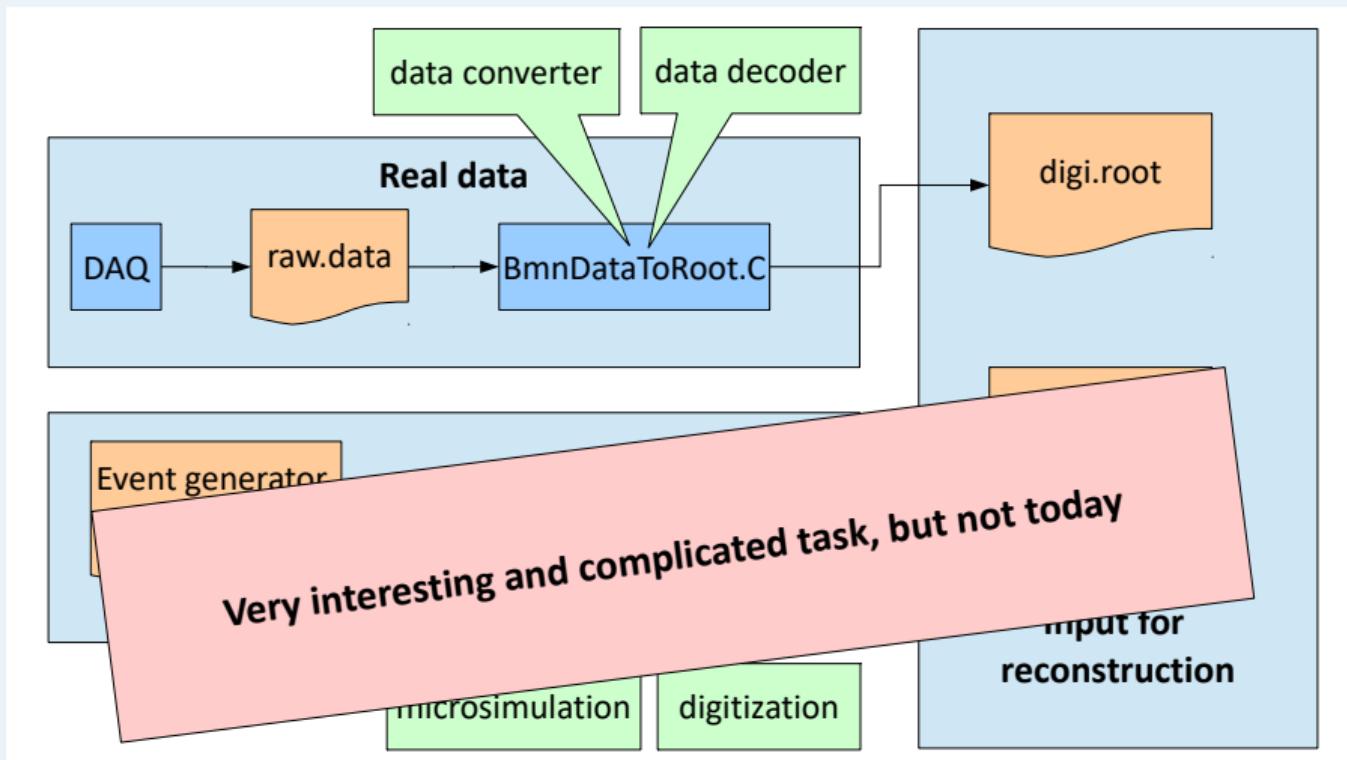


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- But what about input data?



## Where do we get data





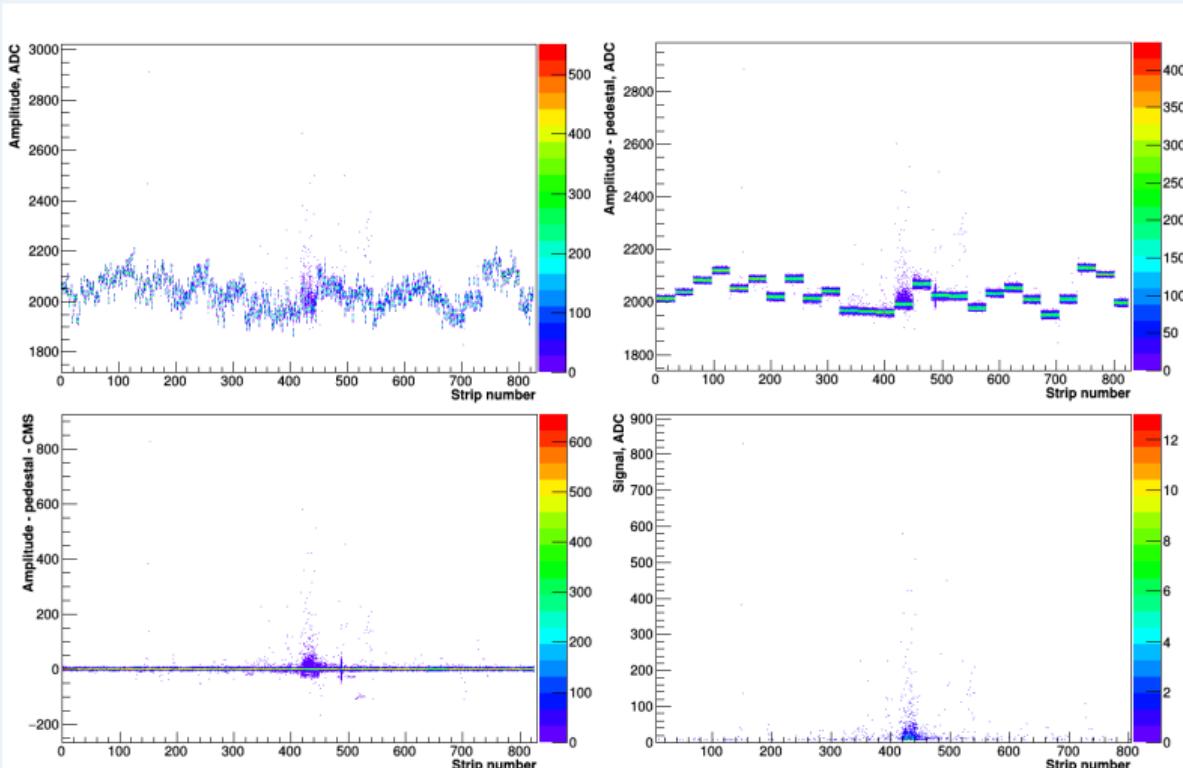
## Converter

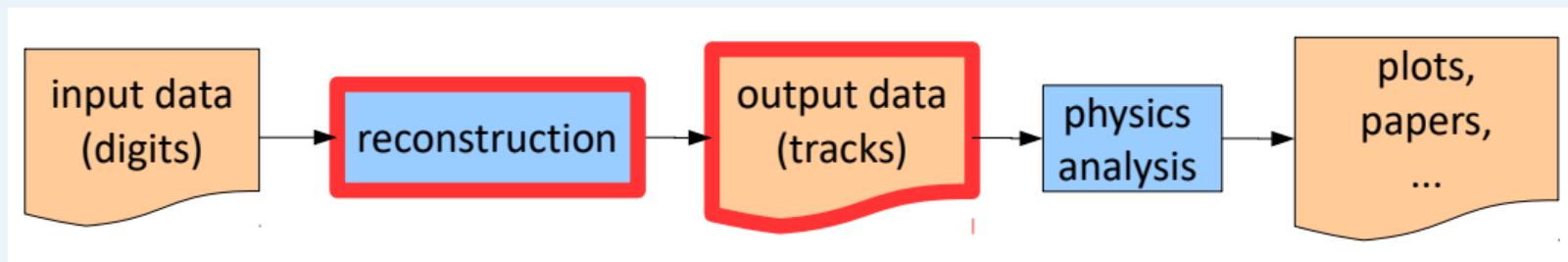
- takes **binary data file** and produces **ROOT-file** accordingly **DAQ-data-format**
- reads **macro parameters** (event number, run number, event type, etc.) and put them into **DB** on fly
- output **ROOT-file** contains tree with «**DAQ-digits**» (ADC, TDC, HRB, etc.)

## Decoder

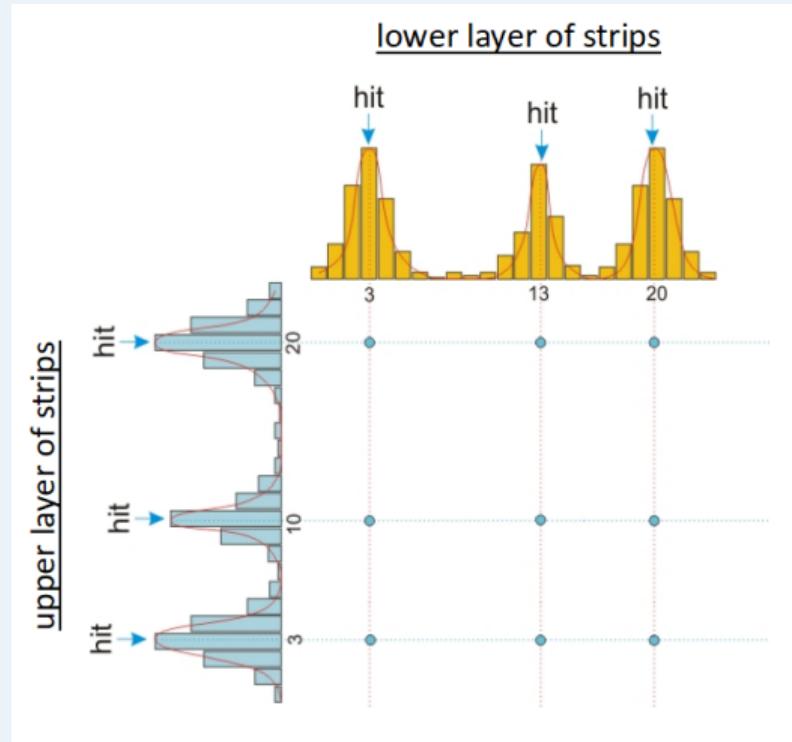
- takes **ROOT-file** with **DAQ-digits** and decodes it into **ROOT-file** with **detector-digits** (BmnGemDigit, BmnTofDigit, etc.)
- connects to **DB** to read **mappings** (channel-to-strip)
- calculates **pedestals** and **common modes** of channels
- clears **noisy channels**

## Digitization. Experimental data. Beam only

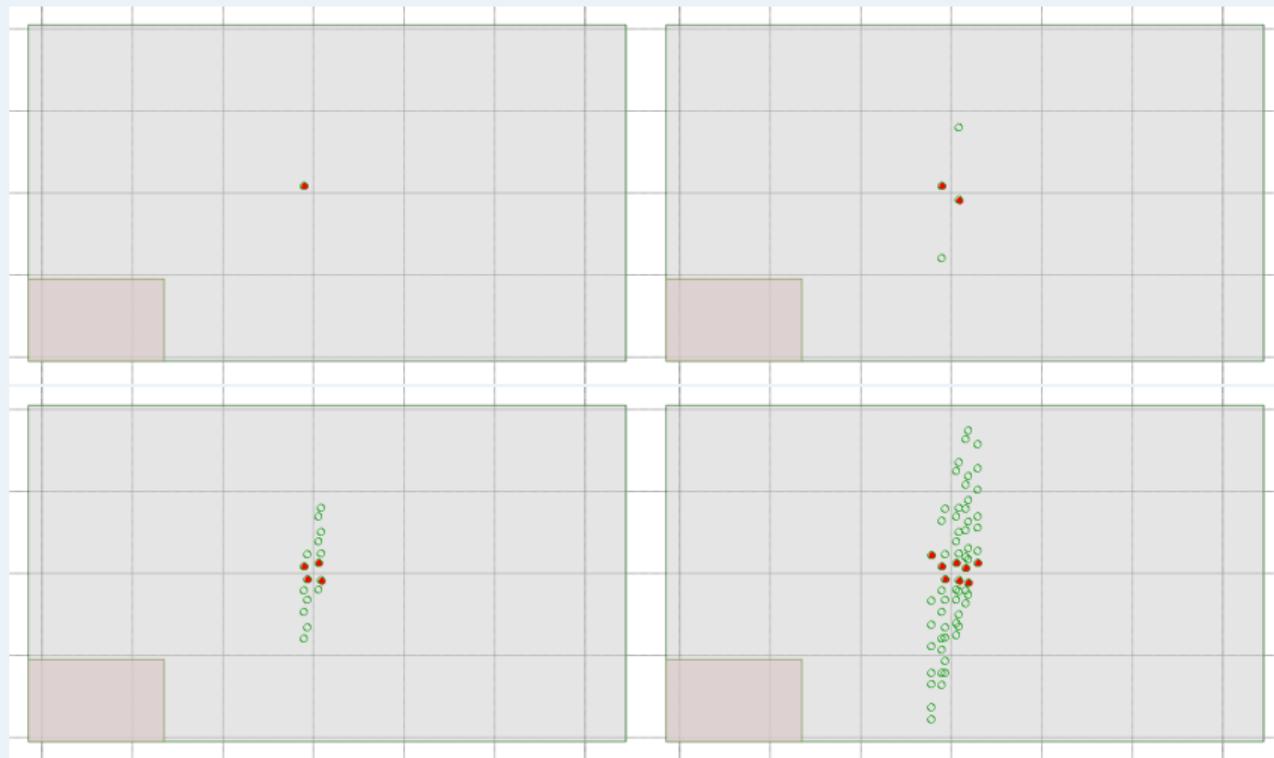


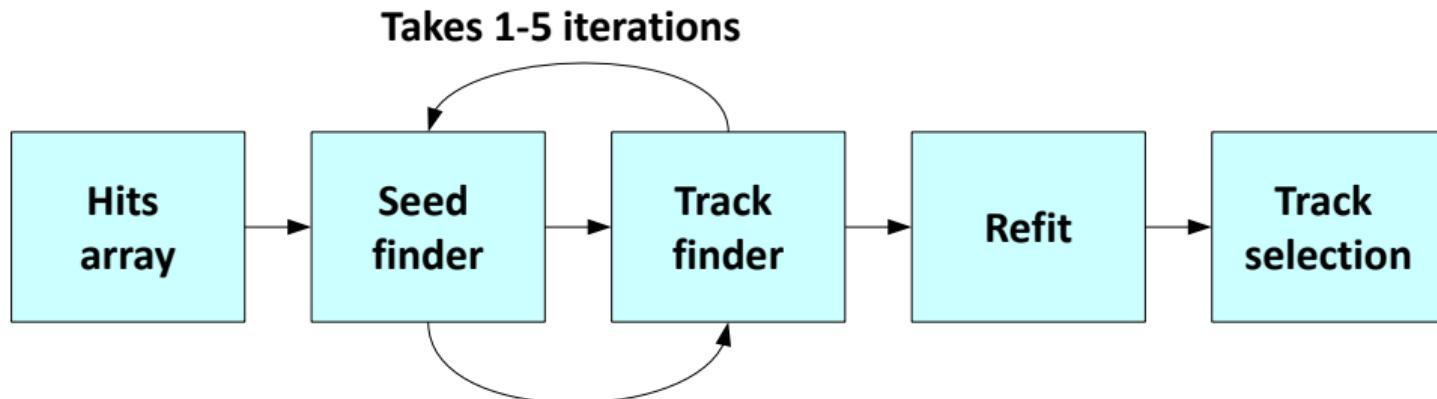


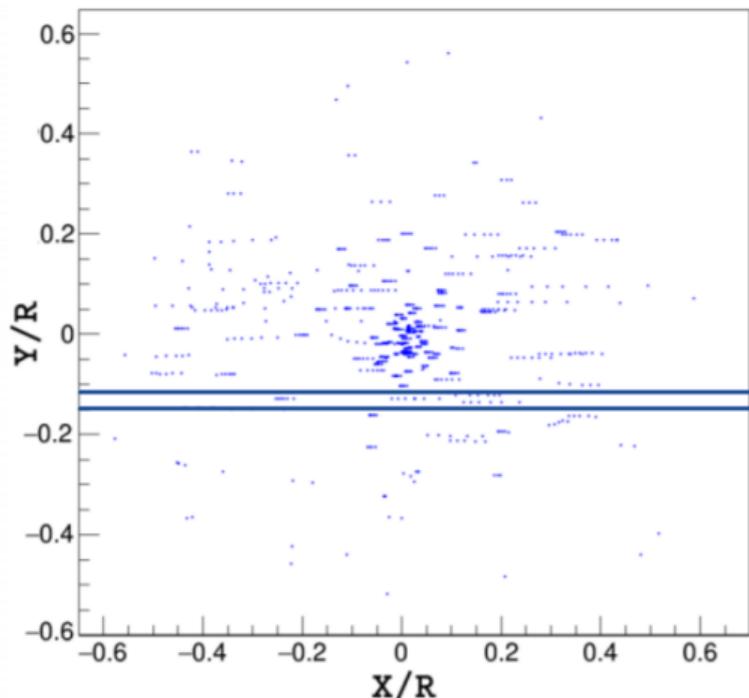
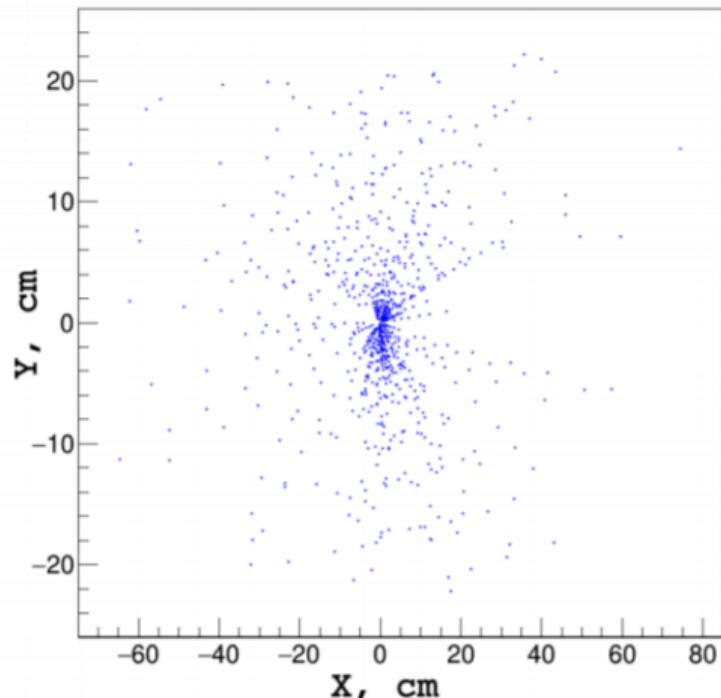
## Hit reconstruction. Description



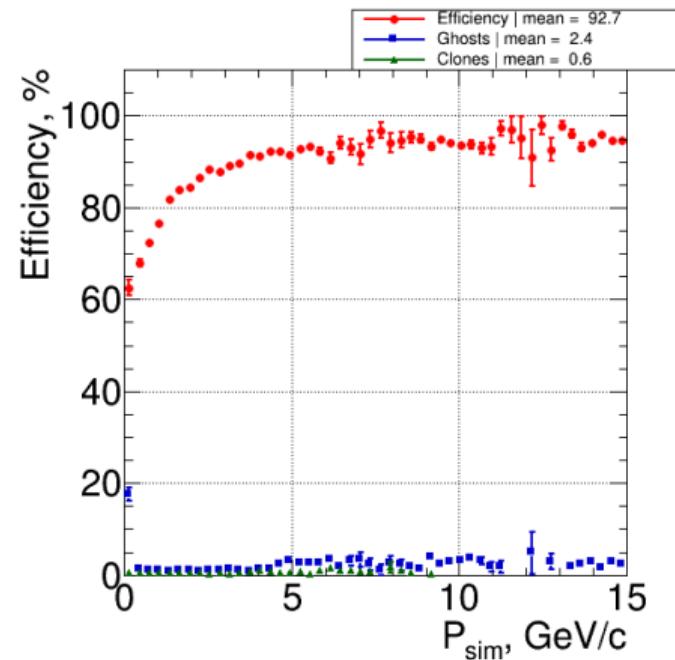
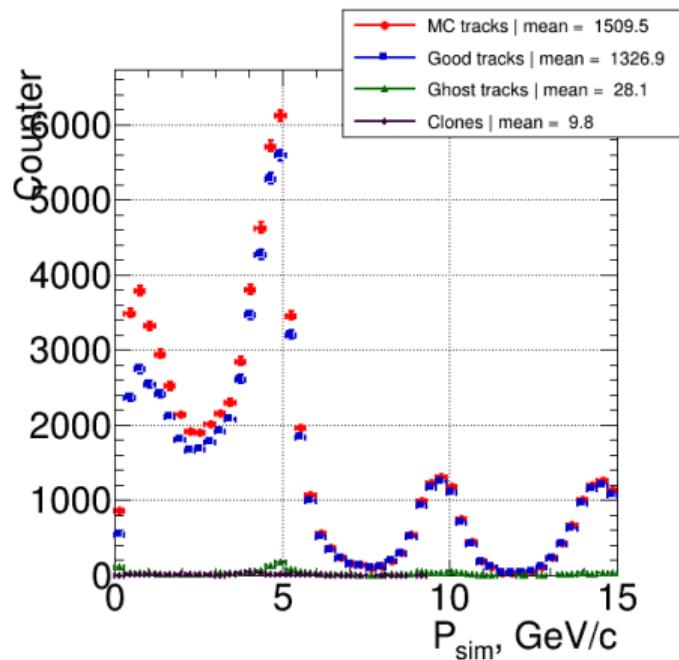
## Hit reconstruction. Fake hits problem

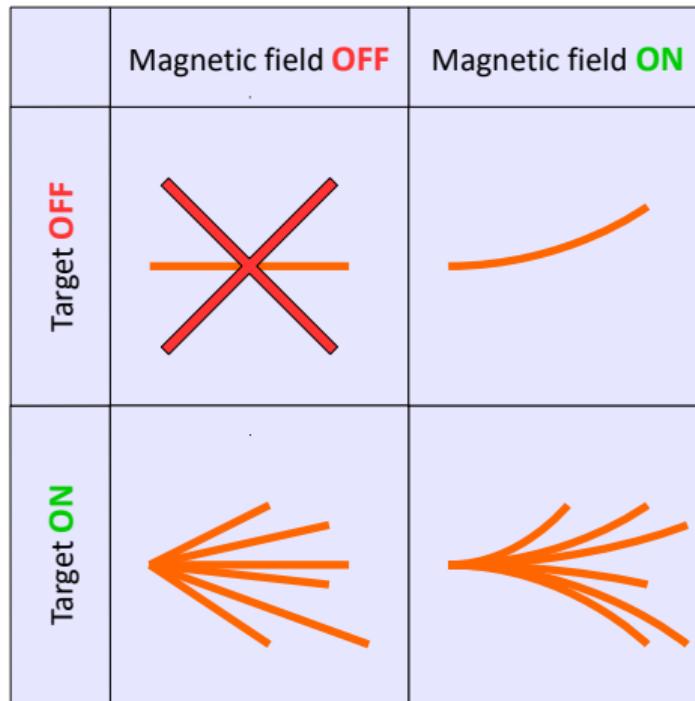






## Tracking quality checking. Monte Carlo

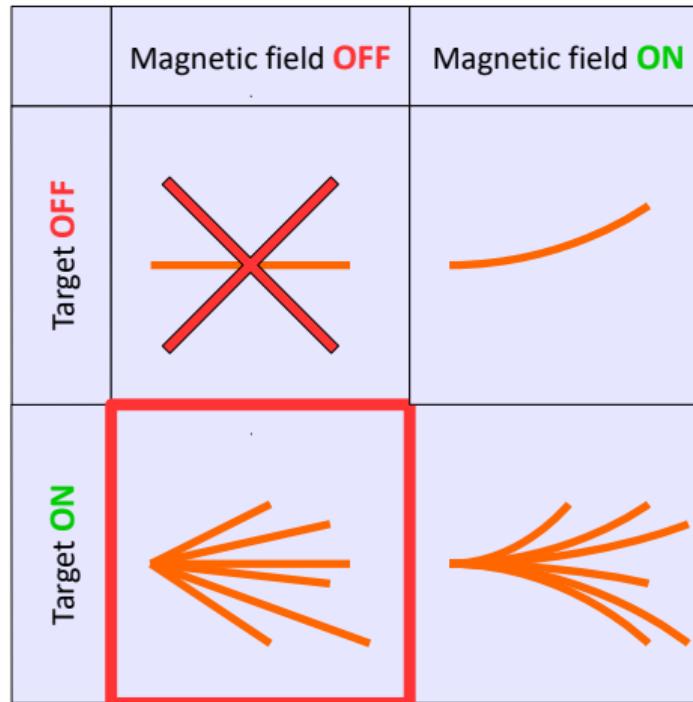




### Possible classification of events

- Field-; Target- - not interested events
- Field-; Target+ - events for alignment
- Field+; Target- - events to estimate momentum resolution and test tracking
- Field+; Target+ - physics events

## Results for experimental data. Alignment



The package based on formalism of **Millepede II** with all its features and allows one to include / exclude different subdetectors from alignment (GEM, SI, MWPC, ...).

**Generalized straight-line model of track:**

$$u_i^j = x_0^j \cos \alpha_i + t_x^j z \cos \alpha_i + y_0^j \sin \alpha_i + t_y^j z \sin \alpha_i + \Delta u_i + (t_x \cos \alpha_i + t_y \sin \alpha_i) \Delta z$$

**Chosen weights:**

$$w_i^1 = \cos \alpha_i - \text{shifts } (x_0)$$

$$w_i^2 = z_i \cos \alpha_i - \text{shearings } (t_x)$$

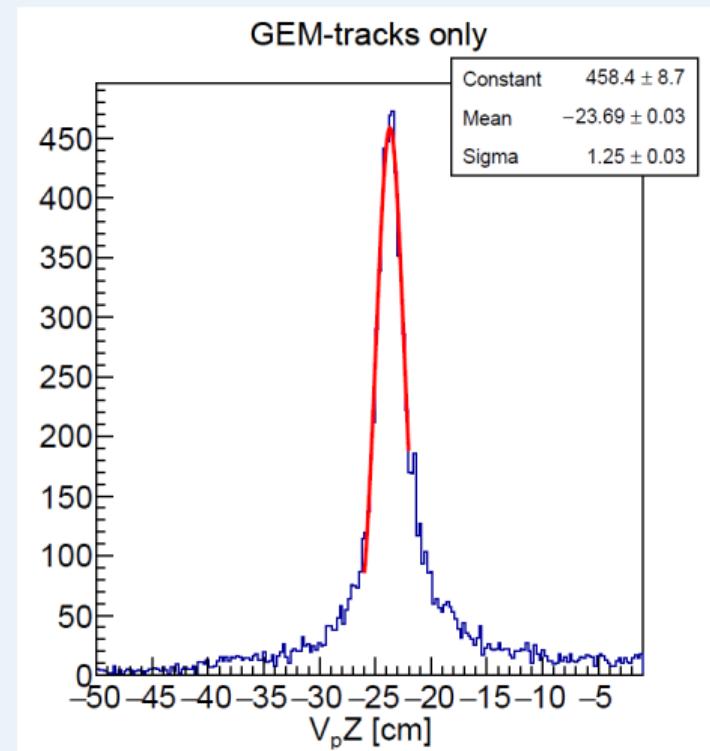
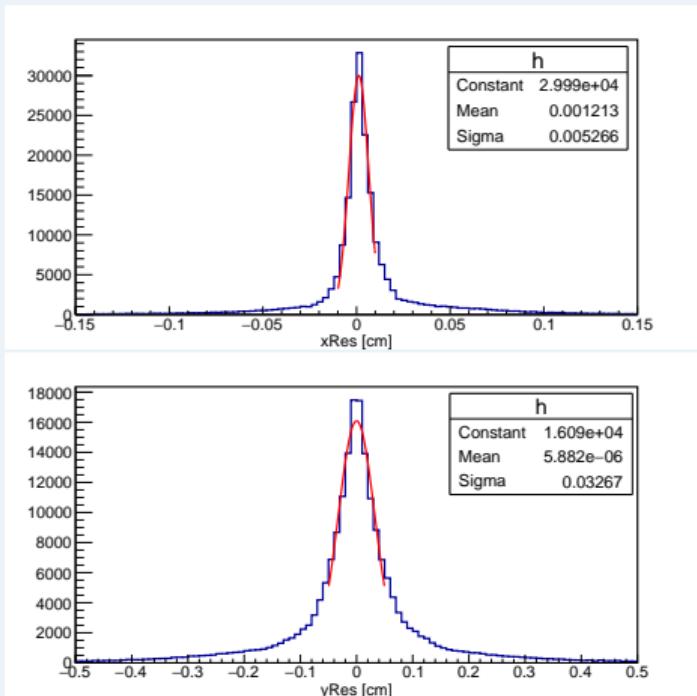
$$w_i^3 = \sin \alpha_i - \text{shifts } (y_0)$$

$$w_i^4 = z_i \sin \alpha_i - \text{shearings } (t_y)$$

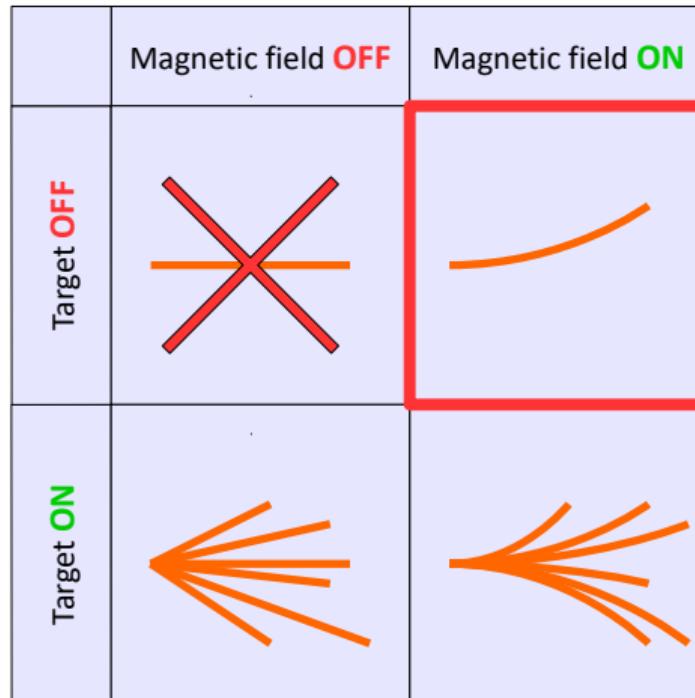
$$w_i^5 = 1 - \text{overall shift in Z}$$

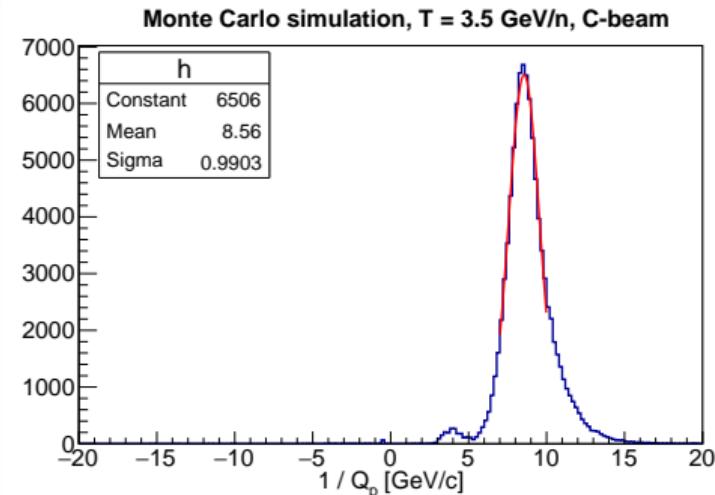
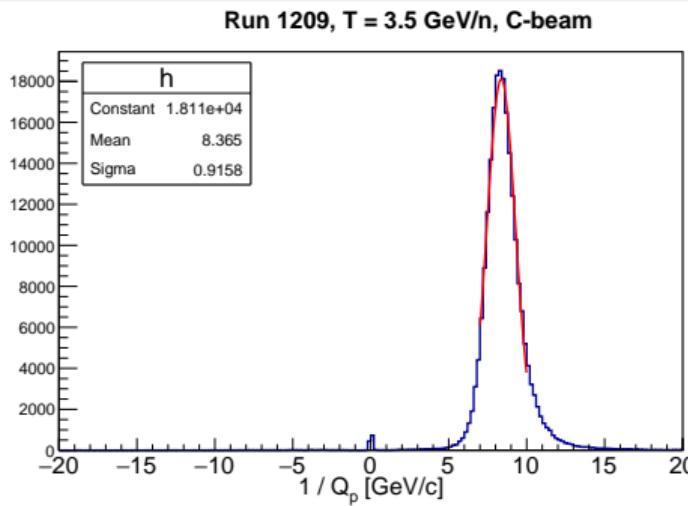
$$w_i^6 = z_i - \text{scaling in Z}$$

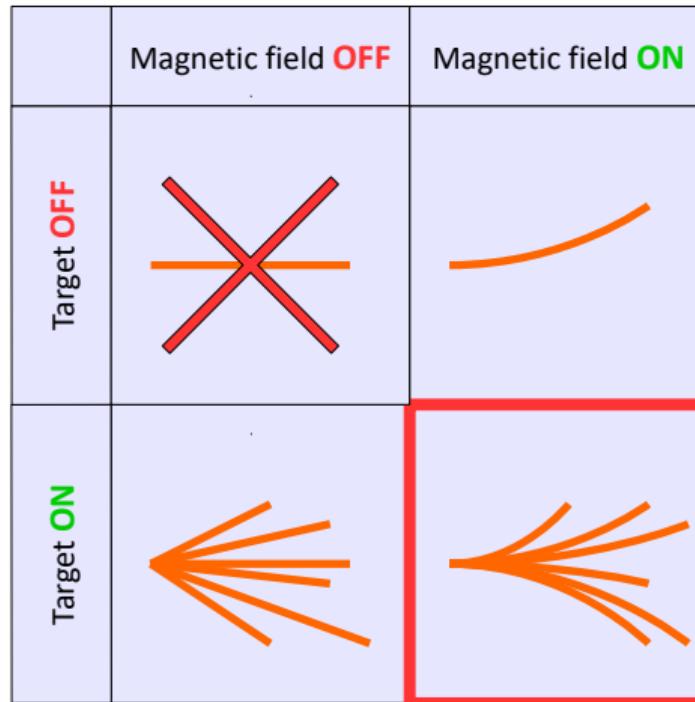
## Quality of alignment

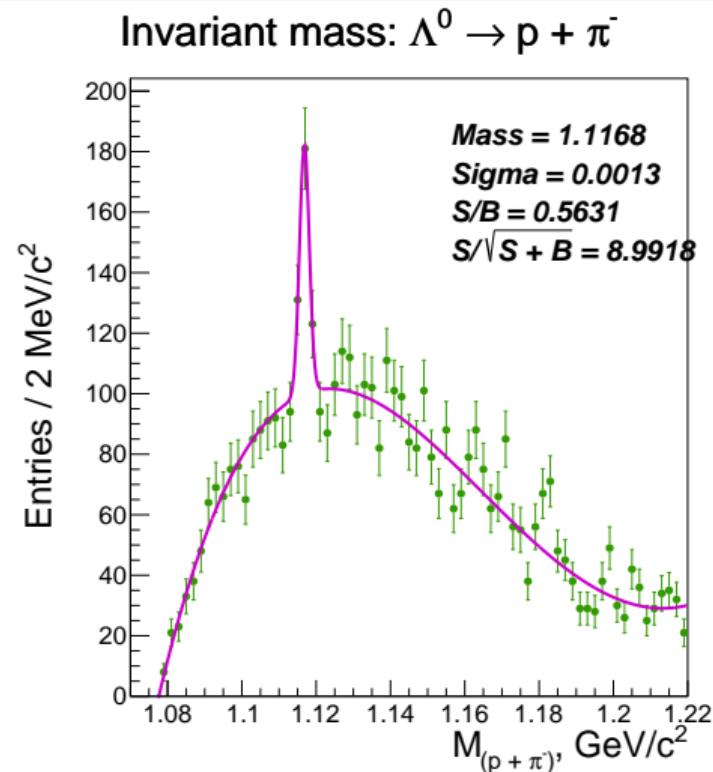
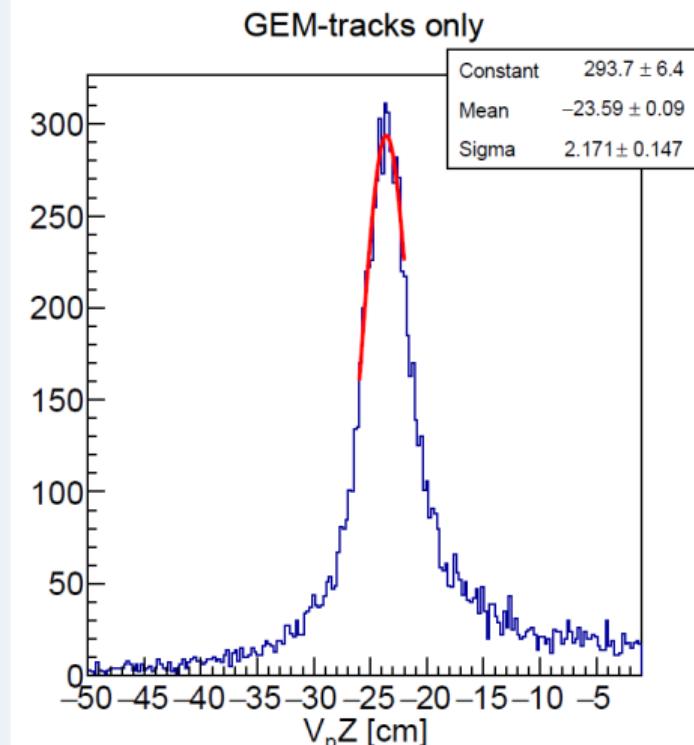


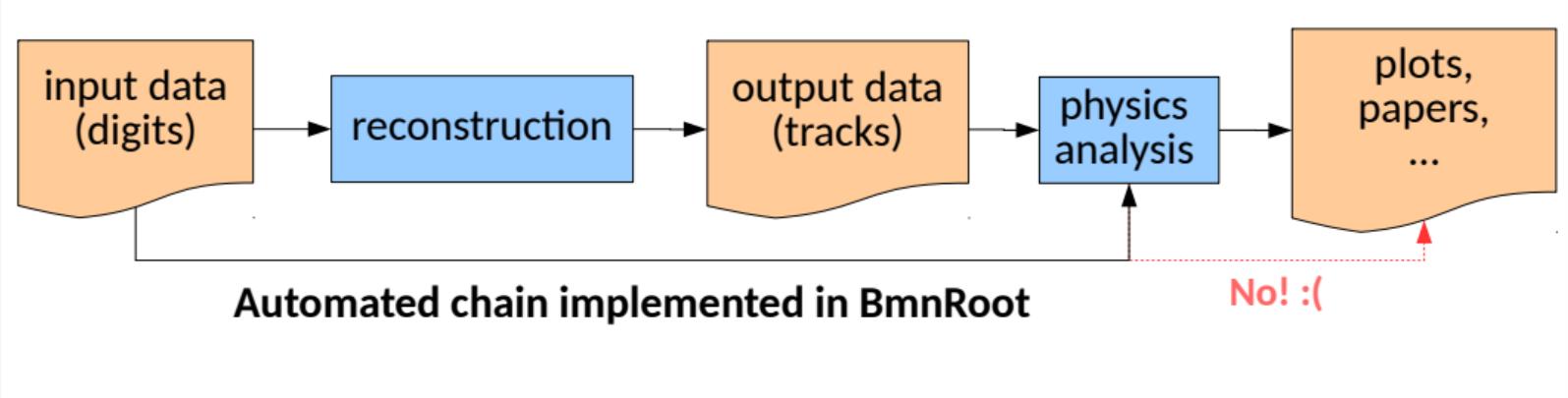
## Results for experimental data











Thank you!